



X-AR: Augmented Reality with X-Ray Vision

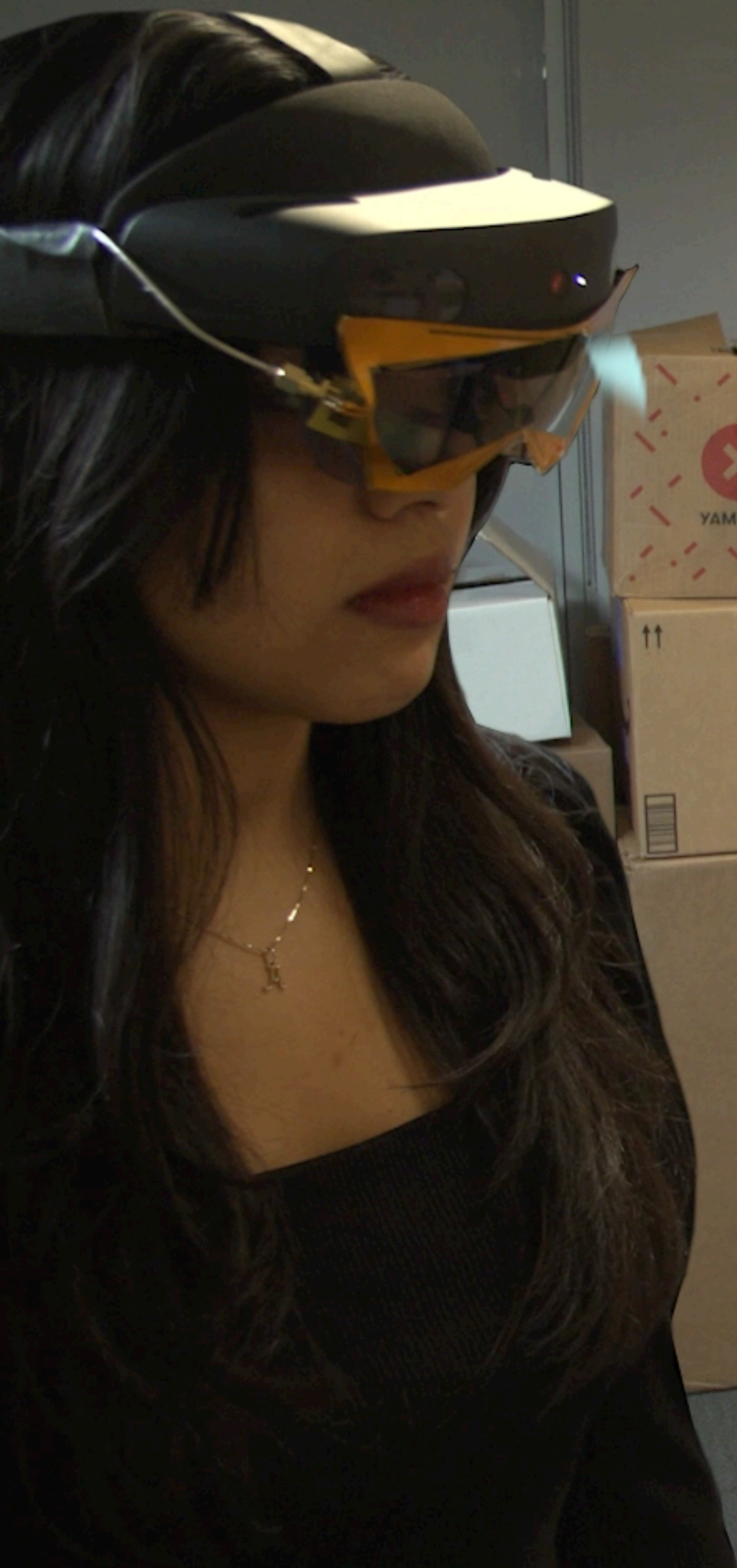
Tara Boroushaki

Maisy Lam, Laura Dodds, Aline Eid, Fadel Adib



Battery-less 3 cent Radio Frequency IDentification (RFID) Tags

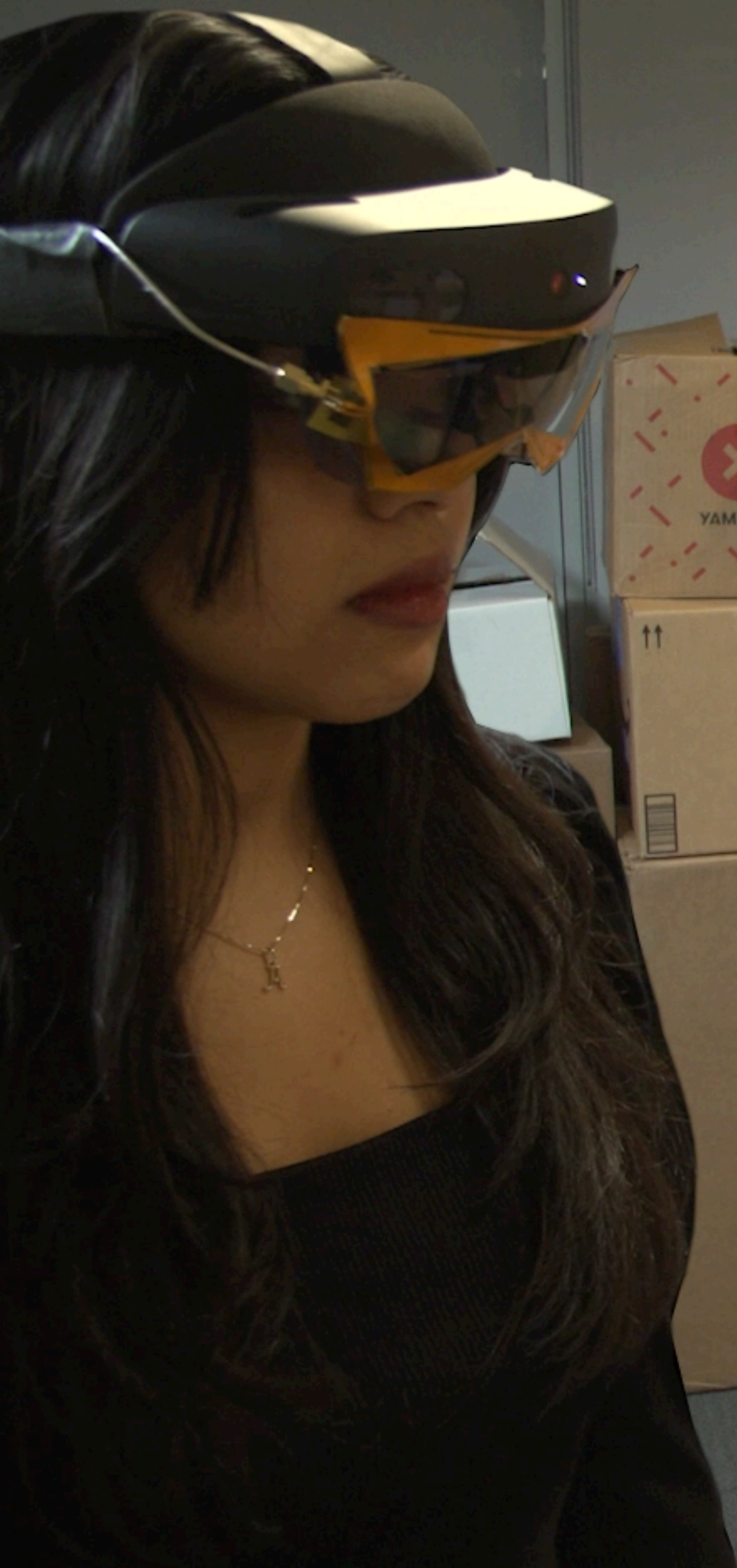




**RFID tagged items
inside boxes**



**RFID tagged items
inside boxes**



Applications



Applications



Applications



X-AR

- First augmented reality headset that enables **non line of sight perception**
- It introduces novel techniques that **bridges network wireless sensing with augmented reality** for sensing and localization
- It can **locate items with 9.8 cm accuracy** in line-of-sight, non-line-of-sight, or fully occluded settings.

