Swing: Short-cutting Rings for Higher Bandwidth Allreduce

<u>Daniele De Sensi</u>¹, Tommaso Bonato², David Saam³, Torsten Hoefler²

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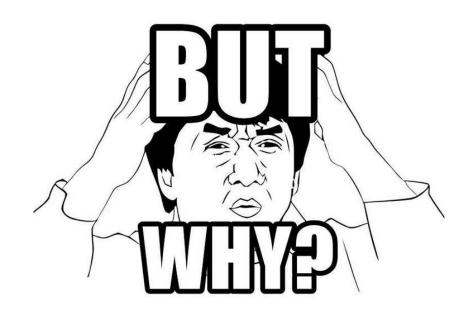
NSDI Santa Clara – April 16-18, 2024



Swing

A novel allreduce/allgather/reduce-scatter algorithm

optimized for multi-dimensional torus networks



(expected advantages on any blocking network)



Why torus and why allreduce?

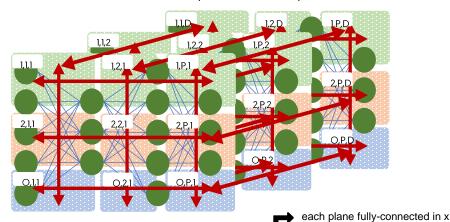
1,x

2,x

3,x

y,x

3D - Data, Pipeline, and Operator Parallelism



1,1

3,1

y,1

Enabling next-generation AI workloads: Announcing TPU v5p and AI Hypercomputer

December 7, 2023

Google's TPU v5p Pod (> 9,000 chips on a 3D torus)

Amazon EC2 Trn1 Instances

High-performance, cost-effective training of generative AI models

Get started with Trn1 instances using AWS Neuron

AWS Trainium Instances (16 chips on a 2D torus)

GRAPHCORE





Graphcore IPU-POD (64 chips on a 2D torus)

HammingMesh: A Network Topology for Large-Scale Deep Learning (2022)

1,2

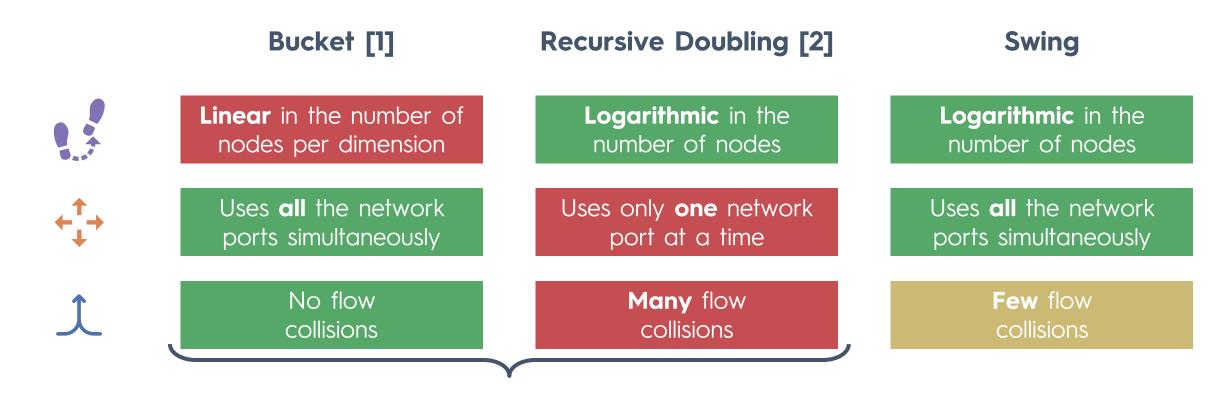
3,2

2,1 2,2 2,3

3,3

Torsten Hoefler, Tommaso Bonato, Daniele De Sensi, Salvatore Di Girolamo, Shigang Li, Marco Heddes, Jon Belk, Deepak Goel, Miguel Castro, Steve Scott



