

ICSFuzz: Manipulating I/Os and Repurposing Binary Code to Enable Instrumented Fuzzing in ICS Control Applications

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Introduction

ICS Landscape

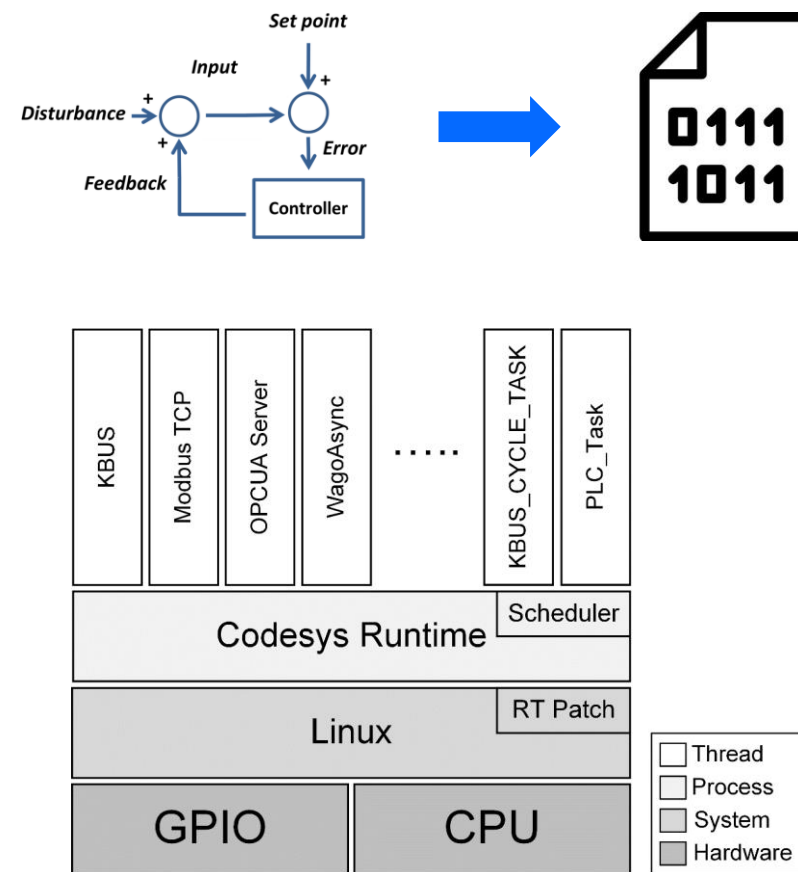
- Industrial Control Systems (ICS) evolving
 - Industry 4.0, IIoT
- IT/OT convergence
- Most research focused on network/system/operational security
 - What about have software bugs?



Introduction

Control Application Intro

- Control logic in PLCs compiled into a software application
 - Assembly instructions
 - Unique format
- Application written in dedicated languages
 - Third-party libraries
- Application hosted in a runtime process
 - Codesys platform a.k.a. a soft PLC
- Runtime is hosted in a Linux-based OS
 - Single binary, multi-threaded