How does X-AR work?

We need an **Antenna** for RF sensing

**Typical
RFID Reader**



AR headset



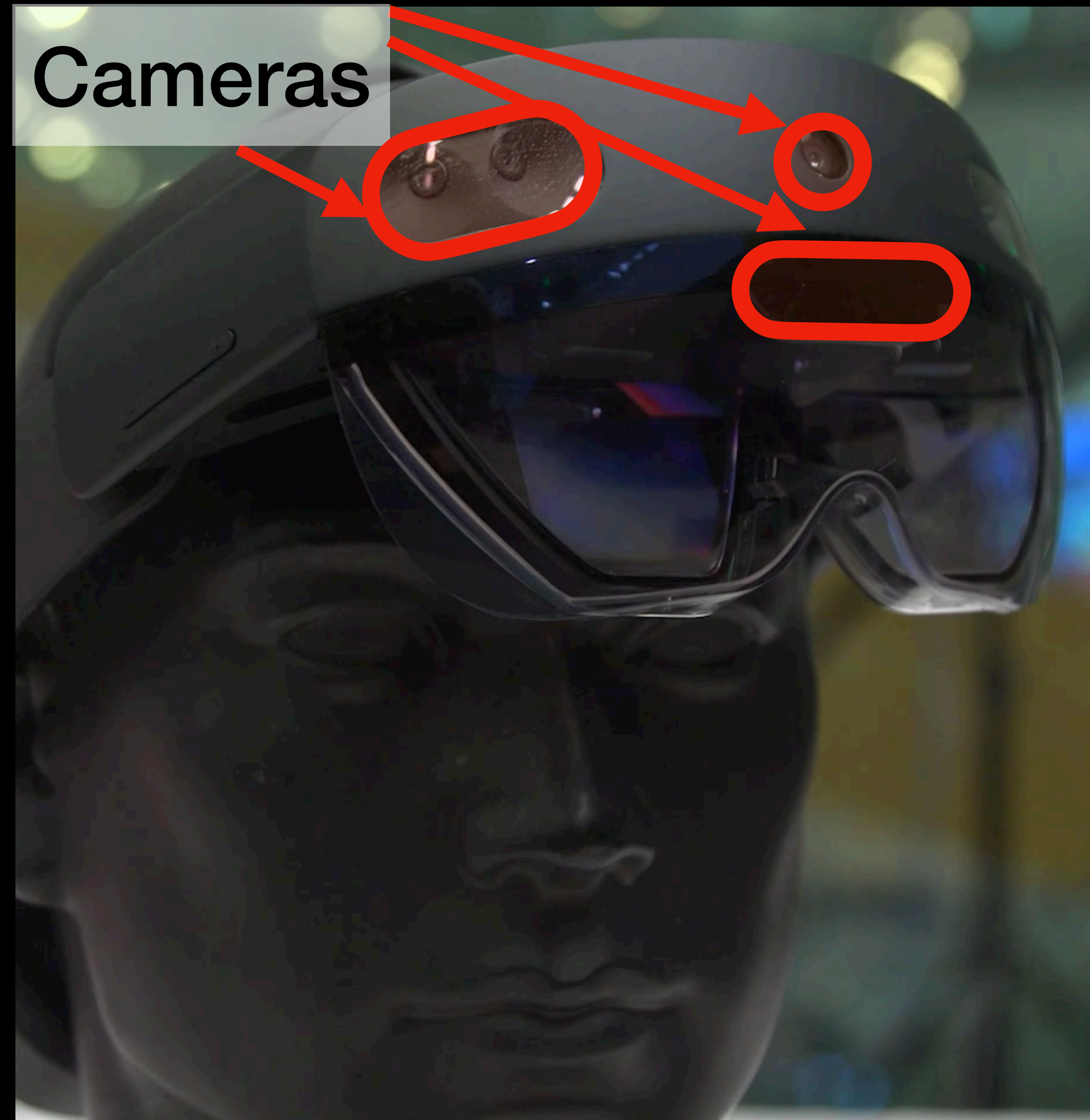
Heavy and bulky

Difficult to move



We need an **Antenna** for RF sensing

- **Wide Bandwidth**
 - for accurate localization
- **Light Weight and Flexible**
 - for easy mounting
- **Matches Visor's Shape**
 - for not blocking cameras

