UVScan: Detecting Third-Party Component Usage Violations in IoT Firmware

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• Third-party components are widely used in IoT firmware to shorten the development cycle.



- TPCs usually have strict usage specifications, e.g., checking the return value of the function.
- Violating the upge specifications of TPC Consequences n cause serious ulletconsequences е. Description Apache Accumulo versions 1.5.0 through 1.10.0 and version 2.0.0 do not properly check the return value of some policy enforcement functions before permitting an authenticated user to perform certain administrative operations. Specifically, the return values of the 'canFlush' and BLOG HOME > 'canPerformSystemActions' security functions are not checked in some instances, therefore allowing an authenticated user with insufficient Major Vulnera Qualcomm QCNI permissions to perform the following actions: flushing a table, shutting down Accumulo or an individual tablet server, and setting or removing system-wide Accumulo configuration properties. By Ori Hollander and Asaf Karas October 14, 2020 © 14 min read

- **Deprecated API violation:** A set of APIs will be deprecated or abandoned for various reasons, e.g., security issues.
- **Return value violation:** Return values usually need to be checked after the API call.
- Argument violation: The arguments that are passed into APIs often have strict constraints.
- **Causality violation:** Many APIs may have a strict causal relationship, e.g., lock/unlock, fopen/fclose, and malloc/free.

Building a Practical System from Scratch



Two Challenges:

- 1. How to fill the gap between the <u>high-level</u> <u>specifications</u> from TPC documents, and the <u>low-level implementations</u> in the IoT firmware?
 - Previous works only perform well on <u>well-formatted</u> TPC documents and are hard to handle <u>unusual</u> or <u>ambiguous</u> API specifications.

Building a Practical System from Scratch



Two Challenges:

- 2. How to perform the TPC usage violation analysis on *closed-source* binaries?
 - Previous works only focus on <u>source-level</u> API misuse detection.

UVScan

UVScan: The first automated and practical system to detect TPC usage violations in binary IoT firmware.



Framework of UVScan

Component 1: API Specification Extraction

• **Goal:** Extract the API specifications from corresponding TPC documents.



Step 1-1: Document Distillation

- **Goal:** Filter out irrelevant API descriptions and dig for relevant API descriptions.
- Previous research indicates that relevant API descriptions usually have a strong sentiment^[1].
- This observation does not apply to all scenarios when analyzing the TPC document and will introduce false positives.
- The sentence "<u>additionally it indicates that the session ticket is in a renewal period and</u> <u>should be replaced</u>" has a strong sentiment word "<u>should</u>" but it is not a relevant API description.

^[1]Lv et al., "Automatic Assumption Discovery and Verification Derivation from Library Document for API Misuse Detection", CCS 2021.

Step 1-1: Document Distillation

• Our Approach:

- Leverage WL-Coref, an off-the-shelf coreference resolution model, to resolve the coreferences in the TPC document.
- Adopt BiLSTM model with the multi-head self-attention mechanism to capture the sentiment of a sentence.



Sentiment-based Document Distillation Model

- Goal: Extract precise API specifications from relevant API descriptions.
- **Our Approach:** Adopt the Machine Reading Comprehension (MRC) system with well-designed question sets.

Question Sets

	Category	Question
"SQLITE_OK be returned by sqlite3_snapshot_recover if	Return Value	What are return values supposed to be? In which condition does the function have a return value?
"SQLite error code be returned by sqlite3_snapshot_recover If failed."	Causality	 What operation is required if the return value is <i>ReturnValue_i</i>? What operation is required if <i>Condition_i</i>? Which function should be called before the API? Which function should be called after the API?
	Argument	What is the value of the N-th argument supposed to be before the API? What is the value of the N-th argument supposed to be after the API? How to check the N-th argument before the API? How to check the N-th argument after the API?

Step 1-2: MRC-driven Extraction

- Goal: Extract prec
- Our Approach: Additional (MRC) system with a second s

"SQLITE_OK be returned by sqlite3_ successful, <u>or an SQLite error code c</u>

"SQLite error code be returned by sulf failed."

API: int pcap_activate(pcap_t *p);

Distilled Document: pcap_activate() returns 0 on success without warnings, a non-zero positive value on success with warnings, and a negative value on error. A non-zero return value indicates what warning or error condition occurred. A program should check for positive, negative, and zero return codes, and treat all positive return codes as warnings and all negative return codes as errors. If pcap_activate() fails, the pcap_t * is not closed and freed; the pcap_t * should be closed using pcap_close().

Question 1: What are return values supposed to be? Answer: 0 on success without warnings; a non-zero positive value on success with warnings; a negative value on error

Question 2: In which condition does pcap_activate have a return value? Answer: success without warnings; success with warnings; error

Question 3: What operation is required if the return value is 0? **Answer:** No answer

Question 4: What operation is required if the return value is a non-zero positive value? **Answer:** No answer

Question 5: What operation is required if the return value is a negative value? **Answer: the pcap_t * should be closed using pcap_close()**

Question 6: What operation is required if successful without warnings? Answer: No answer

Question 7: What operation is required if successful with warnings? Answer: No answer

Question 8: What operation is required if there is an error? **Answer:** the pcap_t * should be closed using pcap_close()

Question 9: Which function should be called before pcap_activate? Answer: No answer

Question 10: Which function should be called after pcap_activate? Answer: No answer

Question 11: What is the value of the first argument pcap_t *p supposed to be before pcap_activate? Answer: No answer

Question 12: What is the value of the first argument pcap_t *p supposed to be after pcap_activate? **Answer:** No answer

Question 13: How to check the first argument pcap_t *p before pcap_activate? Answer: No answer

Question 14: How to check the first argument pcap_t *p after pcap_activate? Answer: the pcap_t * should be closed using pcap_close()

relevant API descriptions.