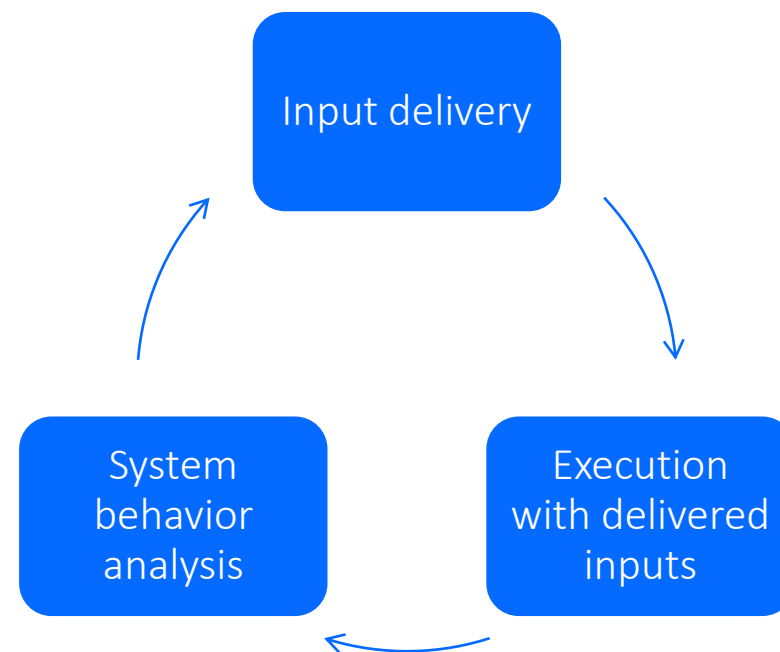
Research Questions/Threat Model

- Can control logic applications have software bugs?
 - Fuzzing!
- Can we fuzz a control applications?
 - Format is not readily accepted by typical fuzzers
- Can fuzzing uncover exploitable bugs?
 - Reverse shell on a PLC sounds exciting!

Fuzzing control applications

Fuzzing basics

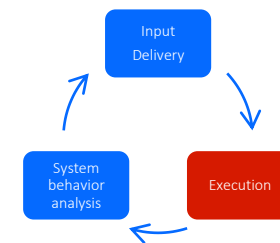
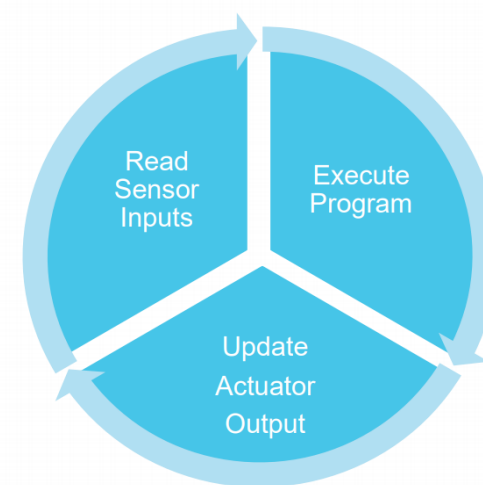
- What is fuzzing?
 - Input control
 - Execution control
 - Execution feedback



Fuzzing control applications

Execution control

- Execution control
 - Scan cycle task
 - Automated cyclic execution!



Fuzzing control applications

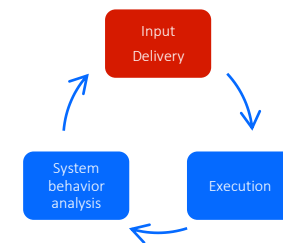
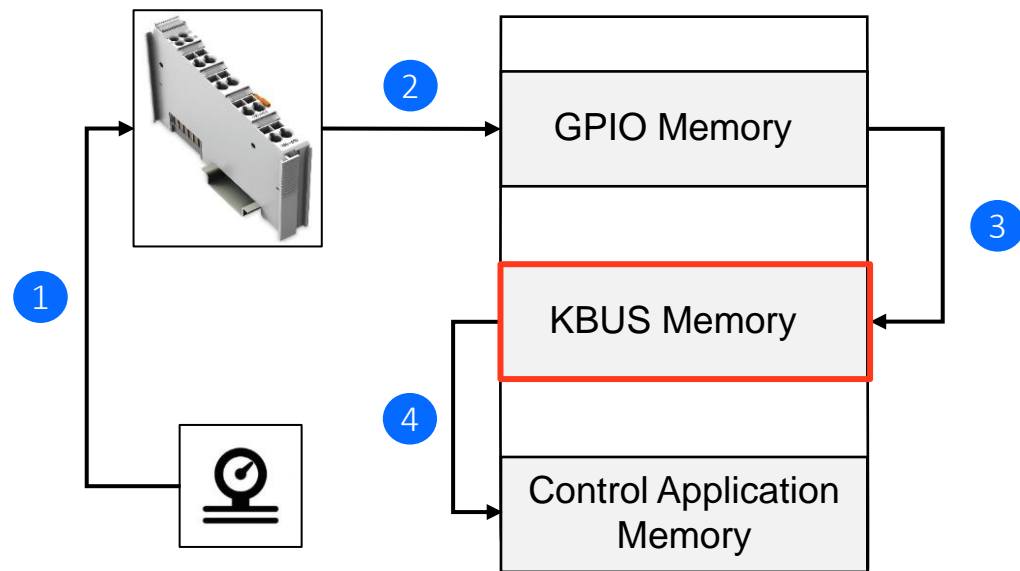
Input Control