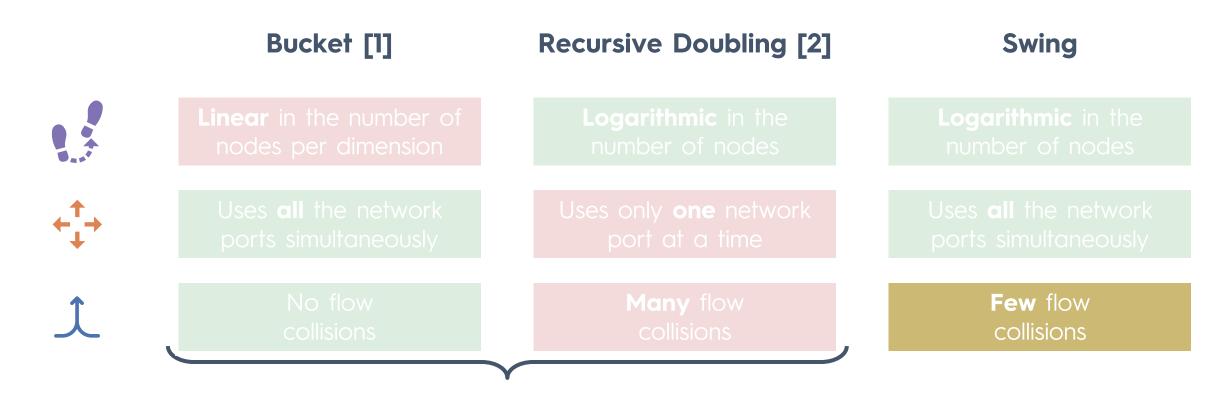


State-of-the-art

[1] N. Jain and Y. Sabharwal. Optimal bucket algorithms for large MPI collectives on torus interconnects (2010)

[2] P. Sack and W. Gropp. Collective algorithms for multiported torus networks (2015)



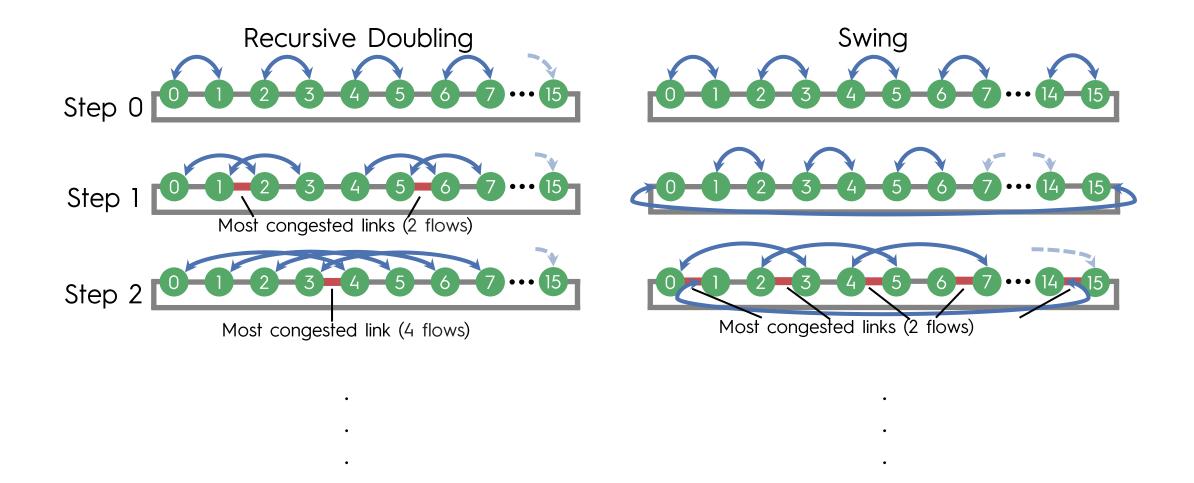


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Swing Allreduce



Swing Allreduce

Recursive Doubling

Details, generalization to D dimensions, and correctness proof in the paper

Most congested link (4 flows)

 $-1 \mod p = p - 1$, whereas node 1 communicates with node 2. Thus, we can say that at step 1 the data sent from 0 reached nodes $\{1, 2, p - 1\}$ (2 has been reached *indirectly* through node 1).

Because the number of reached nodes doubles at each step, and because we perform $\log_2 p$ steps, the data sent from any given node would eventually reach p-1 nodes. We need, however, to prove that those p-1 nodes are distinct (i.e., that the data sent by each node reach every other node exactly once and is thus never aggregated twice). To do so, we need first to prove a few lemmas.

Lemma A.1. $\rho(s)$ and $\delta(s)$ are odd $\forall s \in \mathbb{N}$.

Proof. $(-2)^i$ is odd for i = 0, and even for i > 0. The sum of even numbers with an odd number is odd.

Lemma A.2. If r is even, $\pi(r,s)$ is odd, and vice versa.

Proof. An even node r communicates at step s with node $\pi(r,s) = r + \rho(s) \mod p$. Because p is a power of two (thus even), and $\rho(s)$ is odd (Lemma A.1), $\pi(r,s)$ is odd. Vice versa, odd nodes communicate with even nodes.

If a node r communicates at step s with a node $q = \pi(r, s)$, and q communicates with a node $z = \pi(q, h)$ at step h > s, we say that s indirectly reached node z. Because even nodes only communicate with odd nodes (and vice versa), if r is even, we can rewrite:

$$z = \underbrace{\frac{q = \pi(r,s)}{(r + \rho(s) \bmod p) - \rho(h) \bmod p}}_{\pi(q,h)} = r + \rho(s) - \rho(h) \bmod p$$

I.e., the sign behind $\rho(s)$ alternates between positive and negative, starting from positive. In general, an even node r can reach through a sequence of k steps $\{s_0 < s_1 < s_2 < \ldots < s_{k-1}\}$ a node q, with:

$$q = r + \rho(s_0) - \rho(s_1) + \rho(s_2) - \dots \mod p =$$

= $(r + \sum_{i=1}^{k-1} -1^i \rho(s_i)) \mod p$

The same applies if r is odd, by replacing -1^i with -1^{i+1} .

