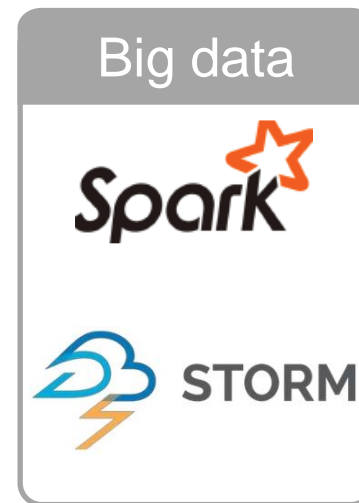
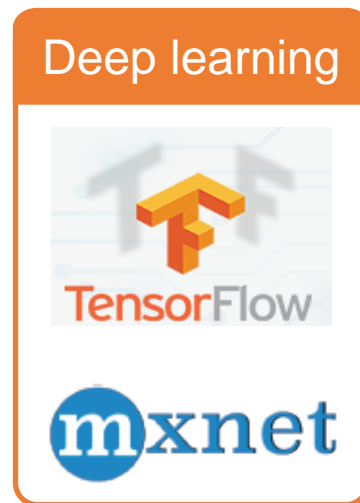
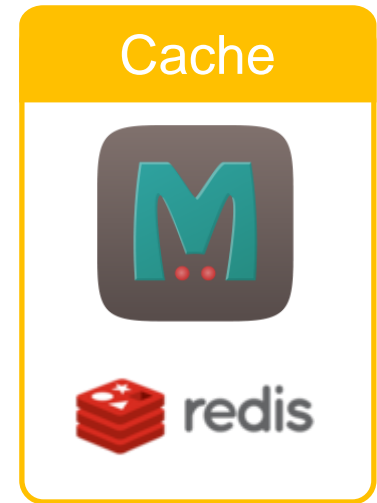
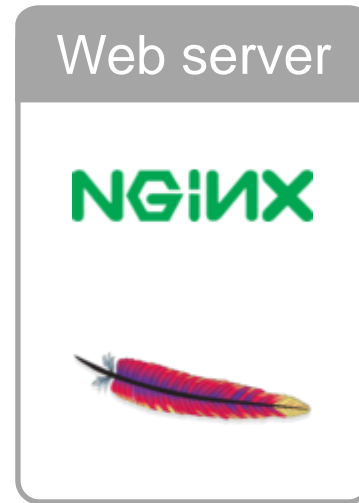


DupHunter: Flexible High-Performance Deduplication for Docker Registries

Nannan Zhao, Hadeel Albahar, Subil Abraham,
Keren Chen, Vasily Tarasov, Dimitrios Skourtis,
Lukas Rupprecht, Ali Anwar, and Ali R. Butt

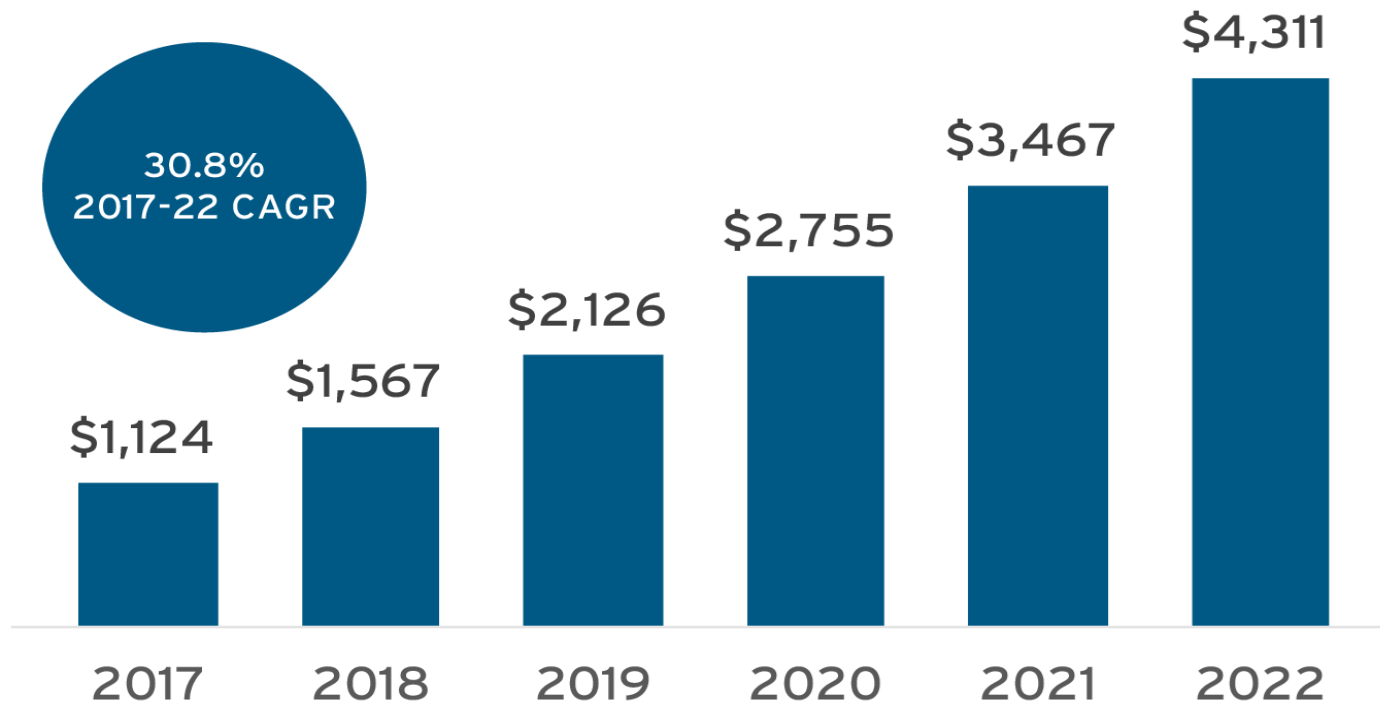


Containers are ubiquitous



Application containerization is becoming a significant market player

Application Containers: Total Market Revenue (\$M)





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Docker image dataset is growing fast!

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How to efficiently manage the ever-growing image dataset for Docker registries?



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Our contribution: DupHunter—a framework to deduplicate images in Docker registries

- We make two key observations:
 1. Container images exhibit a lot of redundancy.
 2. User access pattern is predictable.

- We design DupHunter to work with compressed images and provide layer deduplication and reduce layer restore overhead.

- We evaluate DupHunter with representative real world workloads. Compared to the state of the art, DupHunter:
 - reduces storage **space** by up to **6.9x**.
 - reduces the **GET layer latency** up to **2.8x**.