● How to control input?

- Trace input delivery throughout the stack
- Sensor -> PLC I/O -> GPIO -> KBUS -> PLC binary
- Isolate most controllable input delivery stage
- Force new values through system structures

● How to synchronize input delivery?

- `KBUS_CYCLE_TASK`
- Custom system calls (ioctl's)



Fuzzing control applications

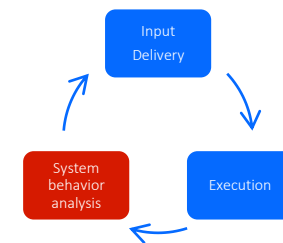
Execution feedback

- Execution feedback
 - Trace the PID family
 - Find a malleable predecessor
 - Trace control application exit through predecessor

Runtime init script

Codesys runtime

PLC_Task



Fuzzing control applications

Instrumentation

● Can we get feedback on the execution of the control application?

● Instrumentation!

● What to do?

● No source code

● Proprietary compiler

● Look for opportunities!

● NOPs

● Replace NOPs with controllable code

● i.e. store the current program counter (PC)

● Approximate coverage with the PC information

```
STR r5 ,[sp ,#0x0]
STR r4 ,[sp ,#0x8]
STR r6 ,[sp ,#0xc]
LDR r11 ,=0xB4F22A8Ch
LDR r6 ,[r11 ,#0x0 ]
CPY r0 ,sp
STR r10 ,[sp ,#0x38 ]!
LDR r10 ,=0xCDE1F2CDh
STR r10 ,[sp ,#0x24 ]!
MOV r10 ,#0x0
MOV r0 ,r0
MOV lr ,pc
```



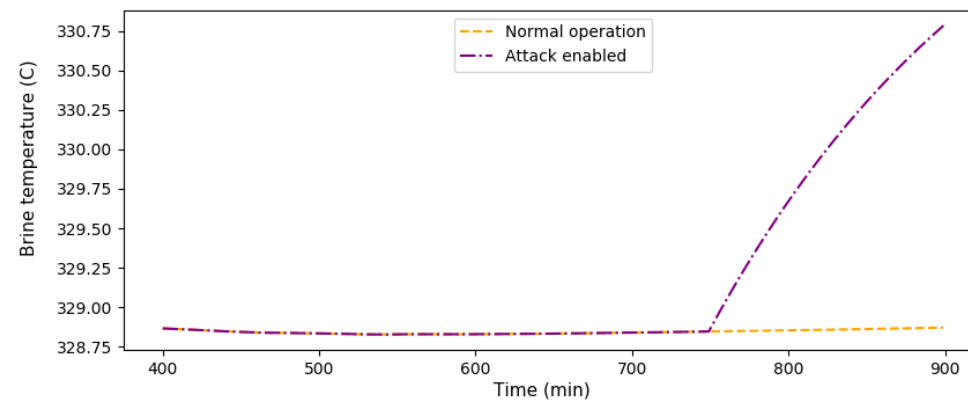
```
STR r5 ,[sp ,#0x0]
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LDR r6 ,[r11 ,#0x0 ]
CPY r0 ,sp
STR r10 ,[sp ,#0x38 ]!
LDR r10 ,=0xCDE1F2CDh
STR r10 ,[sp ,#0x24 ]!
MOV r10 ,#0x0
STR pc ,[r0 ,#0xDEADBEEF]
MOV lr ,pc
```