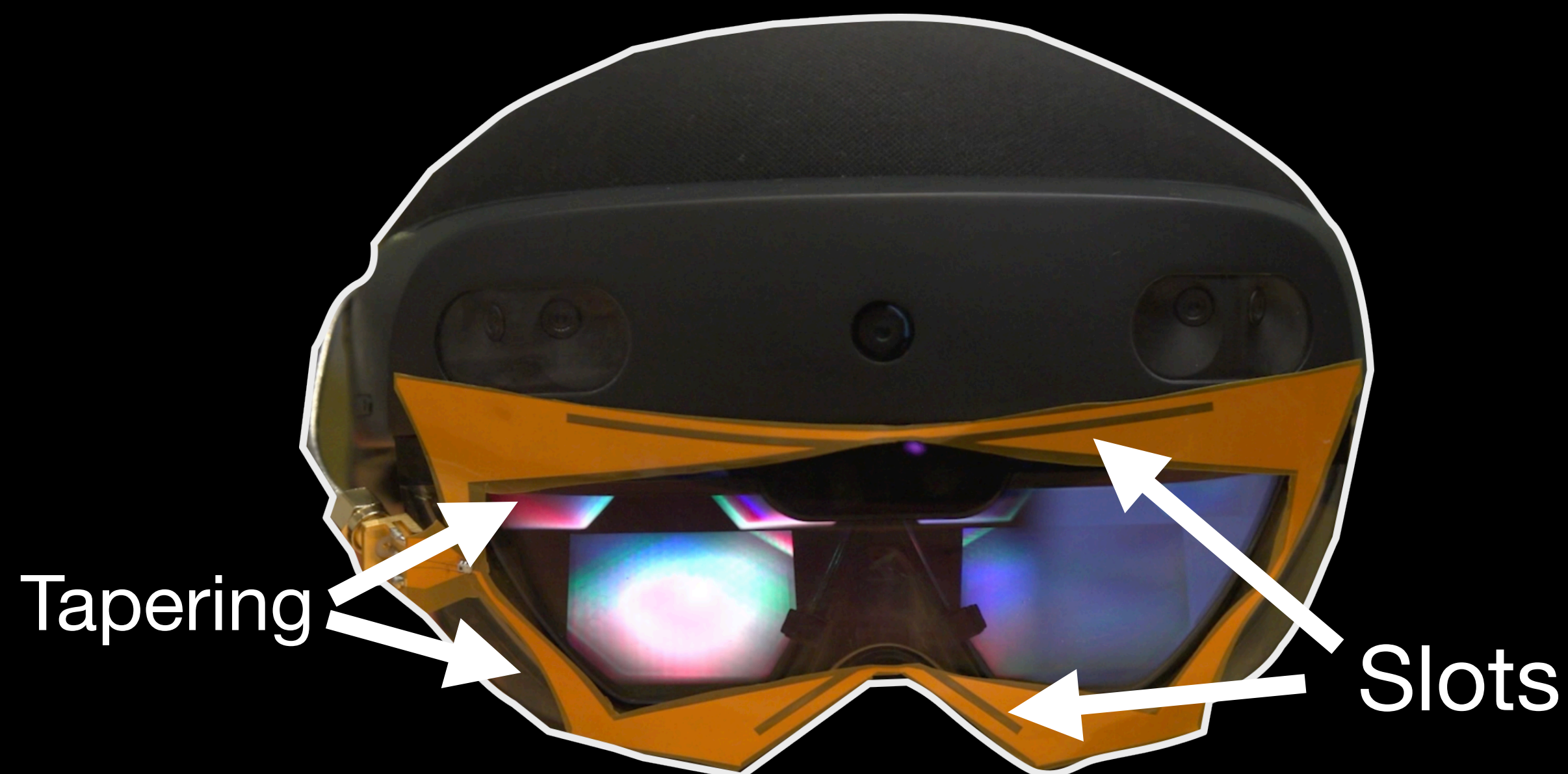


We need an **Antenna** for RF sensing

Single Loop Antenna



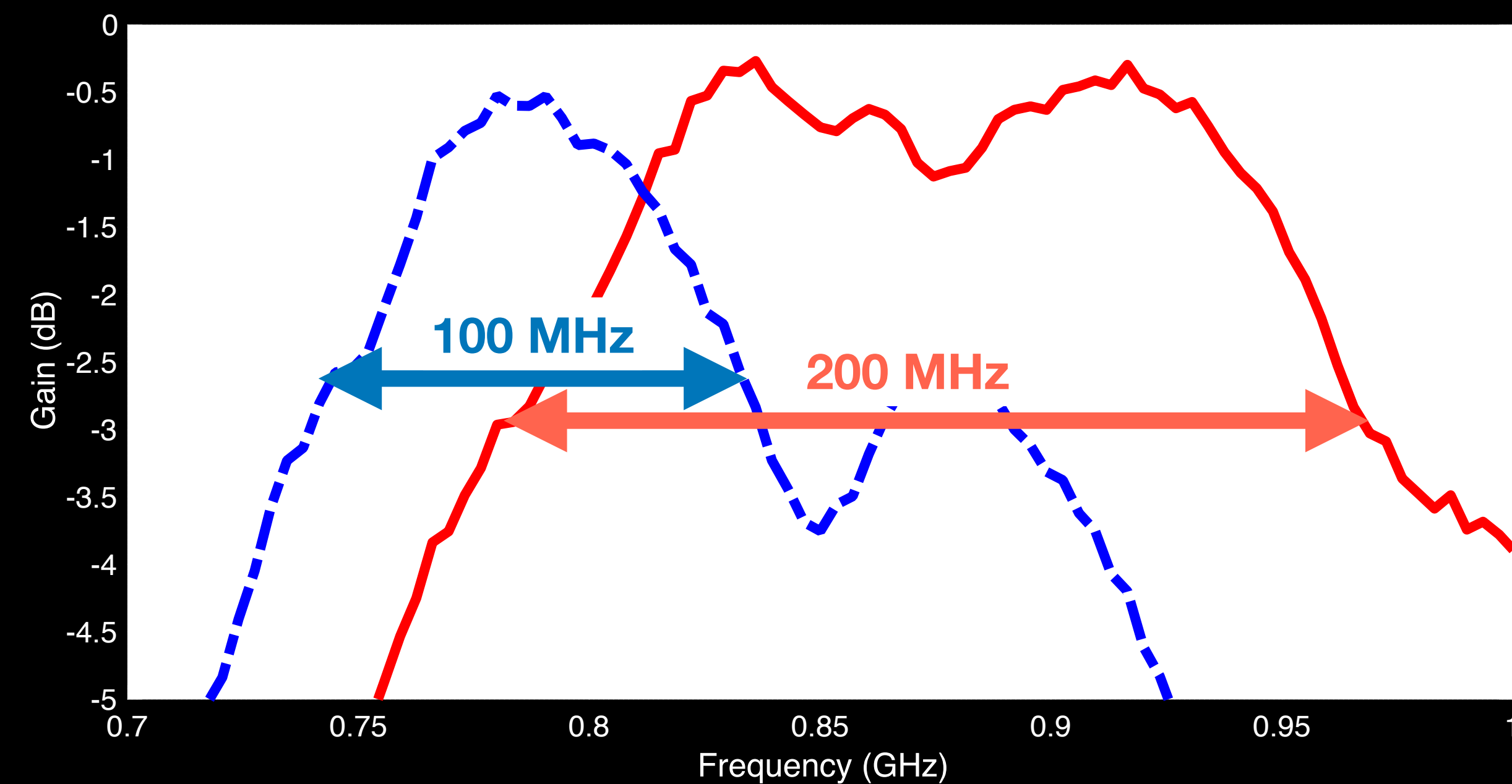
- ✓ Light Weight and Conformal
- ✓ Does not block Sensors
- ✗ Wide Bandwidth



Tapering

Slots

Wideband custom-designed Antenna



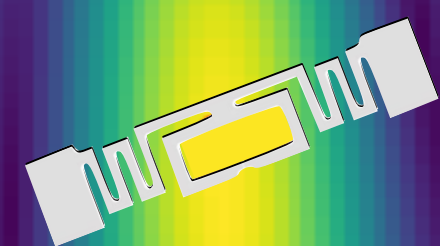
- ✓ Wide Bandwidth (200 MHz)

Synthetic Aperture Radar (SAR)

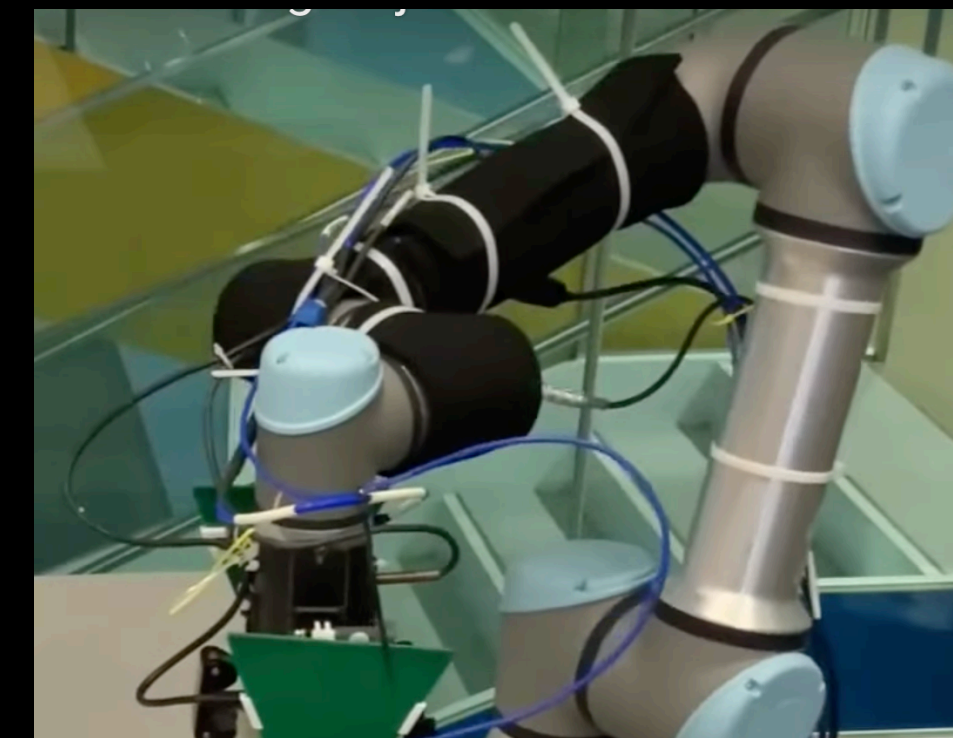
$$P(x, y, z) = \left| \left| \frac{1}{M} \frac{1}{N} \sum_{j=1}^M \sum_{i=1}^N h_{i,j} e^{\frac{4\pi d_i(x, y, z)}{\lambda_j}} \right| \right|$$

Robot and antenna movements are:

- on **specific directions**
- with **constant speed**

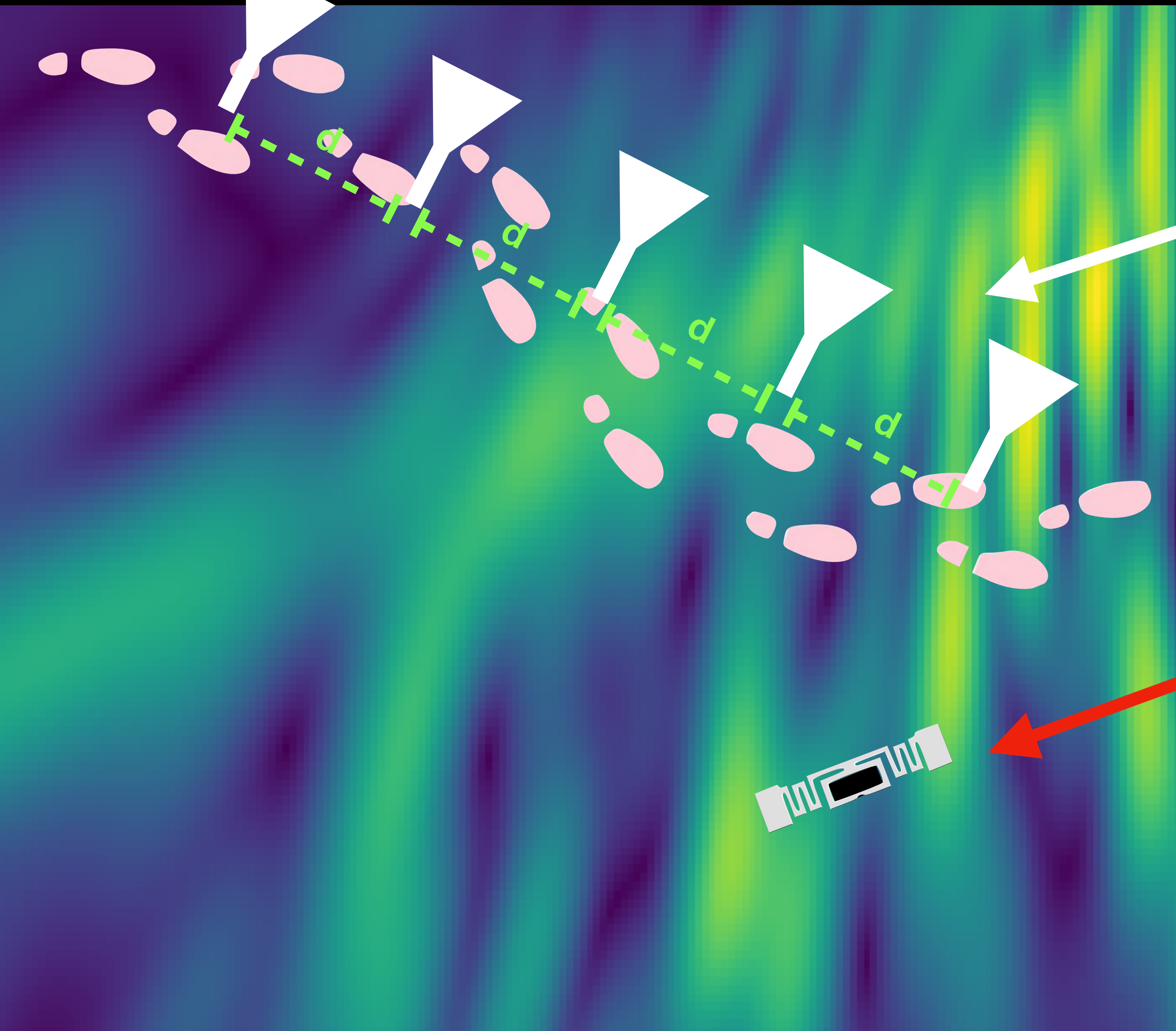


**Target
RFID**



Human Natural Movements do not have constant speed or predictable direction.

Synthetic Aperture Radar



if we approximate antenna locations
assuming constant velocity

Human Natural Movements

Target RFID

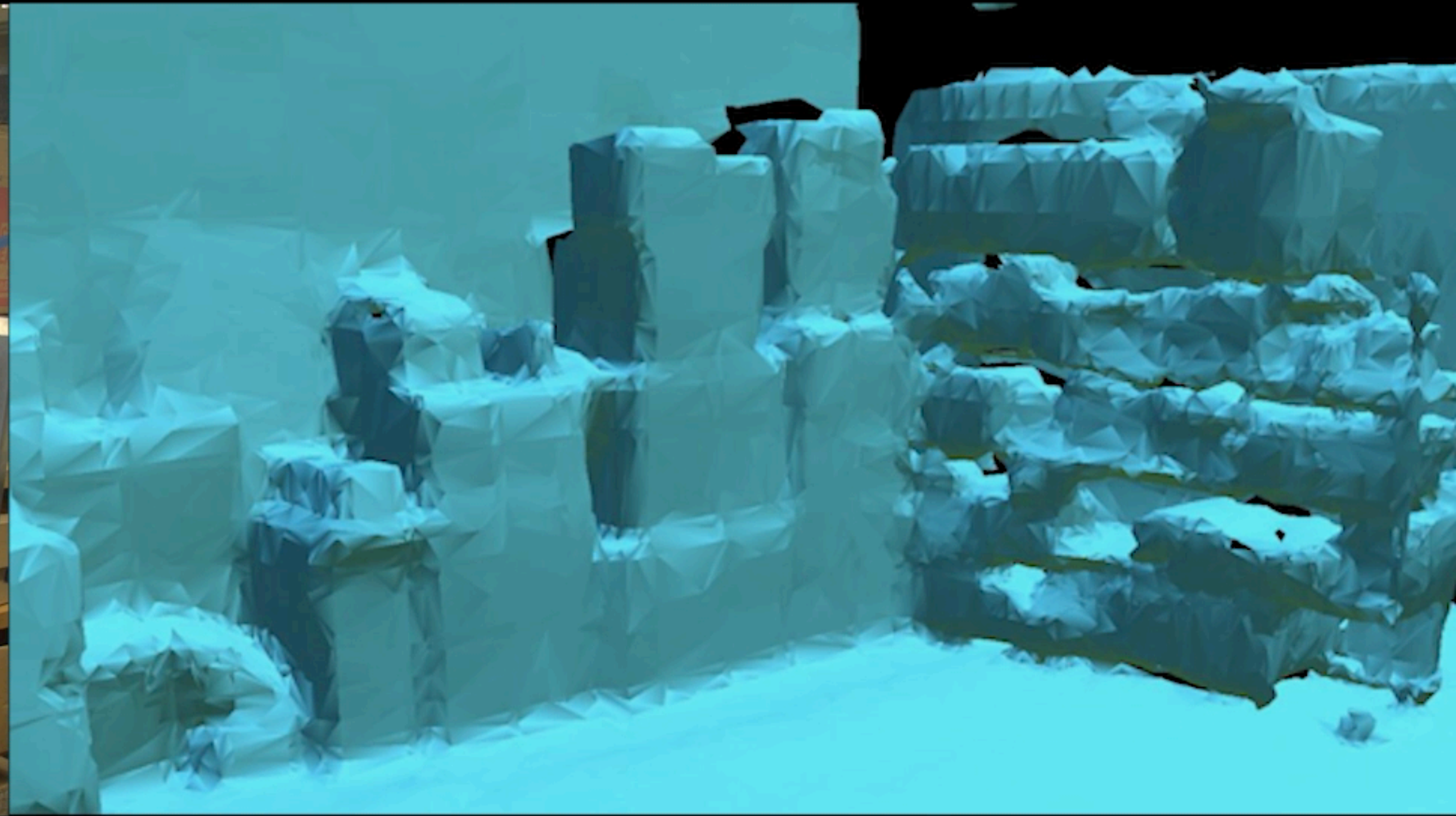
Inaccurate antenna location causes
large errors in SAR localization

How can we accurately locate tags while using natural human motion?

Idea: Exploit AR headset sensors to track the human movements.



Real World



**Virtual 3D map
using Cameras on AR headset**

Idea: Exploit AR headset sensors to track the human movements.