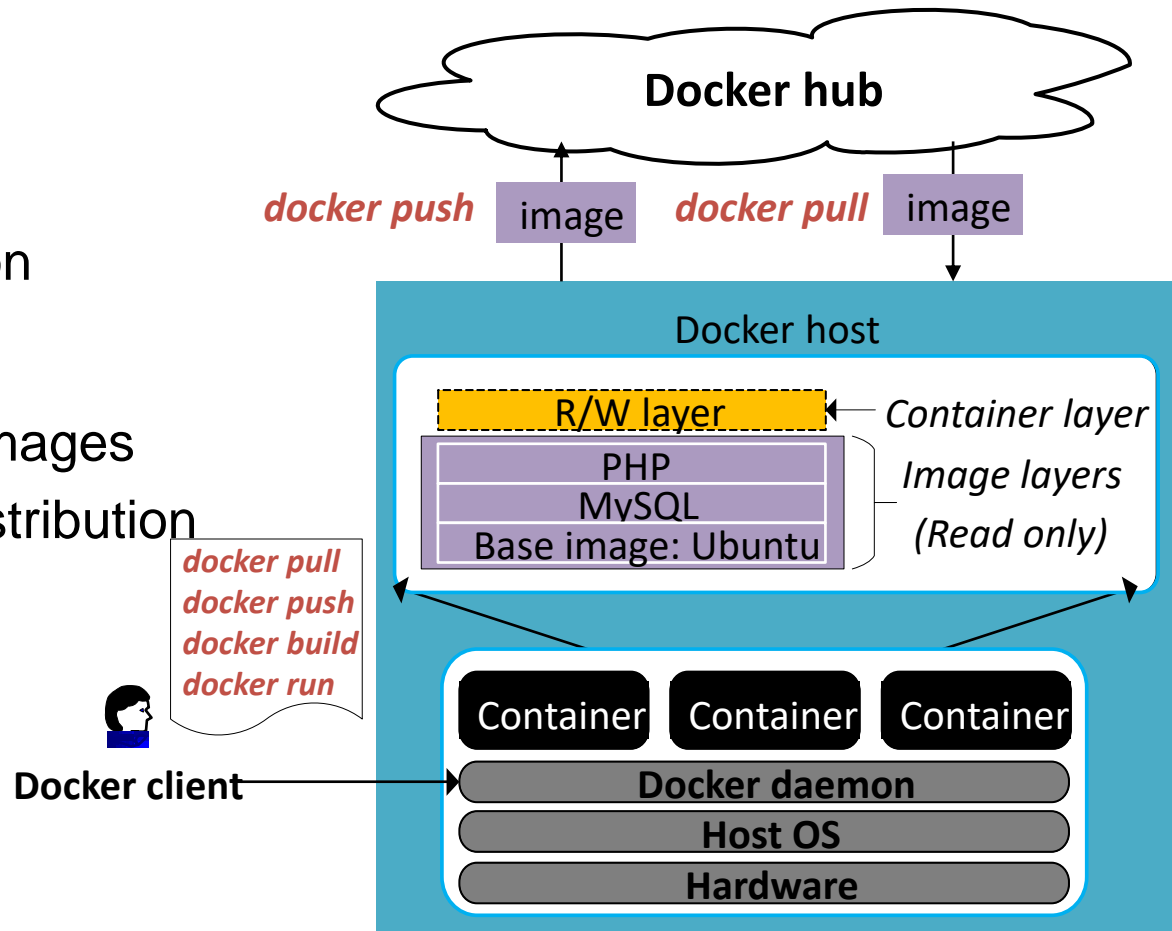
Overview of Docker

❑ Docker container is a self-contained executable package, that is:

- Lightweight
- Portable
- Provides Isolation

❑ Docker registry:

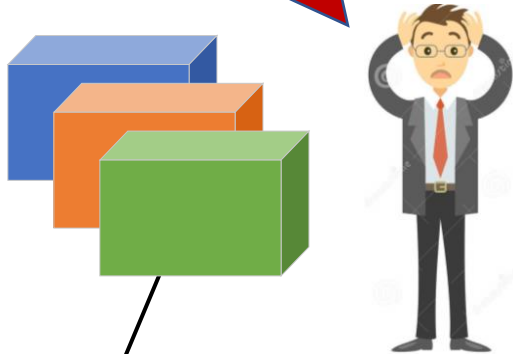
- Stores Docker images
- Supports fast distribution
- Facilitates easy deployment



Key observation I: Image dataset has large amount of redundant files

- ❑ Container images have a lot of redundancy.
 - 97% of files across layers are duplicates!
- ❑ Existing technologies such as Jdupes, VDO, Btrfs, ZFS, and Ceph are unable to harness this redundancy.

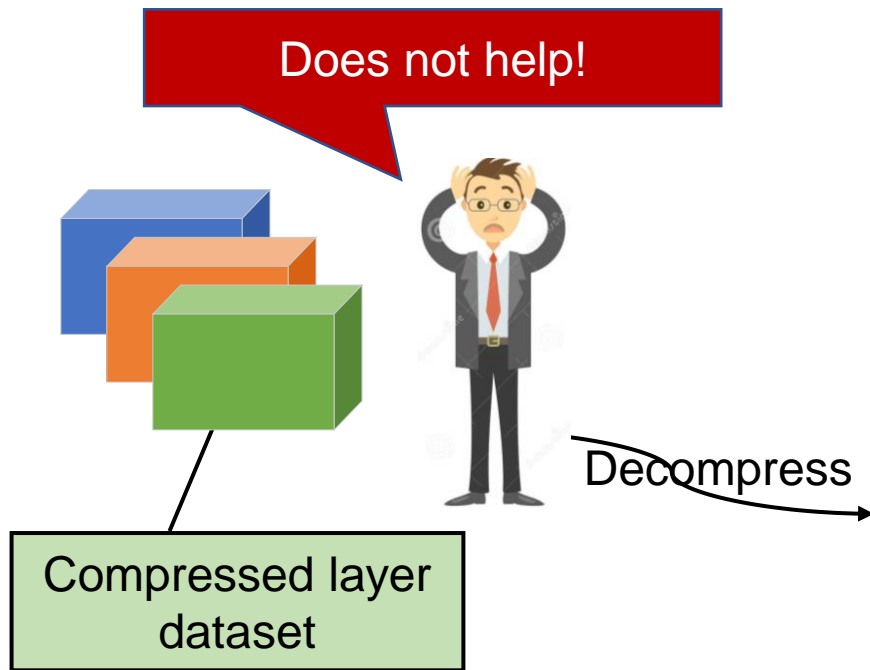
Does not help!