Fuzzing control applications

Experiments

- Fuzz binaries found in the wild
 - Problem: PLC binaries available online are too simple
 - Try something beefier

- Fuzzing an open-source desalination process
 - Bingo!
 - Binary crashed
 - DoS possible



Fuzzing control applications

Experiments (contd.)

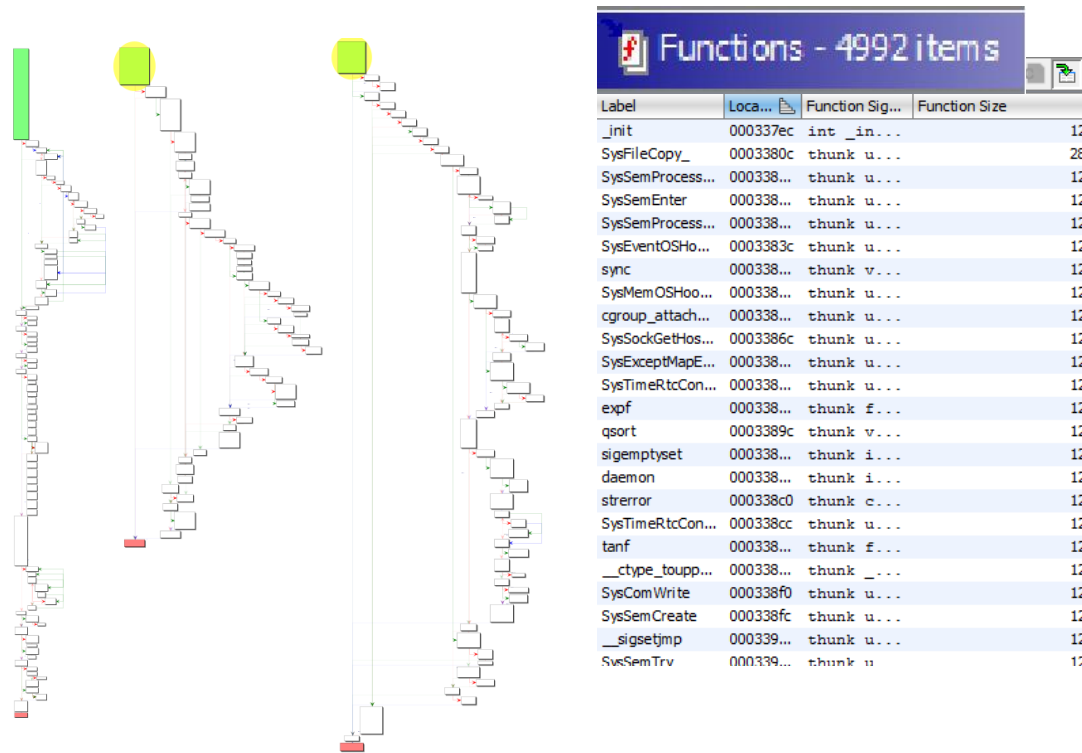
- Dig a little bit deeper
 - Can we make more complex PLC binaries
 - (yes we can!)
- Introduce interesting stuff
 - Complex structures (arrays, strings, etc.)
 - Notorious functions (`memcpy`, `memmove` etc.)
 - Fuzz away
- Crashes, lots of crashes
 - Buffer overflows
 - (Way) Out of bounds read/writes
- Possibility for complex exploits
 - Reverse shell through TCP
 - Rootkit insertion