Lemma A.3. Even nodes reach (directly or indirectly) odd nodes through an odd number of steps k. Odd nodes reach (directly or indirectly) even nodes through an odd number of steps k.

Proof. This stems from Lemma A.2. If r is even and k is odd, then $q = (r + \sum_{i=0}^{k-1} -1^i p(s_i)) \mod p$ is odd because p(s) is always odd. Similarly, if r is odd and k is odd, q is even. \square

Lemma A.4. Given k integers $\{e_0 < e_1 < \ldots < e_{k-1}\}$, with $e_{k-1} \le \log_2(p) - 1$, then $-p < \sum_{i=0}^{k-1} (-2)^{e_i} < p$.

Proof. We have
$$\sum_{i=0}^{k-1} (-2)^{e_i} \le \sum_{i=0}^{k-1} 2^{e_i} < 2^{e_{k-1}+1} \le p$$
. Similarly, $\sum_{i=0}^{k-1} (-2)^{e_i} \ge -\sum_{i=0}^{k-1} 2^{e_i} > -(2^{e_{k-1}+1}) \ge -p$.

Theorem A.5. On a 1D torus, if a node r at step s communicates with node $\pi(r,s)$ (defined in Eq. 2), it will reach (directly or indirectly) all the other p-1 nodes in $\log_2(p)$ steps (with p power of two).

Proof. We need to prove that, a unique sequence of k steps $\{s_0 < s_1 < \dots s_{k-1}\}$ exists by which a given node r reaches a node q. We prove this by contradiction, and we will prove it by assuming that r is even and q is odd (the proof for the other cases is analogous and only requires changing the signs before the p terms). Assume that there are two different sequences of steps $\{s_0 < s_1 < \dots s_{k-1} \le \log_2(p) - 1\}$ and $\{t_0 < t_1 < \dots t_{h-1} \le \log_2(p) - 1\}$ of k and k steps respectively (both k and k are odd from Lemma A.3), so that:

$$q = r + \rho(s_0) - \rho(s_1) + \rho(s_2) - \dots + \rho(s_{k-1}) \mod p =$$

$$= r + \rho(t_0) - \rho(t_1) + \rho(t_2) - \dots + \rho(t_{h-1}) \mod p$$
(4)

By expanding the first of the two sequences we have:

$$q = r + \sum_{i=0}^{s_0} (-2)^i - \sum_{i=0}^{s_1} (-2)^i + \dots + \sum_{i=0}^{s_{k-1}} (-2)^i \mod p$$

= $r + \sum_{i=0}^{s_0} (-2)^i + \sum_{i=s_1+1}^{s_2} (-2)^i + \dots + \sum_{i=s_{k-2}+1}^{s_{k-1}} (-2)^i \mod p$

By expanding similarly the second assignment in Eq. 4, we have that the two sequences exist if:

$$\sum_{i=0}^{s_0} (-2)^i + \dots + \sum_{i=s_{k-1}+1}^{s_{k-1}} (-2)^i \equiv$$

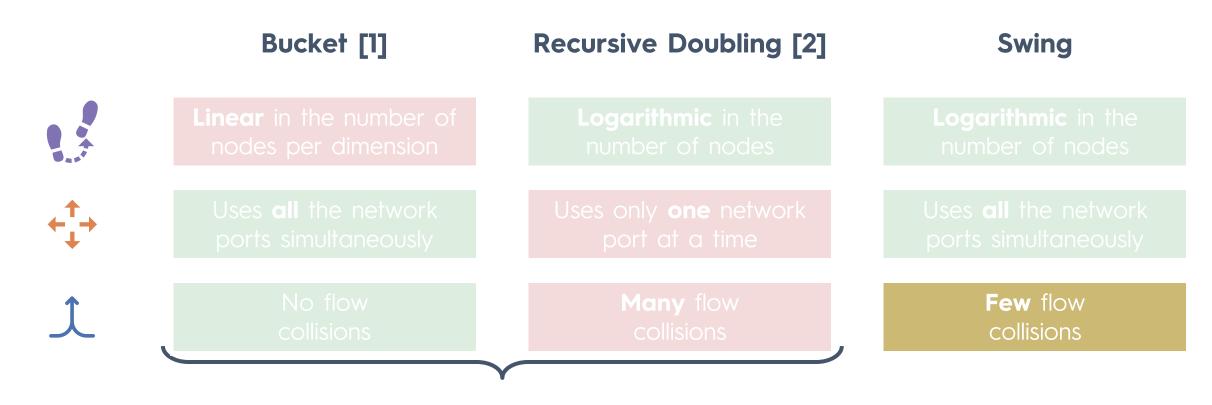
$$\equiv \sum_{i=0}^{t_0} (-2)^i + \dots + \sum_{i=t_{k-2}+1}^{t_{k-1}} (-2)^i \pmod{p}$$
(5)