Compressed layer
dataset

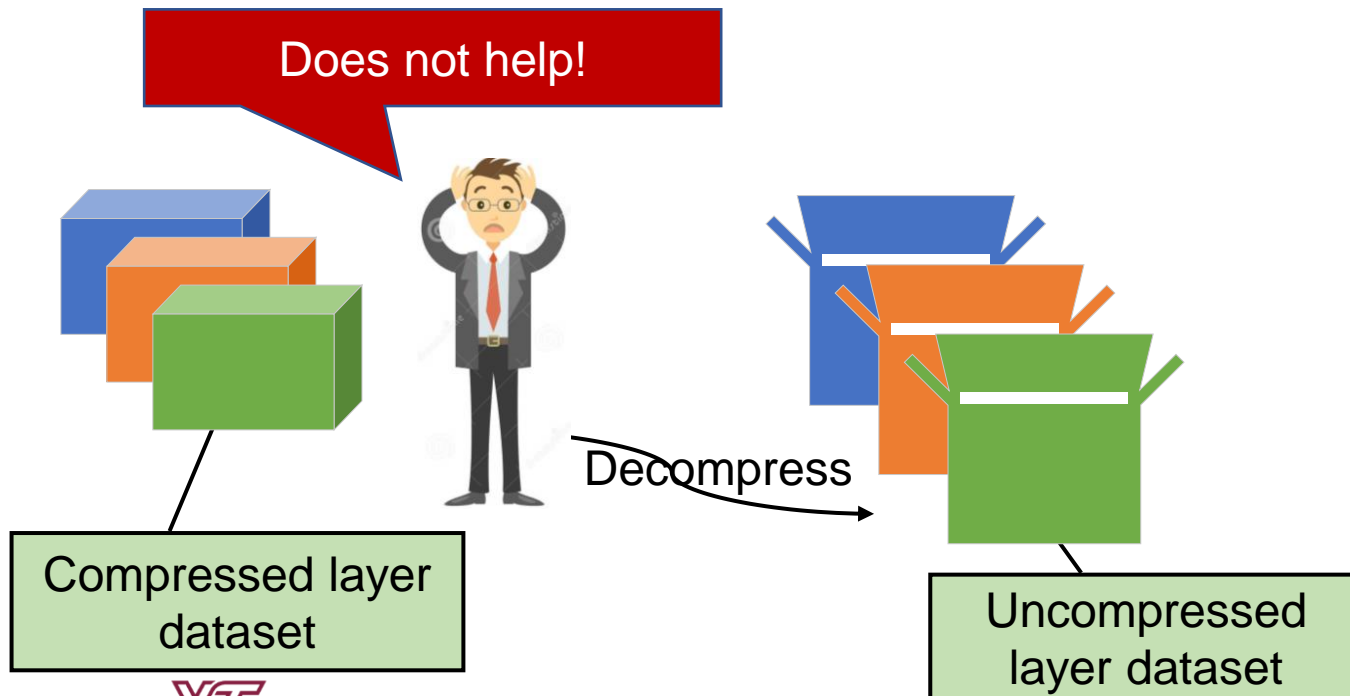
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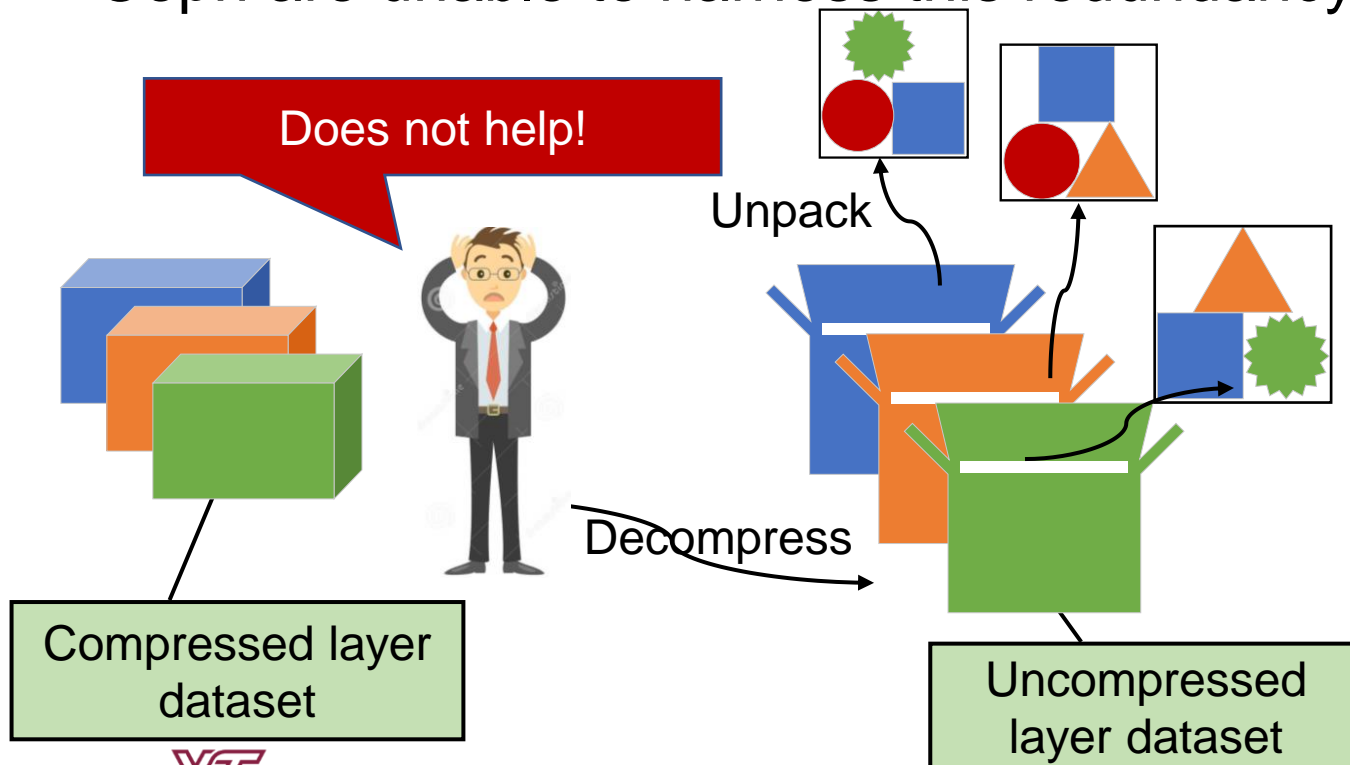
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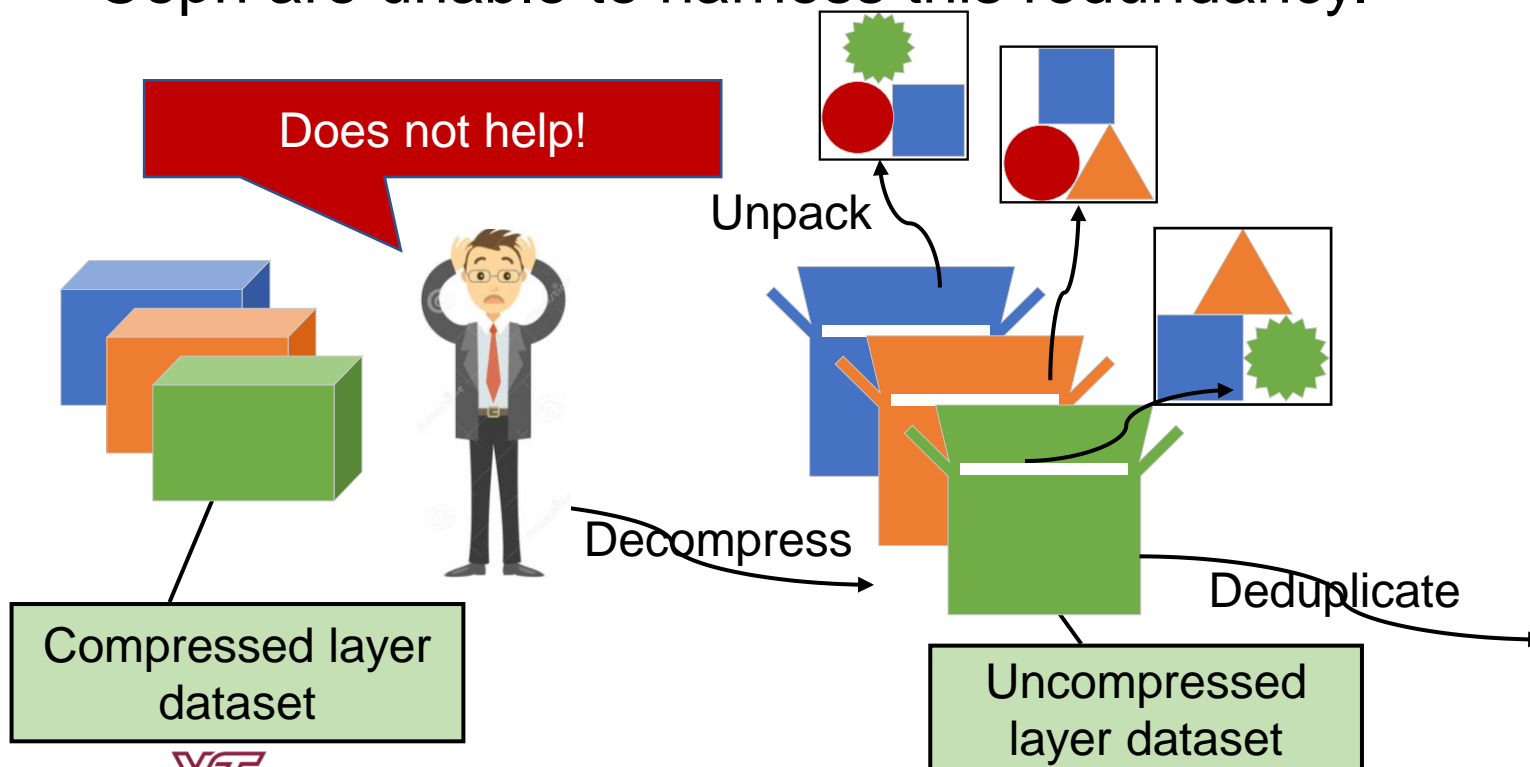