Control Application	Execution Speed (inputs/sec)	First Crash (time mm:ss)	First crash (inputs)	Crashes (1hr)
bf_mcpy_1	70.88	3:54	15270	32
bf_mcpy_6	64.2	3:08	12172	21
bf_mcpy_8	66.06	4:39	18216	17
bf_mcpy_12	62.11	7:06	26645	9
bf_mset_1	64.56	3:28	13441	21
bf_mset_3	62.68	2:54	10906	24
bf_mset_5	68.8	4:14	17554	16
bf_mset_9	69.76	10:23	43530	7
bf_mmove_1	64.63	2:56	11245	28
bf_mmove_4	63.1	2:39	10070	24
bf_mmove_7	66.31	3:49	15317	15
bf_mmove_12	64.53	13:03	50643	6
oob_1_arr_1	71.86	0:55	3880	39
oob_1_arr_6	77.03	1:43	8085	28
oob_1_arr_9	69.78	1:45	7326	27
oob_1_arr_13	75.2	3:27	27241	19
oob_2_arr_1	73.53	1:57	8558	35
oob_2_arr_5	71.1	2:45	22759	27
oob_2_arr_8	69.8	3:08	13366	22
oob_2_arr_13	70.95	3:12	13401	19
divby0_1	73.68	N/A	N/A	0

Fuzzing the runtime

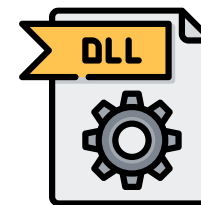
- What about the runtime itself?
 - Control applications can write way outside its memory space
 - Fuzzing crashed the whole runtime

- Must assess the runtime itself
 - Complex
 - Super large
 - Built-in anti-debugging



Fuzzing the runtime

- Divide and conquer
 - Target dynamically loaded libraries
 - Reverse-engineer context
 - Instantiate in C harness
 - Fuzz the produced ELF!
 - Fuzzers galore



```
kbus_ksock_write_data(socket, data, length);
```

```
kbus_ksock_t ksock = fopen("/dev/kbus0", "r");
```

```
#include LIBDBUSCOMMON_H
int main(int argc, char **argv){
    kbus_ksock_t ksock = fopen("/dev/kbus0", "r");
    kbus_ksock_write_data(ksock, &argv, 32);
}
```

Fuzzing the runtime

Experiments

- Limited function eligibility
 - ~250 out of more than 5000
- Focus on “external facing” functions
 - Network protocols
 - Parsers
- Found crashes
 - Recognized a couple of known CVEs

Function	Description	Crashes (1hr)
KbusRegisterRequestWrite	Kbus write function	2
KbusRegisterRequestRead	Kbus read function	1
kbus_ksock_write_data	Kbus write function	4
kbus_ksock_read_data	read function	7
XMLParse	XML Parsing Function	8
SysSockRecv ⁵	TCP receive data	6
CMAddComponentKbus	Kbus instantiation	4
pthread_create	Creates runtime thread	8
pthread_rwlock_unlock	Updates thread privileges	2
pthread_join	Joins PLC task threads	1
pthread_setschedparam	Sets scheduler thread policy	1
GetLoginName	Receives input login name	7
SysLibStrcpy	String copy custom function	2
SysLibStrcmp	String compare custom function	5
SysComWrite	System communication output	7
SysComRead	System communication input	2
GetHookName	Get name of hooked function	6
CopyRtsMetrics	Copies PLC data	8
getspnam	Returns info from shadow file	5

Conclusion

- PLC binaries are inherently robust
 - High-level nature of the PLC programming languages
 - Very well-defined problems they are addressing
- However, the control binaries get more complex
 - Mimicking typical software evolution
 - Exploitable vulnerabilities can be introduced
- PLC runtimes suffer like high-level software
 - E.g. typical C/C++ developed software
 - This can compromise the whole industrial control system computation stack
- Fuzzing is great!
 - Even for Industrial Control Systems
 - Despite the presence of heavy I/O and scan cycles



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Thank you

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