From Lemma A.4, we know that both sides are in the range (-p,p). Thus, the two sides are congruent only if: i) they have the same sign and are equal, or; ii) they have different signs, and by summing p on the negative side, we get the positive side. Since each side is the sum of distinct powers of -2, case i) is only possible if the two sequences of steps are equal. To prove that case ii) is impossible, let us consider the case where the left side is negative (the other case is analogous). Because $p = 2^a$ for some $a \in \mathbb{N}$, and because $2^a = (-2)^a$ (if a is even⁷), Eq. 5 becomes:

$$\begin{split} &\sum_{i=0}^{s_0} (-2)^i + \ldots + \sum_{i=s_{k-2}+1}^{s_{k-1}} (-2)^i + (-2)^a = \\ &= \sum_{i=0}^{t_0} (-2)^i + \ldots + \sum_{i=t_{k-2}+1}^{t_{k-1}} (-2)^i \end{split}$$

²If a is odd, $p = 2^a = (-2)^{a+1} + (-2)^a$, and the same considerations still old.

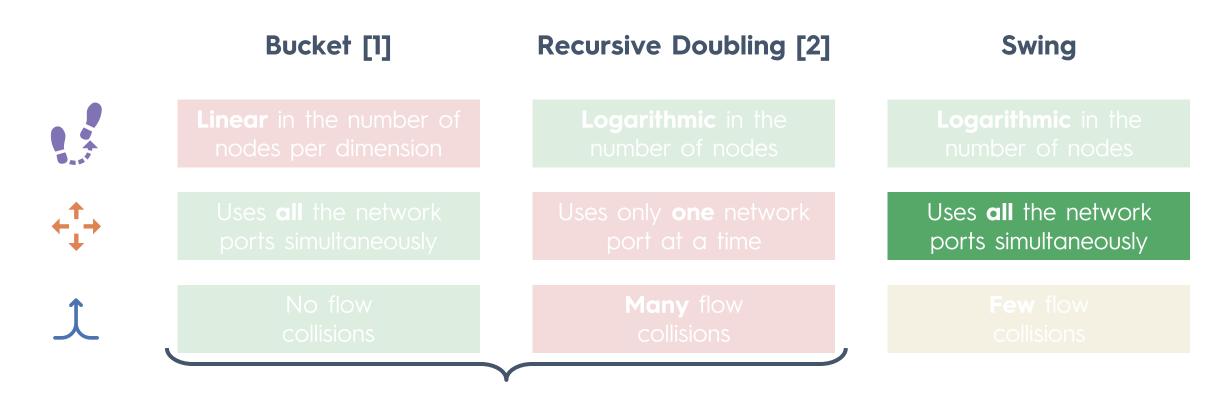




State-of-the-art

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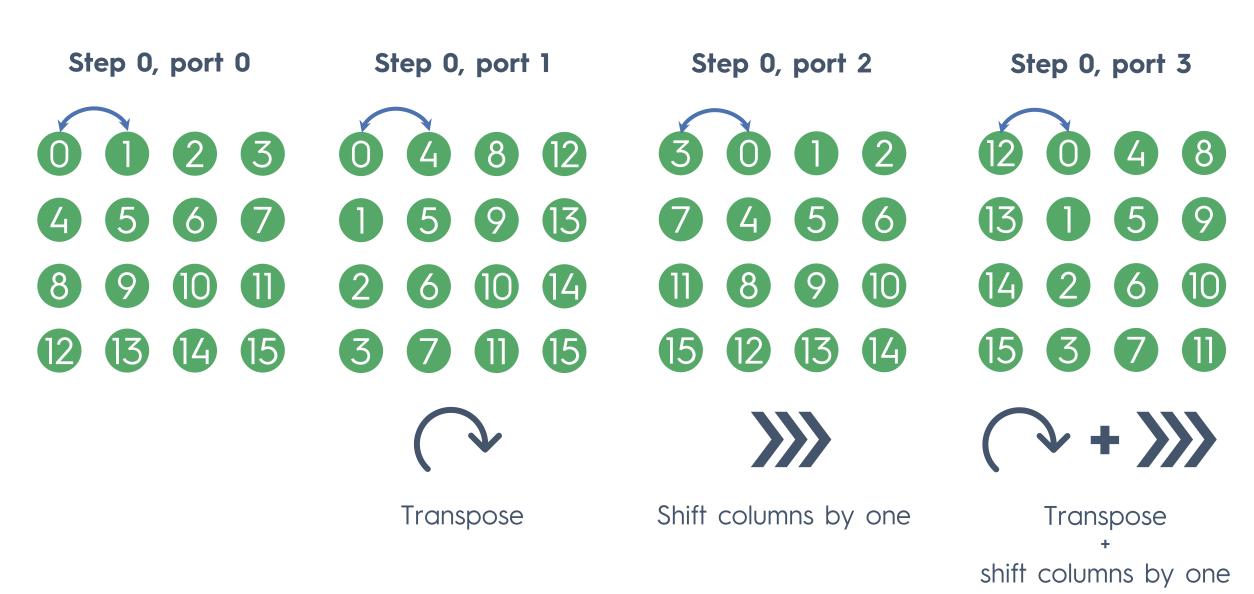