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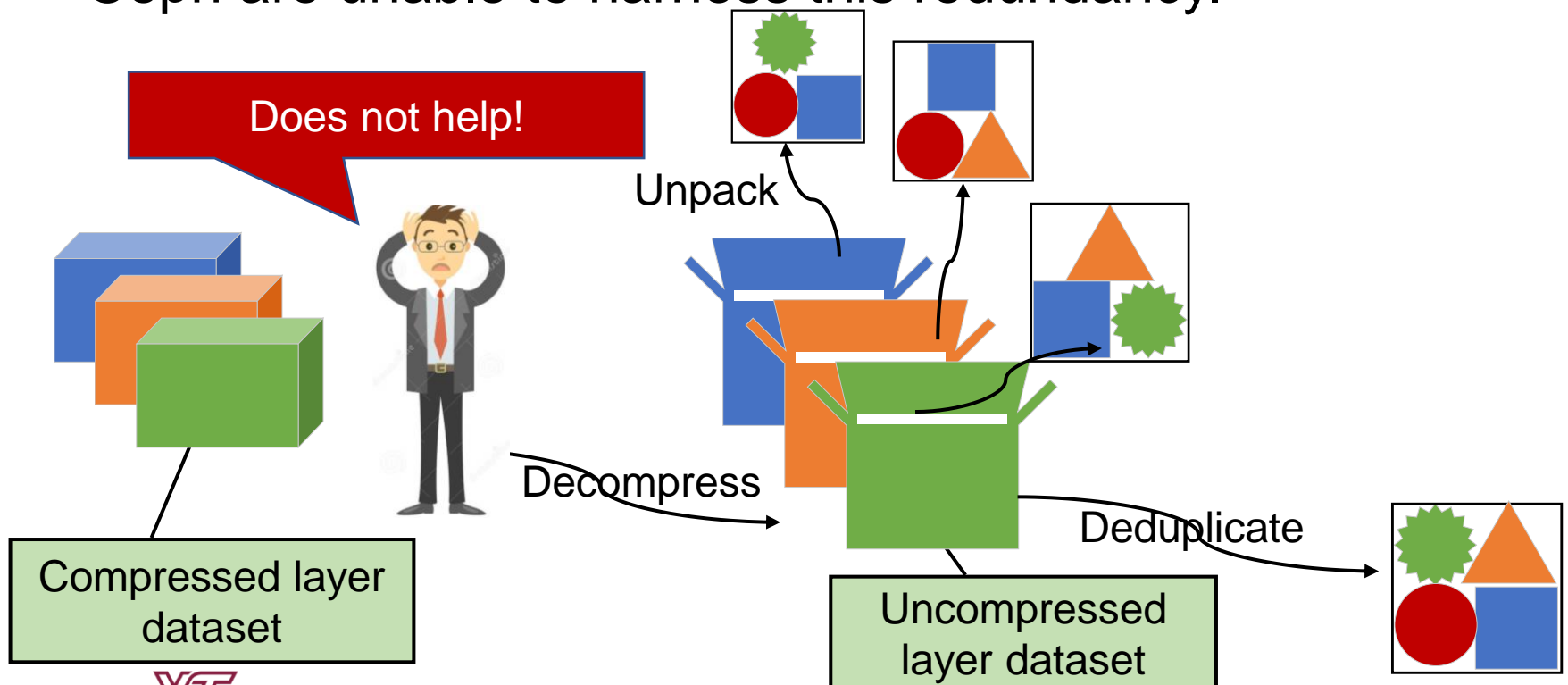
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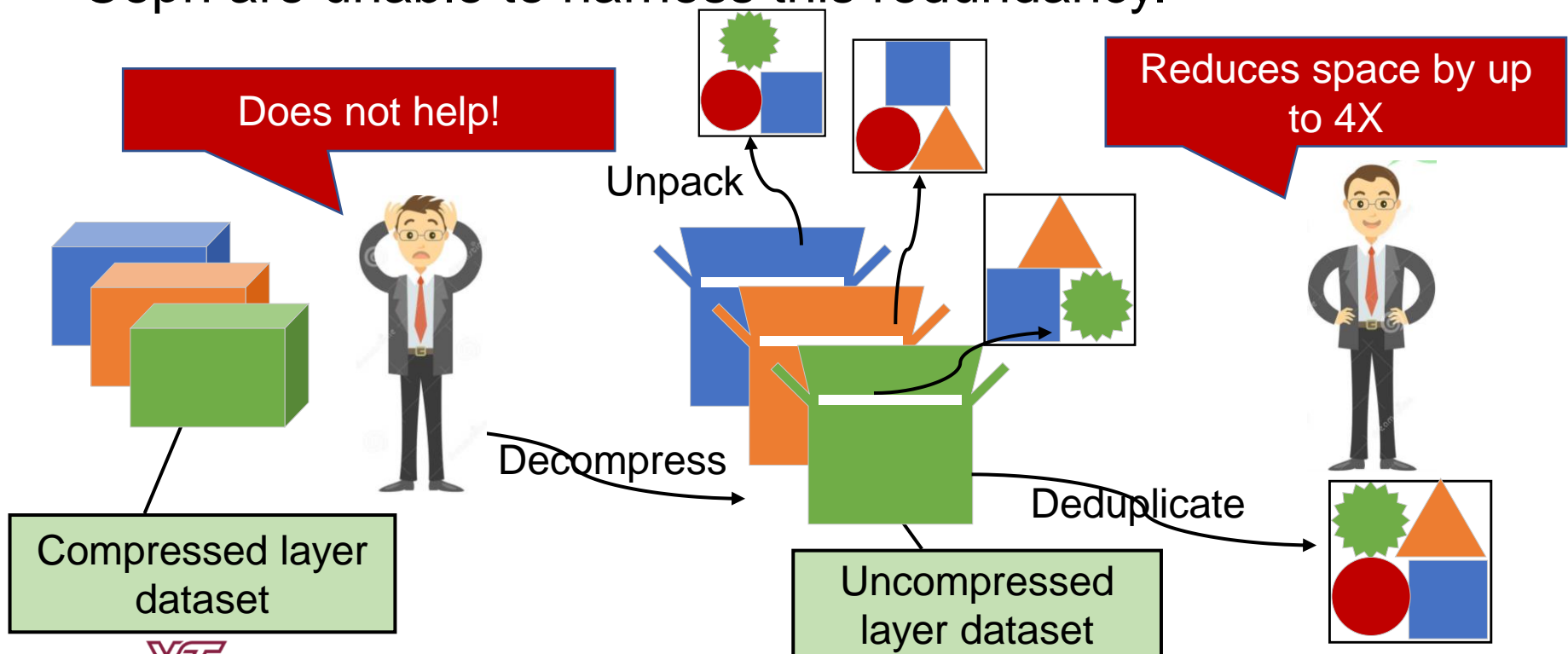