Comprehension ets.

Question Sets

Question

What are return values supposed to be? hich condition does the function have a return value?

peration is required if the return value is *ReturnValue_i*?
What operation is required if *Condition_i*?
Which function should be called before the API?
Which function should be called after the API?

value of the N-th argument supposed to be before the API? e value of the N-th argument supposed to be after the API? How to check the N-th argument before the API? How to check the N-th argument after the API?

Component 2: Programming Expression Generation

- **Goal:** Transfer natural language-based API specifications into machine-readable representations.
- Our Approach:
 - Use POS tagging to annotate each word in an API specification.
 - Create a dependency tree by combining words with a close relationship.
 - Map common phrases into programming expressions, <u>Operation(argument1, argument2, ...)</u>.



An Example of Programming Expression Generation

Component 3: Rule-driven Analysis Engine

- **Goal:** Leverage the generated programming expressions for usage violation detection.
- **Our Approach:** Encode the binary into Datalog facts and perform the usage violation check on the generated facts.



Step 3-1: Binary Encoding

- **Goal:** Encode the binary into Datalog facts.
- **Our Approach:** Leverage *Ddisasm* to encode the binary.

An example of A Rule that Checks the Return Value

Initial Datalog Facts Used by *Ddisasm*

Step 3-2: Checker Implementation

- **Goal:** Perform the usage violation check on the generated facts.
- **Our Approach:** Design four checkers based on the features of different TPC usage violations
 - **Deprecated API violation checker**: Maintain a list of deprecated APIs for each TPC.
 - **Return value violation checker**: Focus on the operation of the registers that hold the return value of the function, e.g., the R0 register in ARM32.
 - Argument violation checker: Focus on the operation of the registers that hold the arguments of the function, e.g., the RO-R3 register in ARM32.
 - **Causality violation checker**: Focus on the functions that are called before or after the API, and the operations under certain return values.



- **Goal:** Evaluate the performance of key components in UVScan and the overall performance of UVScan.
- Evaluate UVScan on four popular TPCs for concept validation.







& LIBPCAP



Evaluation: API Description Extraction Accuracy

- API description dataset (D_{DESC_test}): Train and evaluate our sentiment-based document distillation model.
- Compare UVScan with three off-the-shelf tools: *Advance*, *RCNN*, and *ALICS*.

API Description Extraction Accuracy

Tool	$D_{DESC_{test}}$			
1001	Accuracy	F1		
UVSCAN	92.41%	85.24%		
Advance [30]	85.07%	74.37%		
RCNN [27]	76.25%	61.50%		
ALICS [33]	38.43%	29.02%		

Evaluation: Usage Violation Detection Accuracy

- Real-world usage violation dataset (D_{Real-UV}) includes 77 known usage violations.
- Artificial usage violation dataset (D_{Real-UV}) includes 69 manually created usage violations.
- Compare UVScan with three state-of-the-arts: *Advance*, *APISAN*, and *APEx*.

Performance	x86	UVSCAN ARM	MIPS	Advance	APISAN	APEx
$D_{Real-UV}$						
Precision Recall	72.84% 76.62%	74.70% 80.52%	77.03% 74.03%	80.72% 87.01%	17.31% 11.69%	23.07% 7.79%
$D_{Artif-UV}$						
Precision Recall	68.92% 73.91%	74.32% 79.71%	76.47% 75.36%	77.33% 84.06%	25.49% 18.84%	34.62%

Usage Violation Detection Accuracy

Large-scale Analysis on IoT Firmware

• Conduct a large-scale analysis on 4,545 firmware images.



- **Research Question** ①: Which are the most prevalent TPC usage violations in IoT firmware?
- Detect 27,621 potential usage violations of the four TPCs in the 4,545 firmware images.

ТРС	# Deprecated API Violation	#Causality Violation	# Return Value Violation	# Argument Violation
OpenSSL	4,831	3,679	3,521	1,073
SQLite	2,740	1,996	931	112
libpcap	3,359	2,515	1,364	857
libxml2	418	114	75	36
Overall	11,348	8,304	5,891	2,078

Usage Violation Distribution



Research Question ②: What are the practical impacts of TPC usage violations on IoT firmware?

- Impacts:
 - Security vulnerabilities: Can be exploited to perform attacks, e.g., the Man-In-The-Middle (MITM) attack.
 - **Ordinary bugs**: May result in the malfunctioning of firmware but cannot be leveraged for attacks.
 - **No impact**: Will not affect the operation of the device and cannot be used for attacks.

- Propose UVScan, the first automated and practical system to detect TPC usage violations in binary IoT firmware.
- Conduct the first large-scale analysis on TPC usage violation problem in IoT firmware.

Thanks!