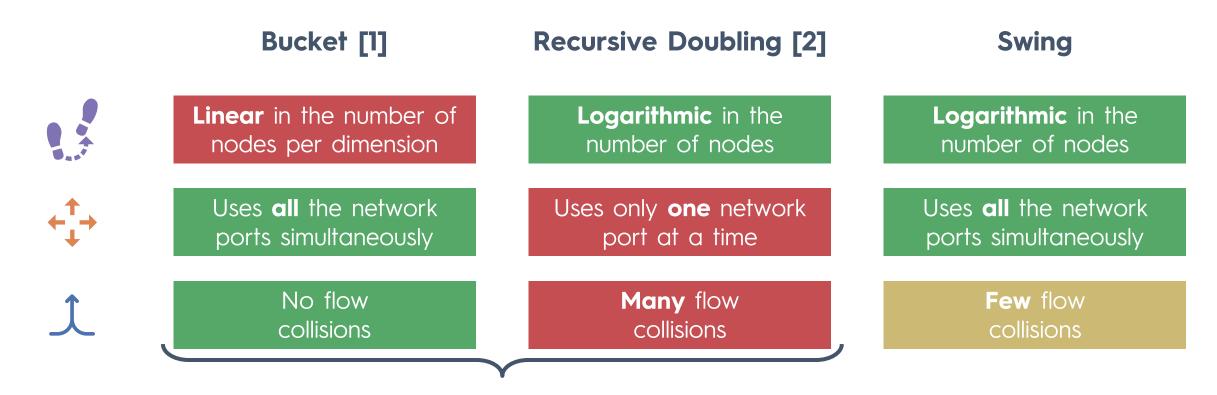
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Multiport Swing