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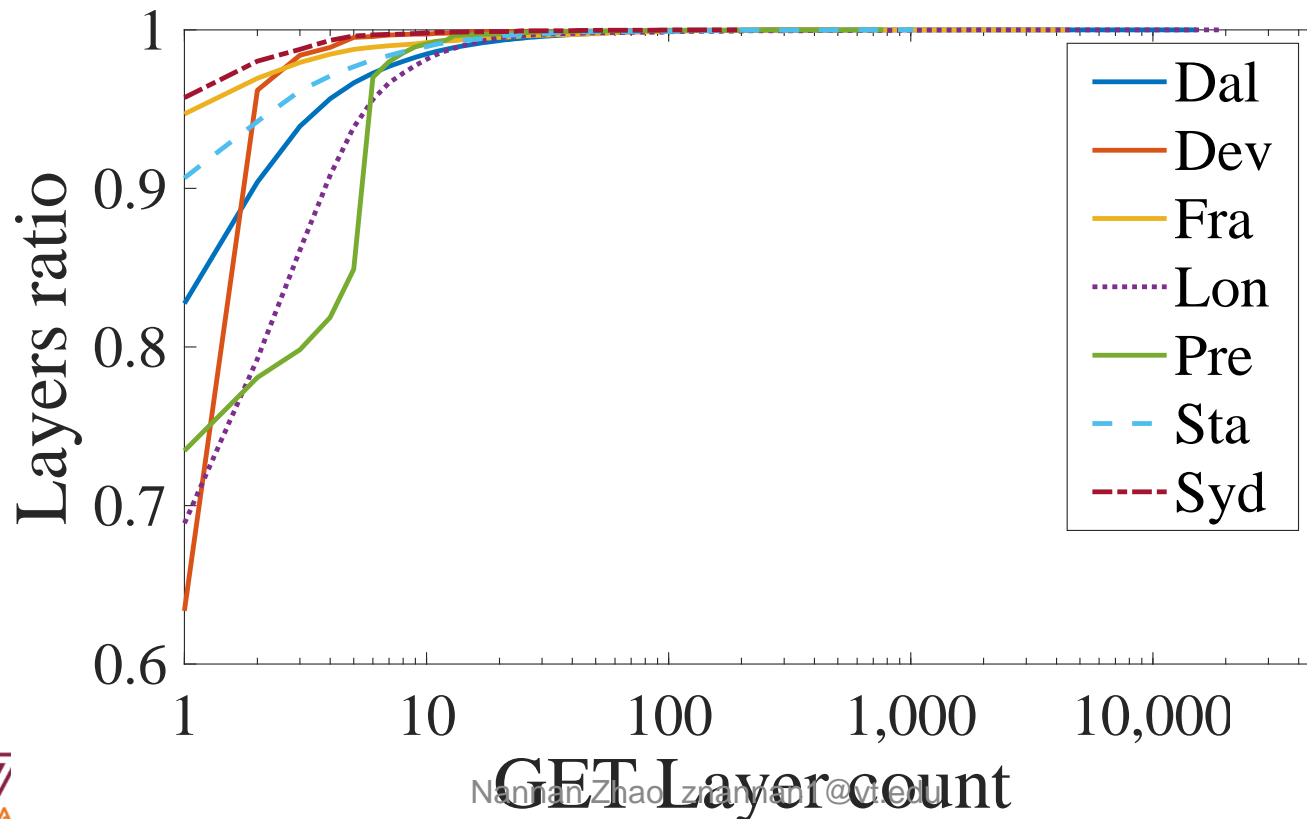
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Layer restore incurs considerable overhead for layer pulling latency up to 98x!