**Track Headset location
through visual and inertial odometry**



Real World



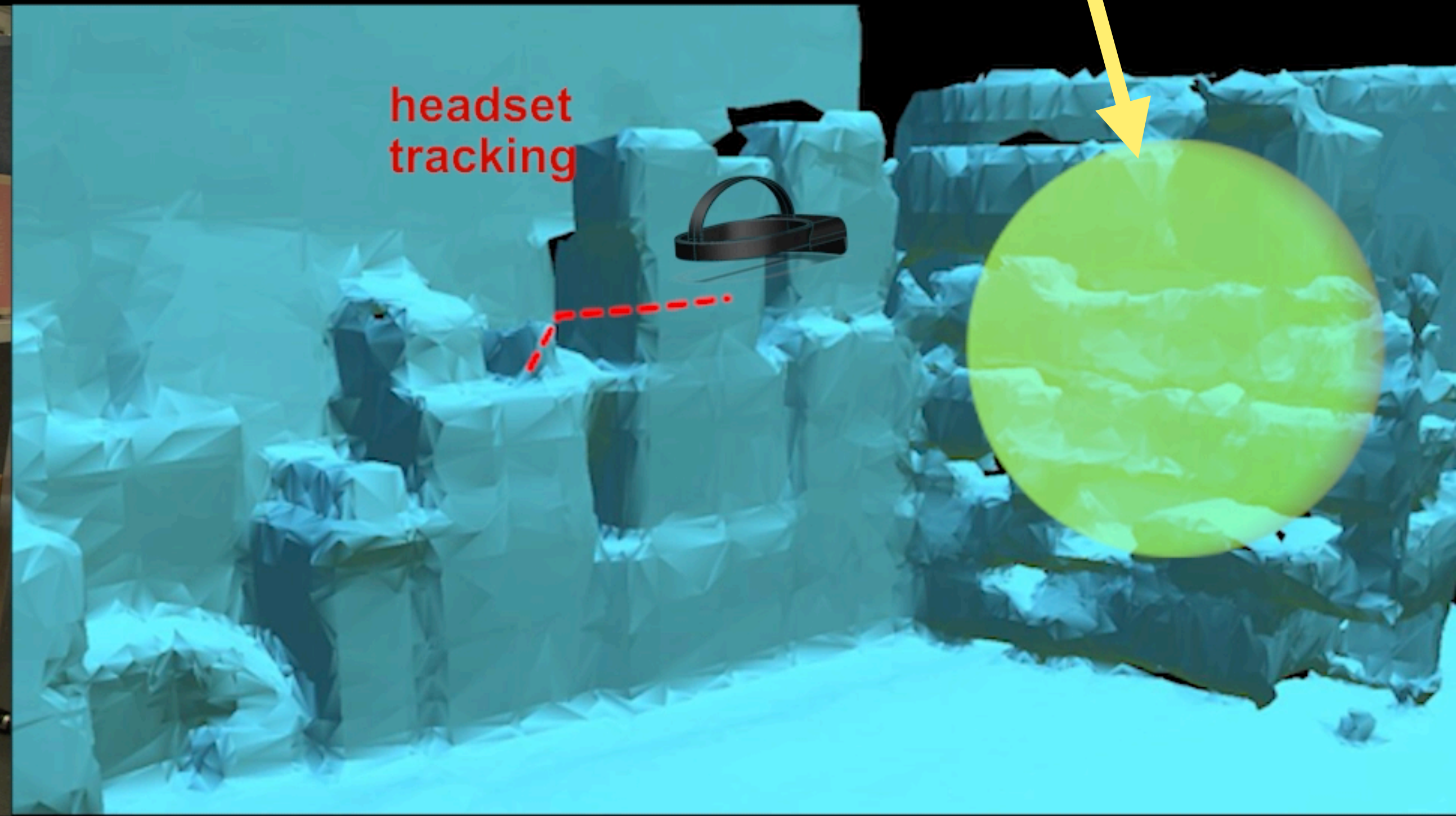
**Virtual 3D map
using Cameras on AR headset**

Idea: Exploit AR headset sensors to track the human movements.

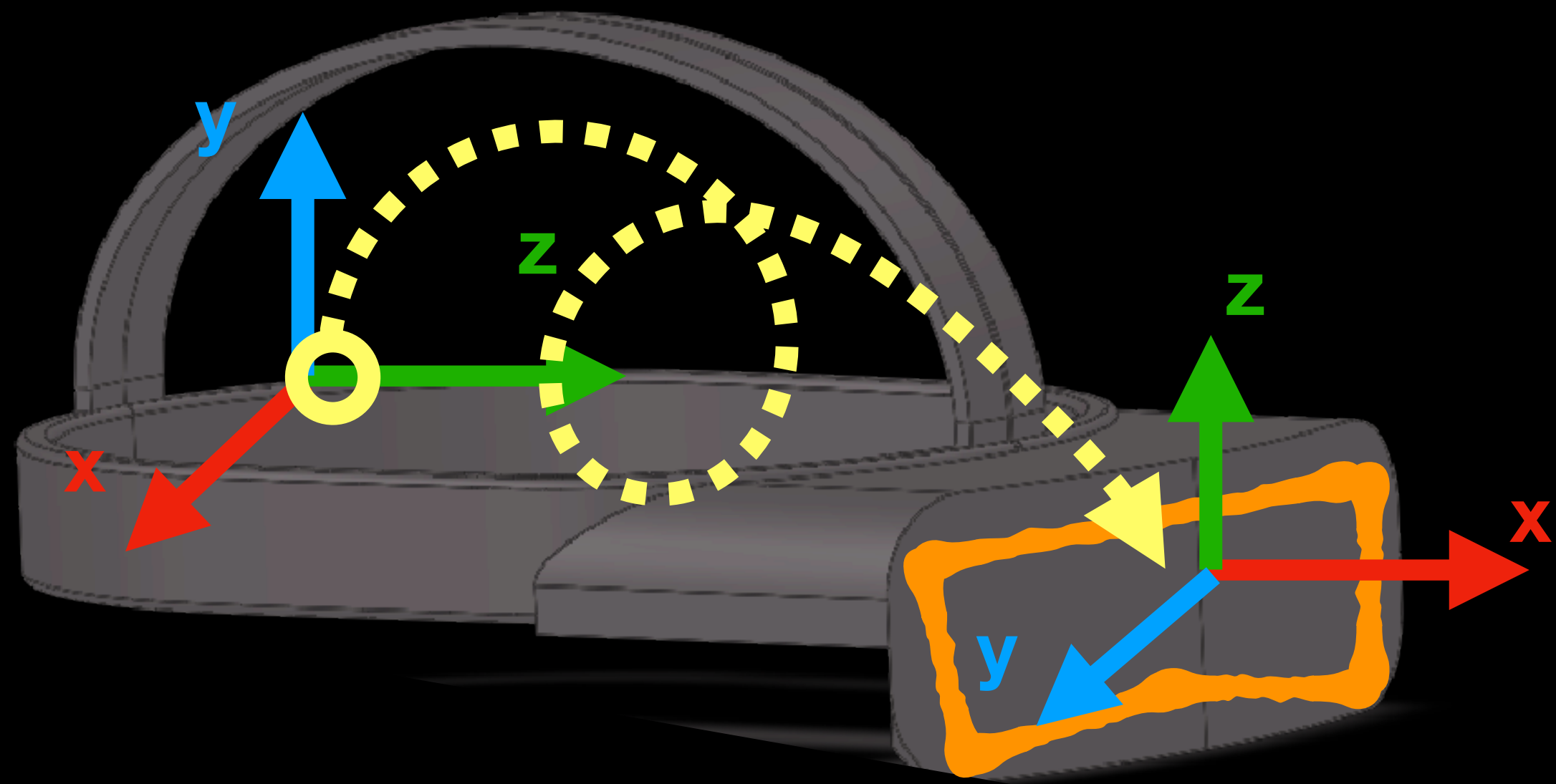
Possible Target Location



Real World



**Virtual 3D map
using Cameras on AR headset**



Hololens
Rotation

Hololens
Position

Transformation

$$W_{PA} = W_{RH} \times {}^H P^A + W_{PH}$$

$$P(x, y, z) = \left| \left| \frac{1}{M} \frac{1}{N} \sum_{j=1}^M \sum_{i=1}^N h_{i,j} e^{\frac{4\pi d_i(x, y, z)}{\lambda_j}} \right| \right|$$

User View



How can X-AR verify if user retrieves the target item?