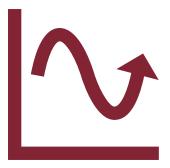




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Evaluation



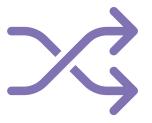
Setup



SST packet-level network simulator

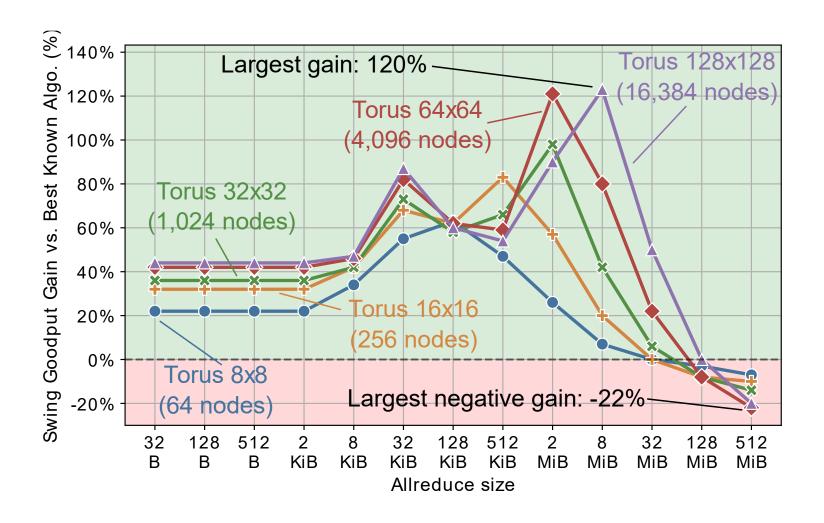


400 Gb/s links 100 ns latency



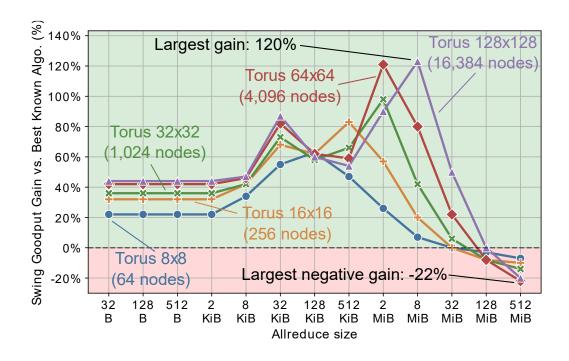
300 ns per-hop latency

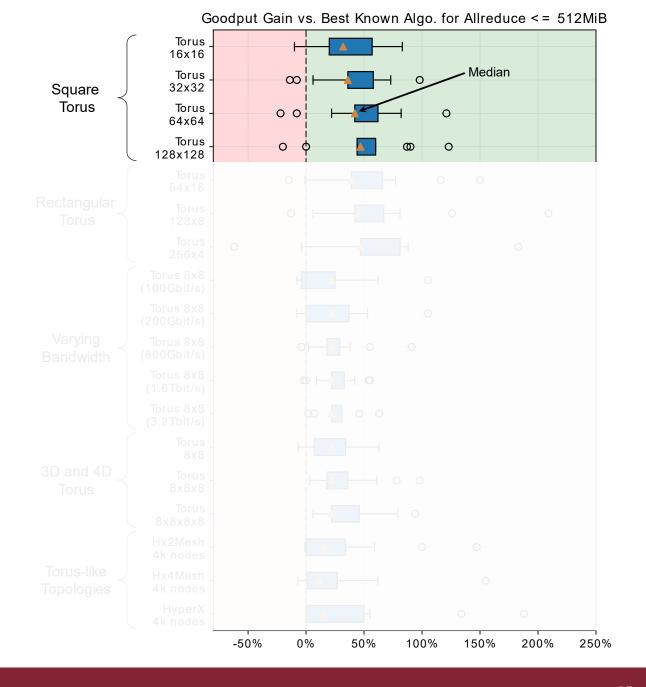
Results - Performance Gain





Results Summary





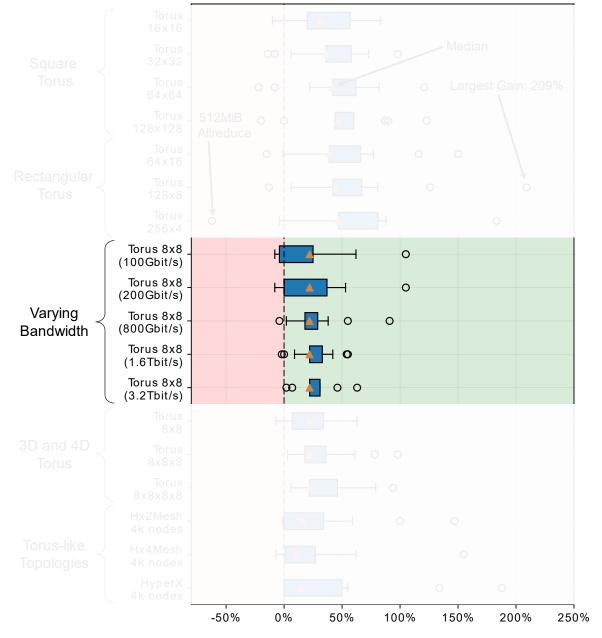


Goodput Gain vs. Best Known Algo. for Allreduce <= 512MiB

Results Summary



At higher bandwidth, the number of steps has a higher relative impact on performance



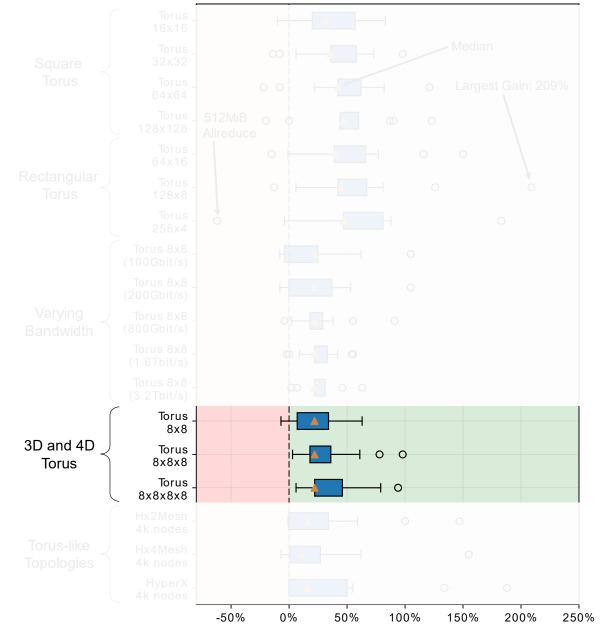


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Results Summary



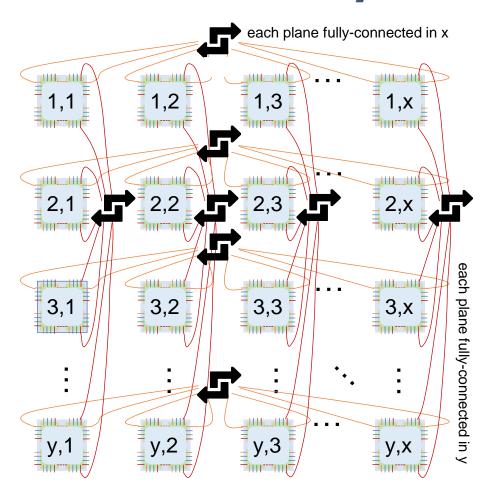
More dimensions imply more communications with close nodes