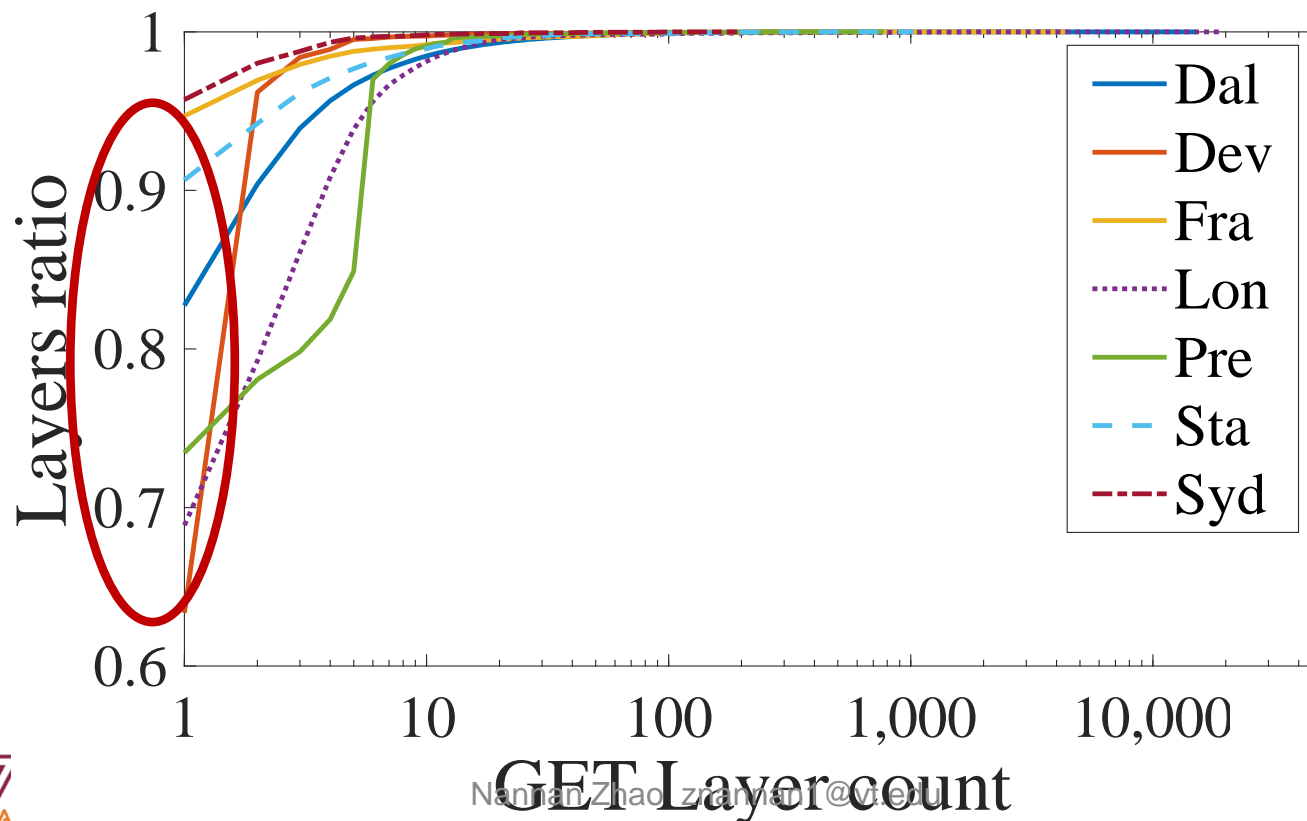
Key observation II: Predictable user access pattern