How can X-AR verify if user retrieves the target item?

Solution 1:

- Use **Computer Vision** for object recognition

X Cannot distinguish between similar objects (e.g small or medium size shirt)

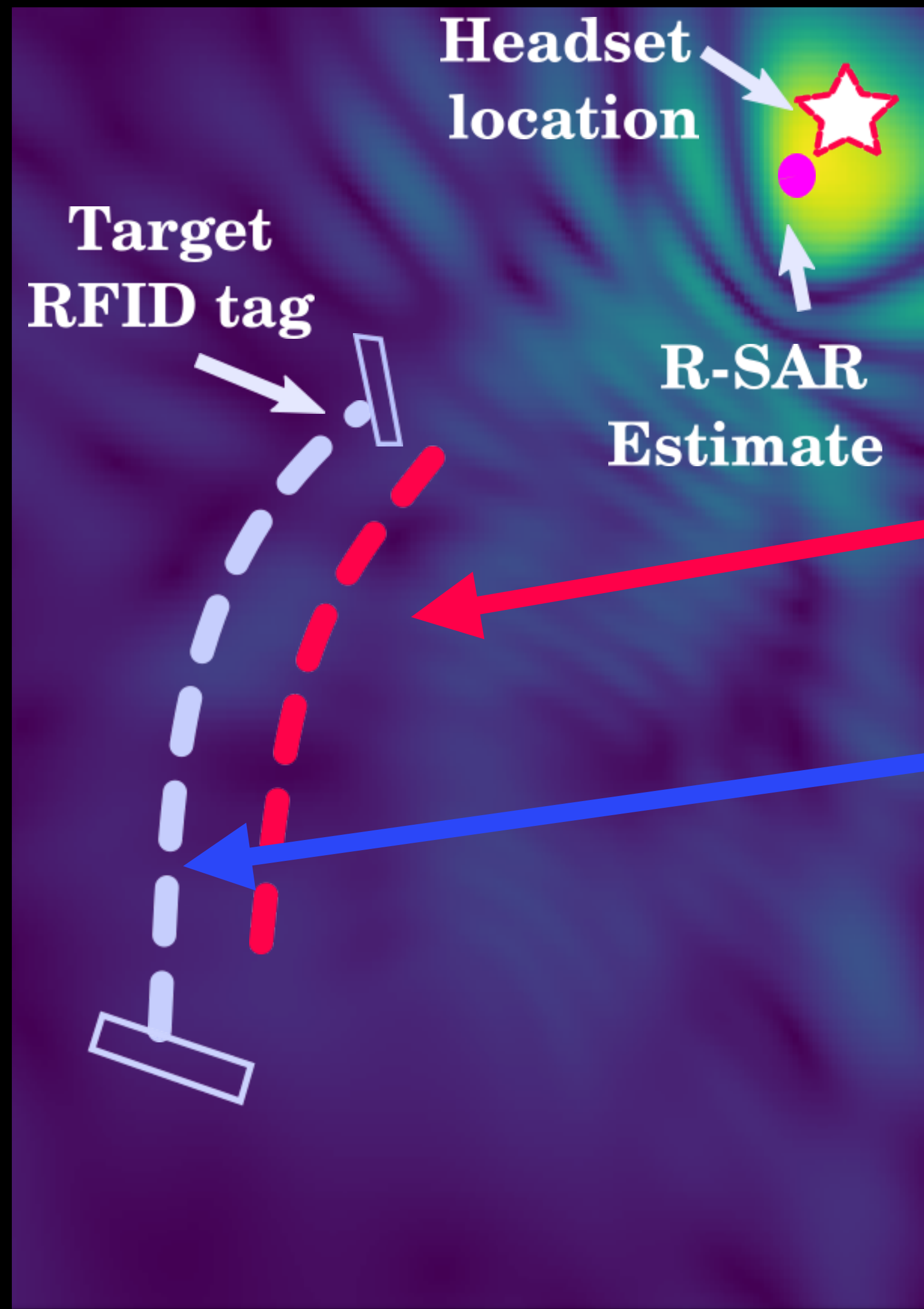
Solution 2:

- Use SAR to find RFID tag again

X Cannot locate a moving RFID tag

Idea: Use AR headset's hand tracking to create a reverse SAR with the RFID tag

How can X-AR verify if user retrieves the target item?