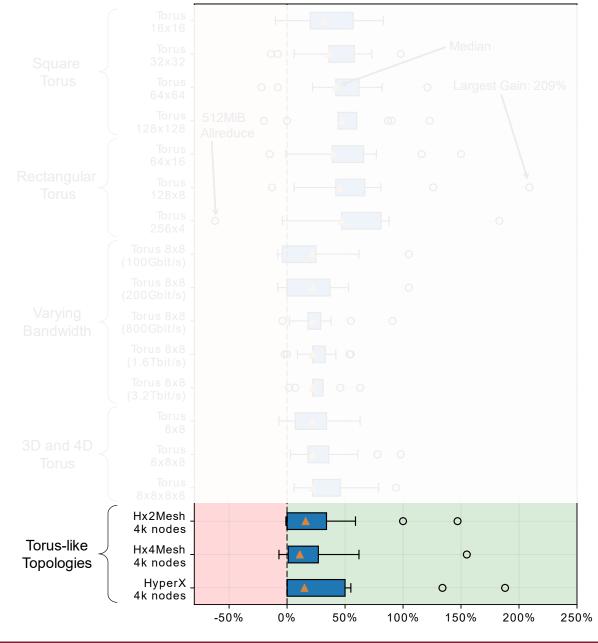


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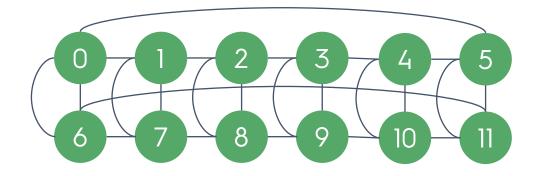


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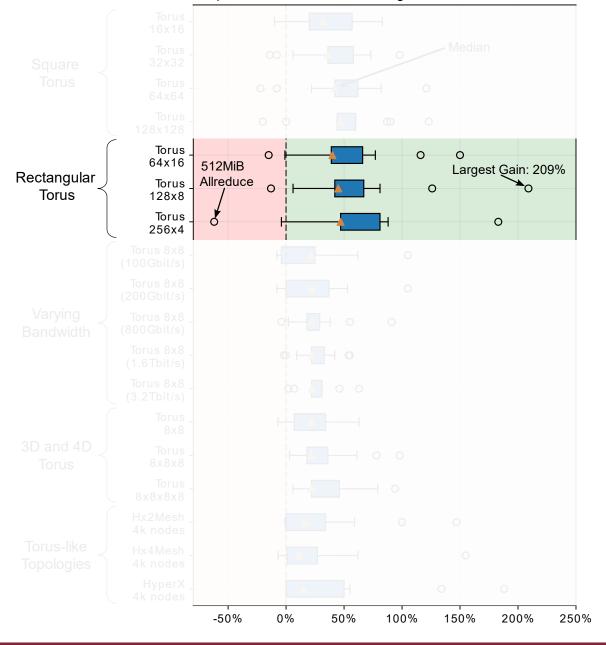




Results Summary



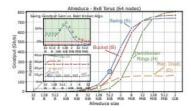
Goodput Gain vs. Best Known Algo. for Allreduce <= 512MiB

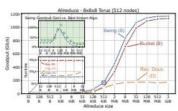




5.3 Performance for 3D and 4D Torus

As discussed in Sec. 4 and summarized in Table 2, the performance of the allreduce algorithm for multidimensional torus also depends on the number of dimensions. Thus, we evaluate the performance of the different allreduce algorithms on 8², 8³ and 8⁴ torus networks.





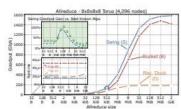


Figure 11: Goodput on higher-dimensional torus networks: 2D 8x8, 3D (8x8x8), and 4D (8x8x8x8).

We report the evaluation result in Fig. 11. We do not include the Hamiltonian ring algorithm in the 3D and 4D torus results since it only works for 2D torus networks. When increasing the number of dimensions, the goodput gain of Swing increases because, as shown in Table 2 and discussed in Sec. 4, the congestion deficiency drops to 3% on 3D torus and to 0.8% on 4D torus. Consequently, for 3D and 4D torus networks, Swing outperforms by up to 2x all existing algorithms on allreduce ranging from 32B to 2GB.

5.4 Performance on Torus-Like Topologies

Some topologies like HammingMesh [26] and HyperX [3,20] extend torus by adding additional links, thus increasing the network bisection bandwidth. Seen from a different perspective, those extra links allow distant nodes to communicate crossing fewer hops, decreasing Swing congestion deficiency.