- ❑ We observe a consistent user pulling pattern: Pull manifest first, then layers, but not all of the layers will be pulled.
- ❑ We performed a quantitative study using a 75-day IBM Cloud Registry workload with 7 availability zones.



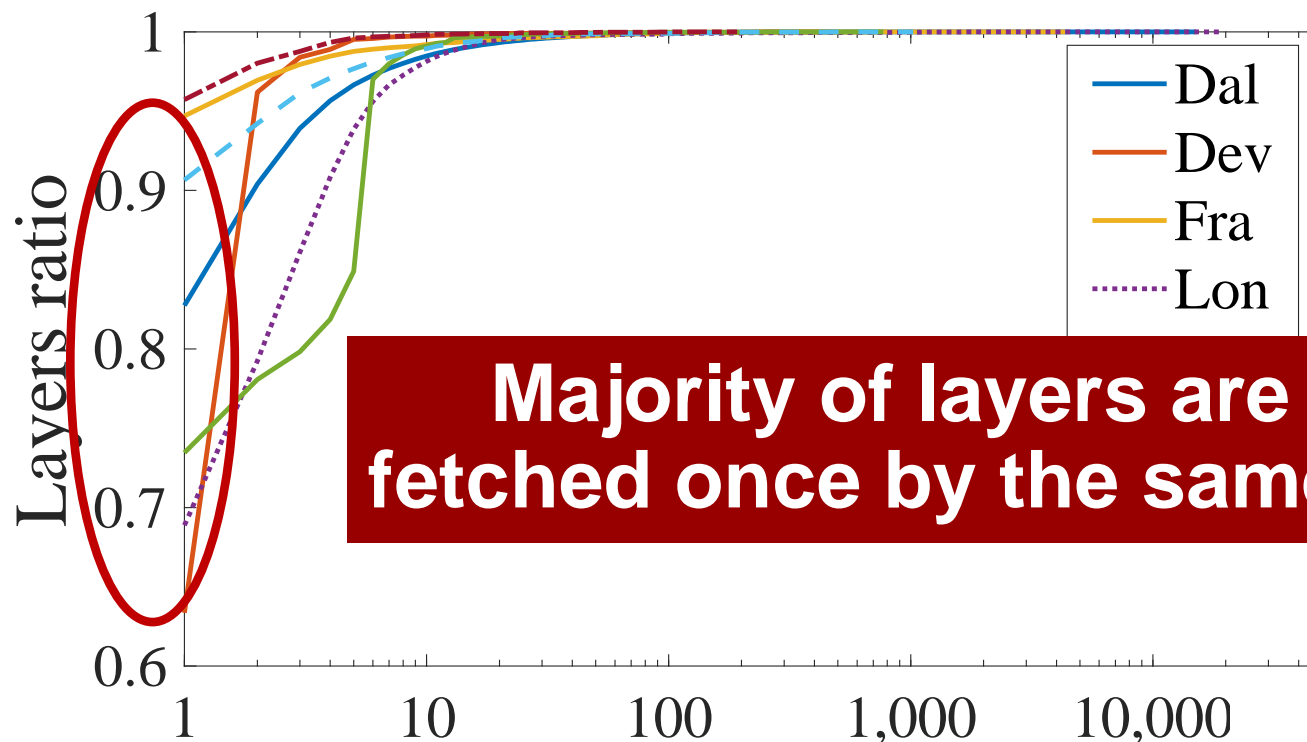
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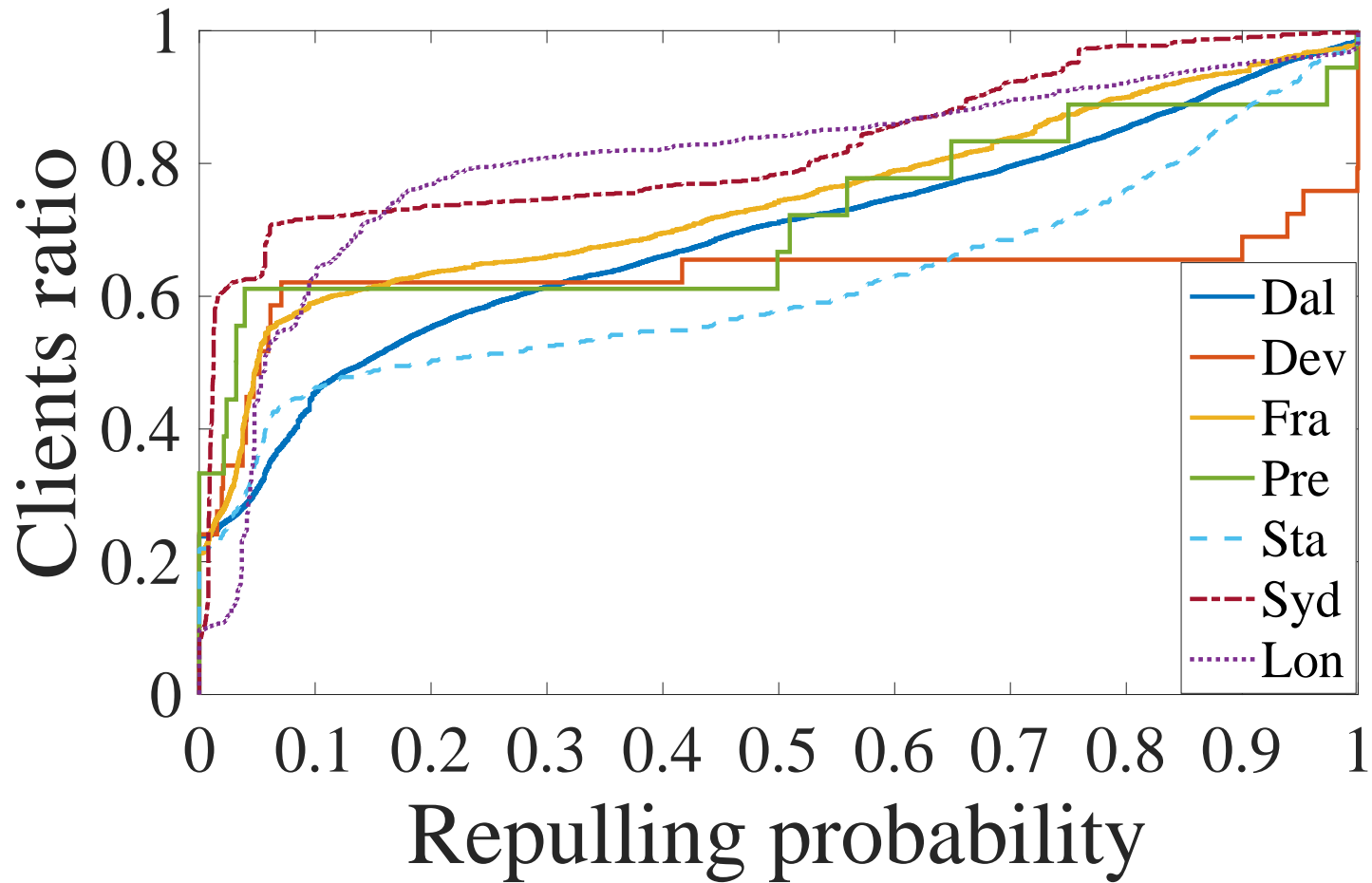
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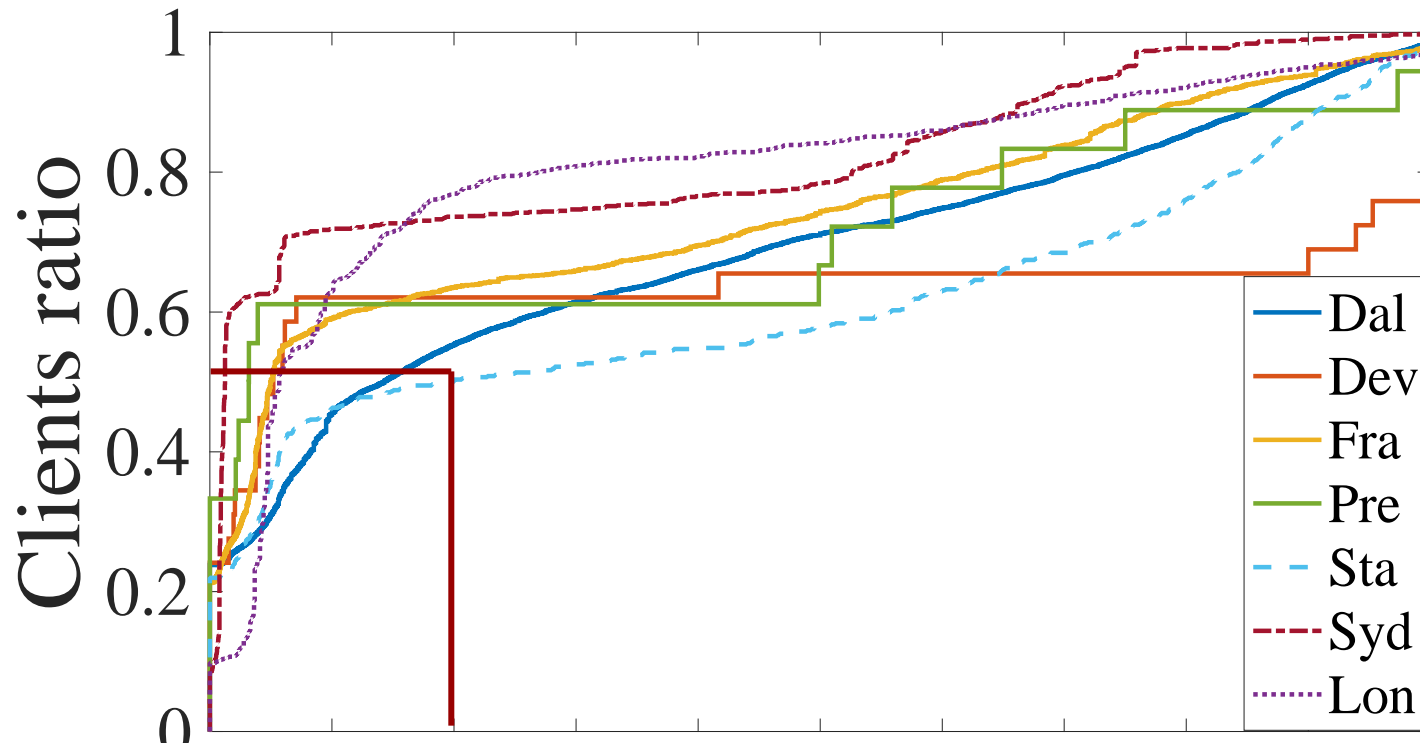