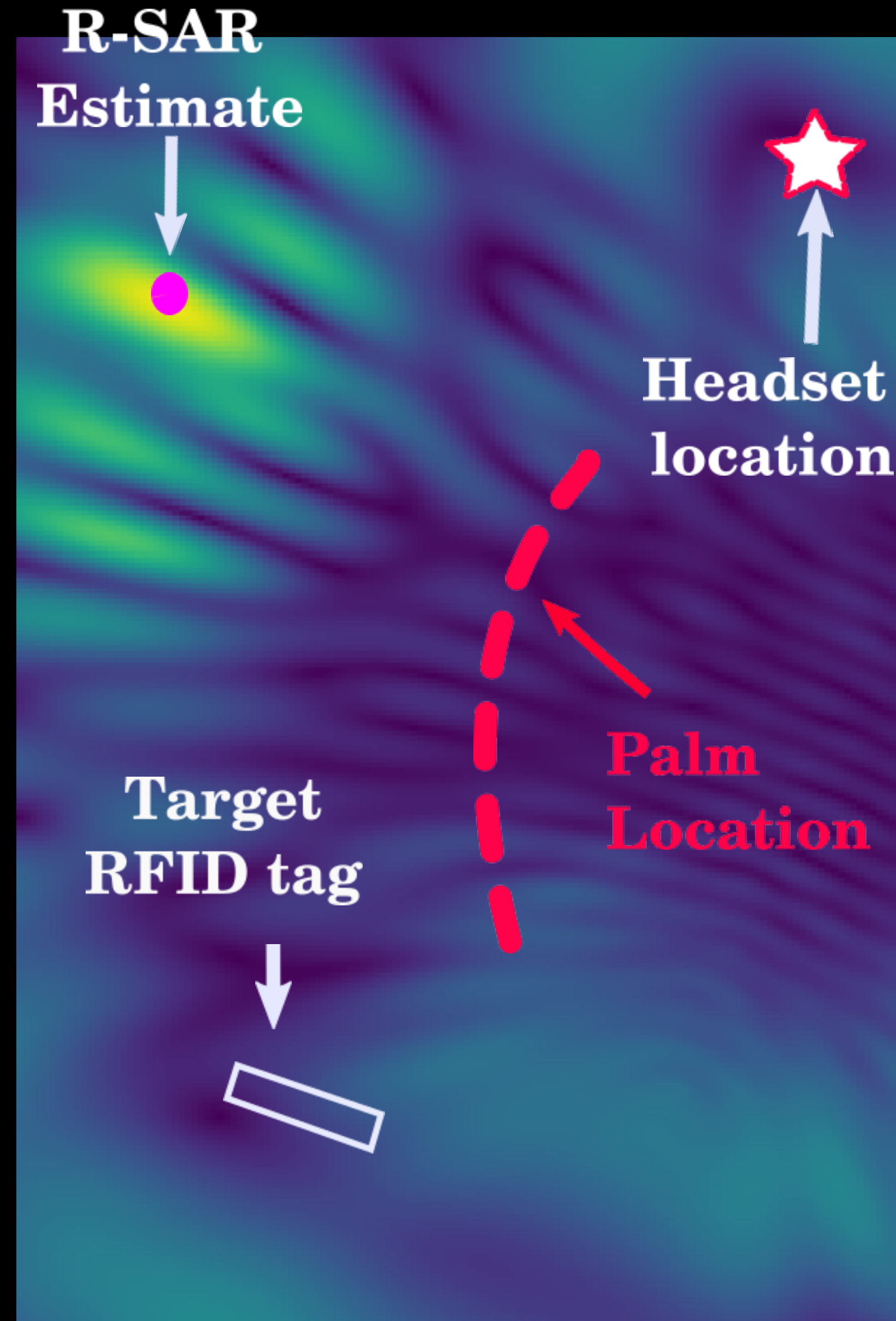
Target object is in-hand

Hand Trajectory

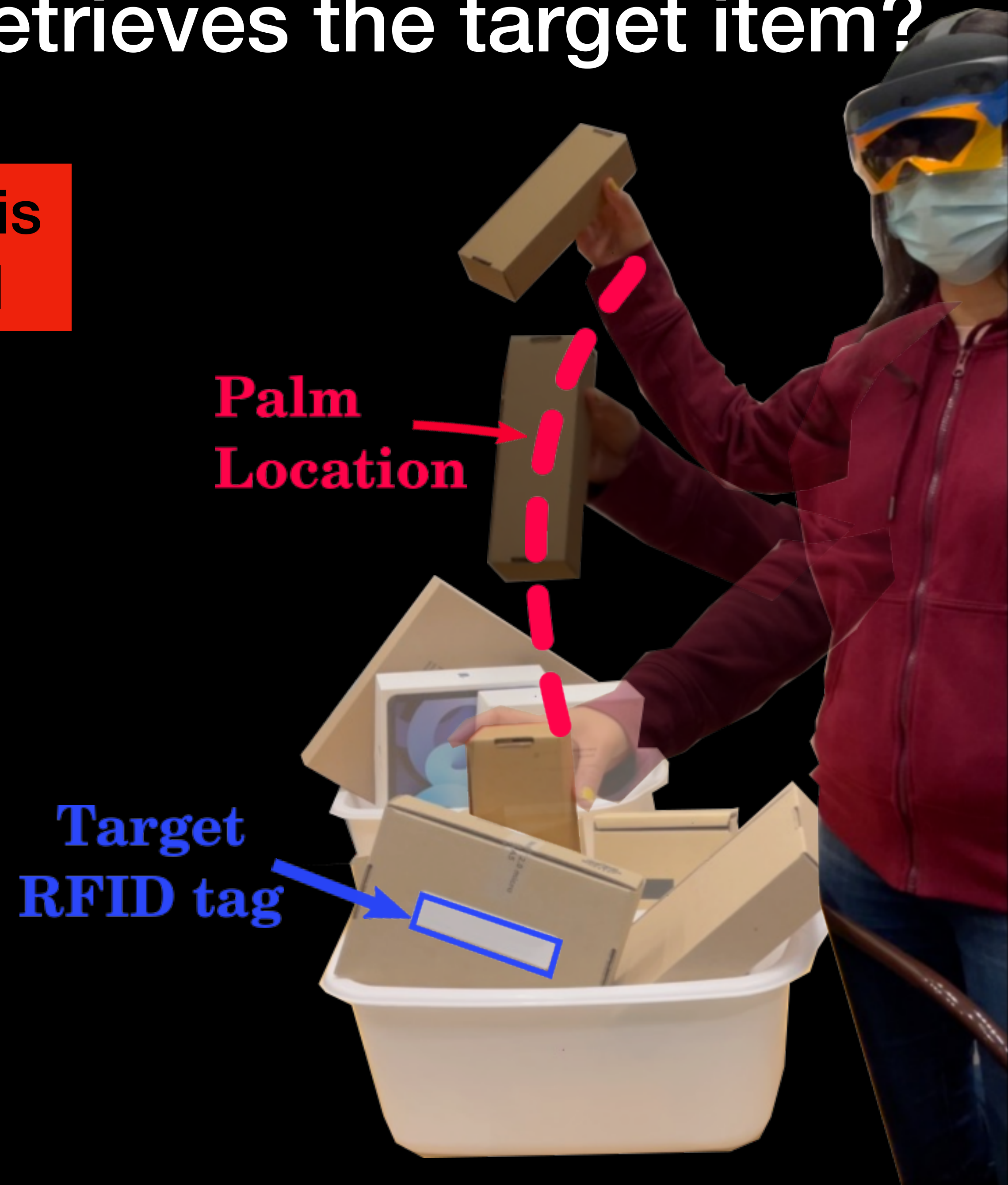
RFID tag Trajectory



How can X-AR verify if user retrieves the target item?



Target object is NOT in-hand



User view



Implementation

HoloLens

Wideband Antenna

on flexible (kapton) substrate
with 0.12 mm thickness
200 MHz BW, 920 MHz CF

Edge Server (Ubuntu Machine):

- Receives information from Pi and HoloLens
- Calculates SAR and R-SAR
- Sends commands to HoloLens

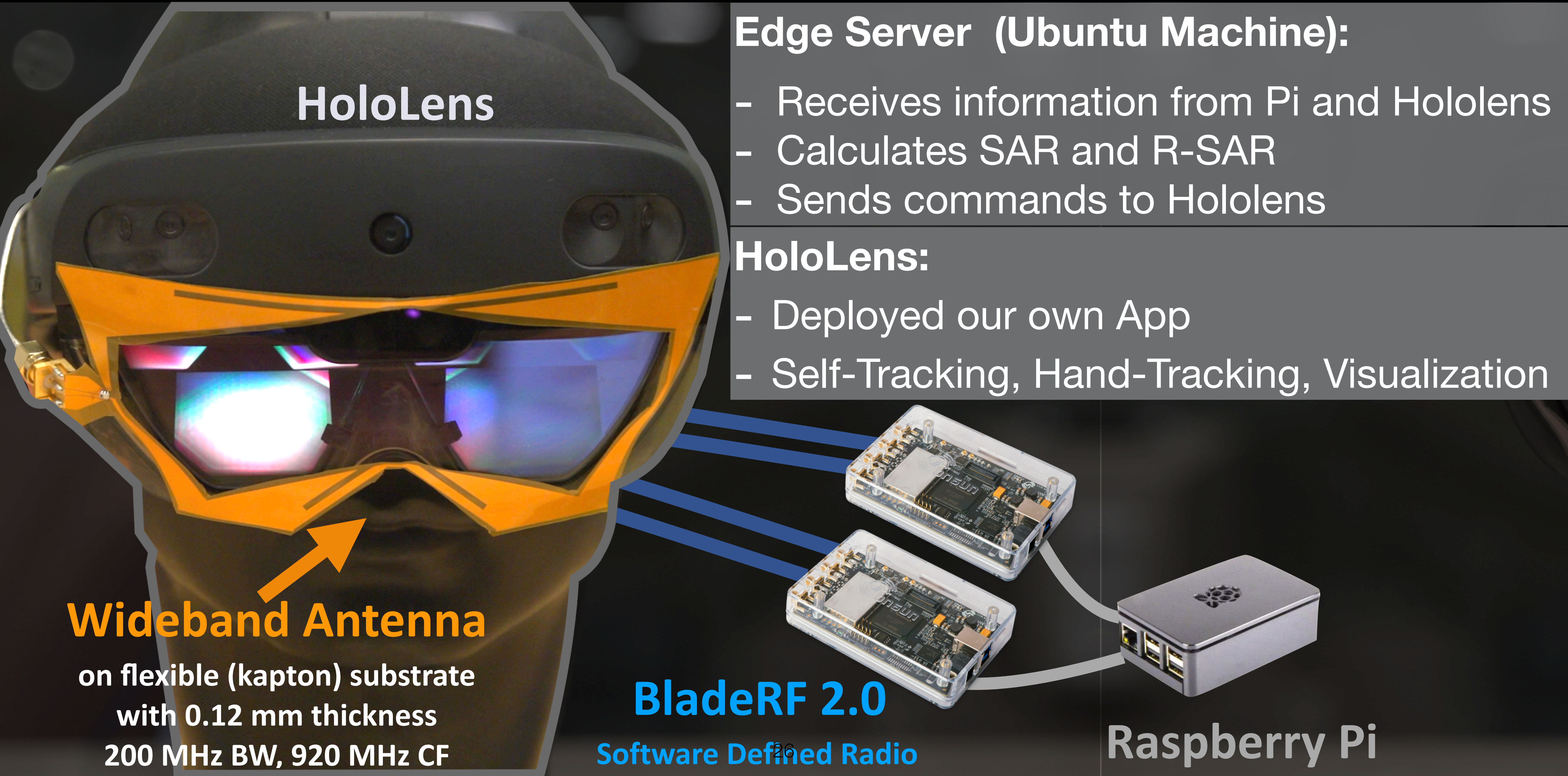
HoloLens:

- Deployed our own App
- Self-Tracking, Hand-Tracking, Visualization

BladeRF 2.0

Software Defined Radio

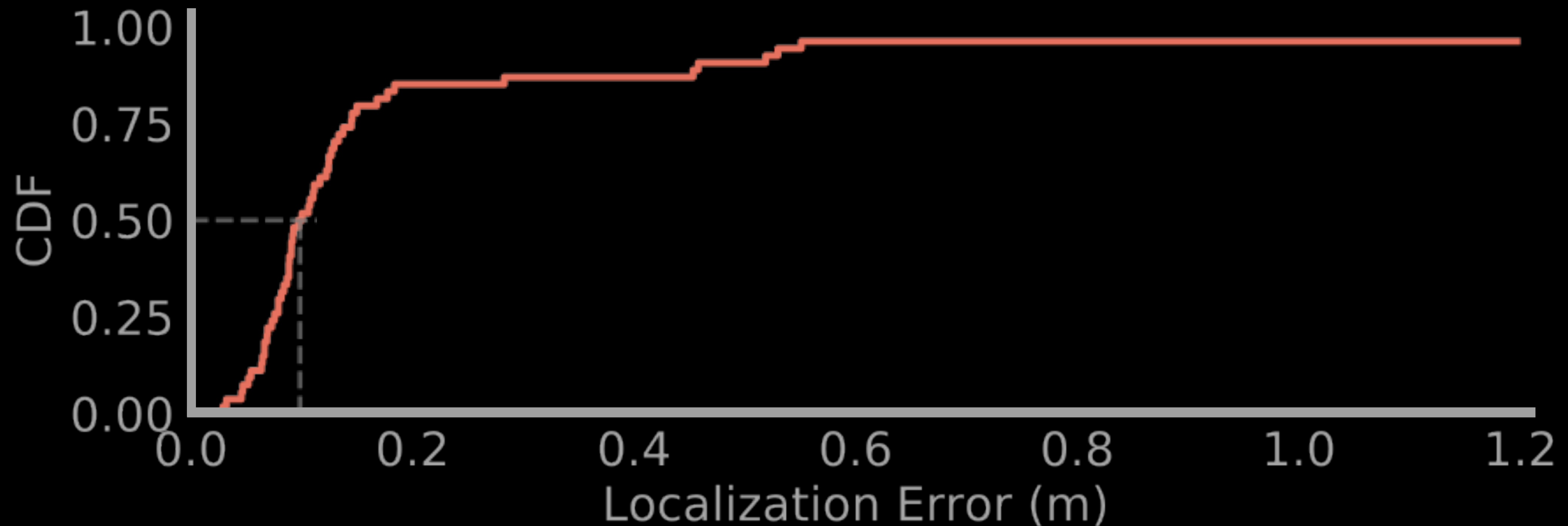
Raspberry Pi



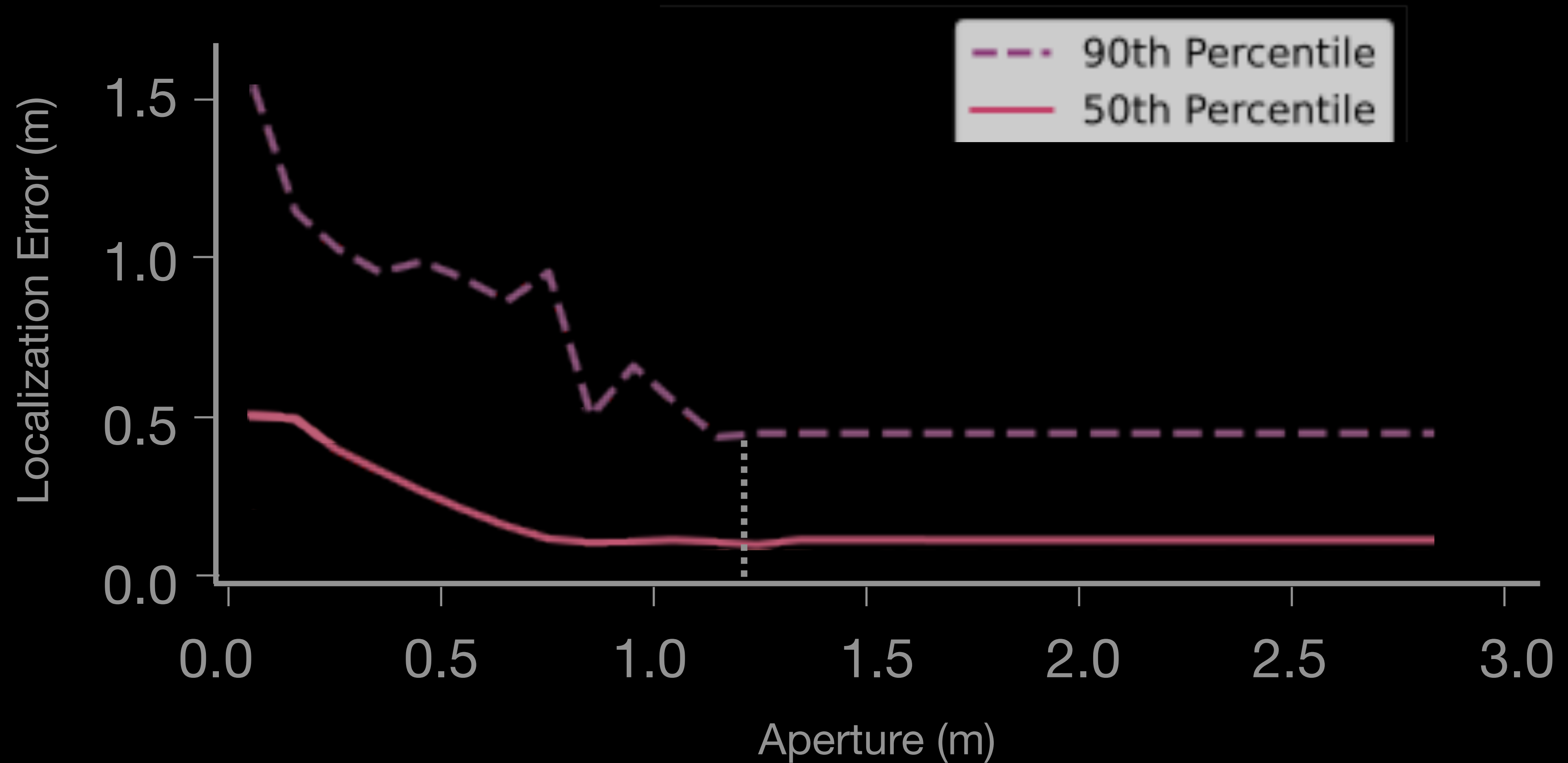
How accurate X-AR is in locating RFID tags?

User walks naturally toward a shelf or stack of boxes

Median Error is 9.8 cm



How much does the user need to walk?



How accurately X-AR can verify if target is in hand?

	Accuracy	
	Precision	Recall
RFID tagged Target in Line of sight	98%	100%
RFID tagged Target inside a box (NLOS)	100%	85.1%

Conclusion

X-AR:

First system to bridge network **wireless sensing with augmented reality** for sensing and localization

- Introduces techniques for:
 - AR-conformal, flexible and wideband Antenna
 - AR-Based SAR
 - In-hand Verification
- Opens up new applications in manufacturing, retail, warehousing, and smart homes

xar.media.mit.edu