5.4.1 Performance on HammingMesh

HammingMesh [26] groups nodes into square boards. Each board is a 2D mesh, and nodes on the same column (or row) located at the edge of the boards are connected together using fat trees. Due to its higher performance and flexibility compared to a torus a similar topology is used, for example, to interconnect TPUv4 devices [31]. Because of the extra links, the congestion deficiency of Swing on a HammingMesh is lower than that on a 2D torus. Moreover, for a fixed number of nodes, having smaller boards increases the number of extra (fat tree) links and, thus, decreases the congestion deficiency.

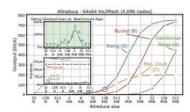
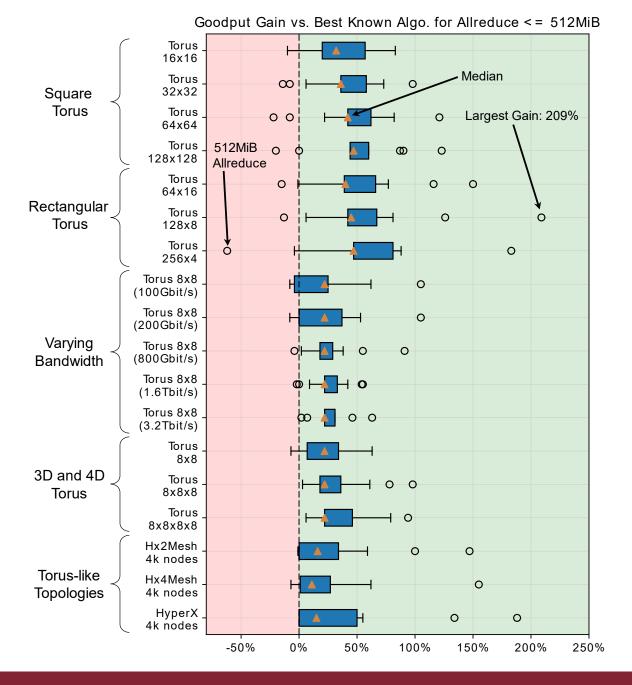


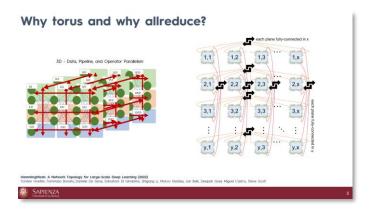
Figure 12: Goodput on a 4,096 nodes Hx2Mesh.

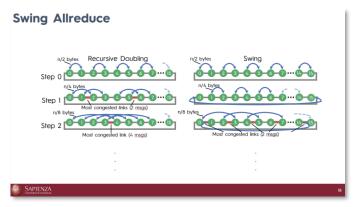
We show in Fig. 12 the performance of the different algorithms for a Hx2Mesh network with 4,096 nodes (2x2 boards arranged in a 32x32 configuration). For such configuration, Swing outperforms the state-of-the-art algorithms at any size, up to 2.5x for 2MiB allreduce. Moreover, because of the lower congestion deficiency, we observe how the peak Swing performance is higher compared to a 2D torus with the same number of nodes (Fig. 6). Last, we also observe a runtime reduction for all the algorithms for small vectors, since nodes on the same board on HammingMesh are connected through PCB traces, with lower latency than optical network cables.

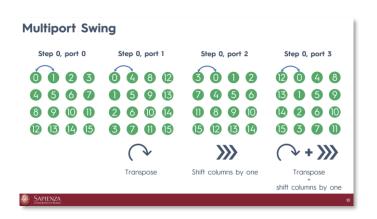


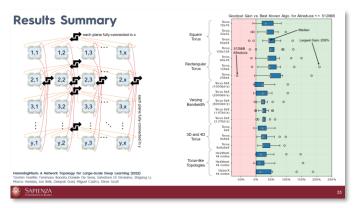


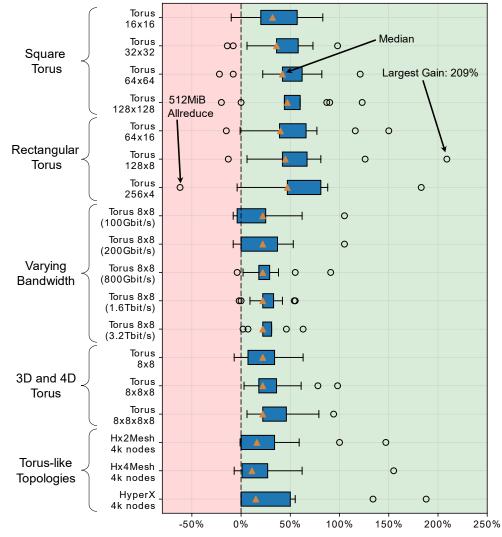
Conclusions











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