Majority of layers are only fetched once by the same client.

Key observation II-b: User repulling pattern can also be predicted

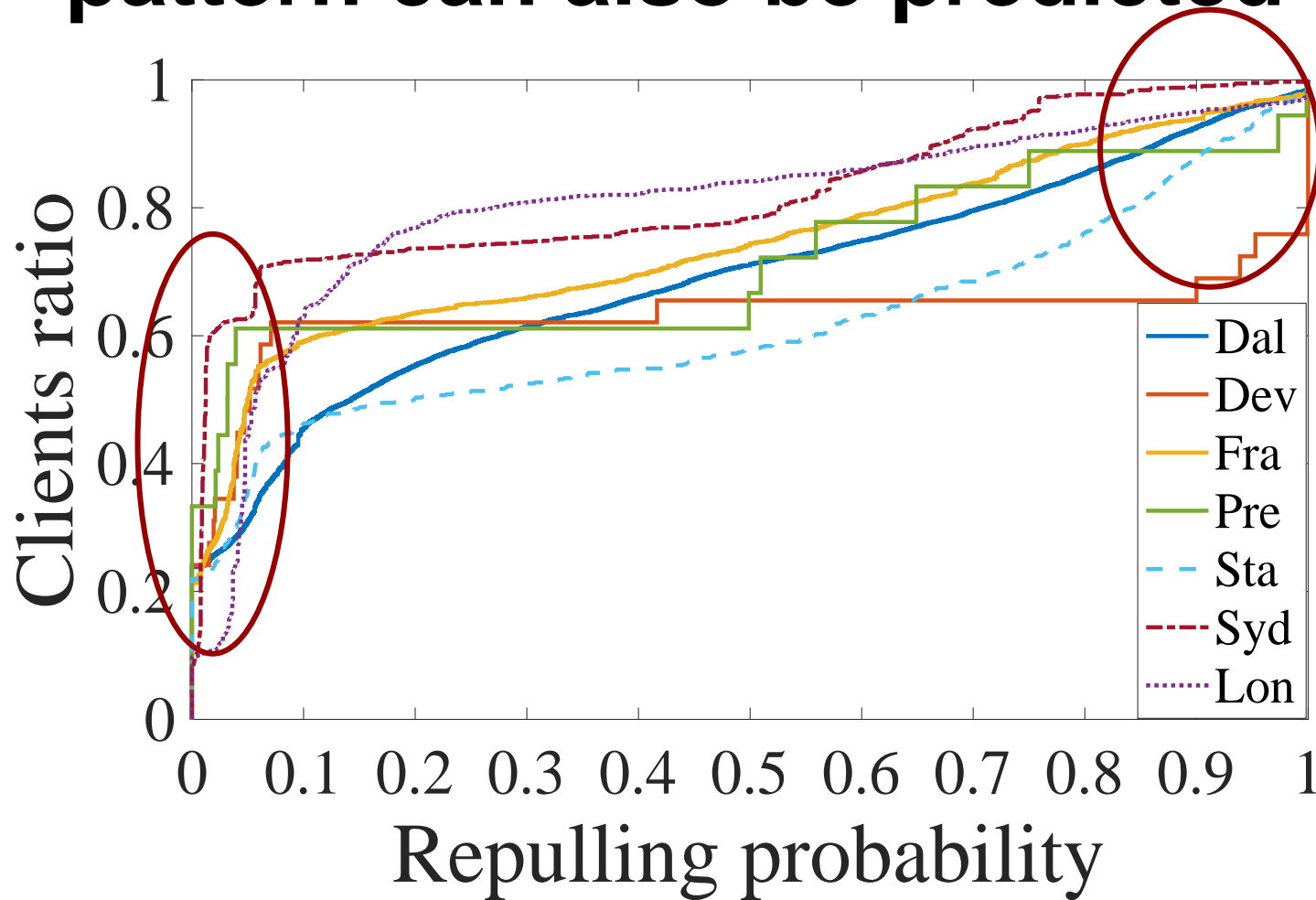


Key observation II-b: User repulling pattern can also be predicted

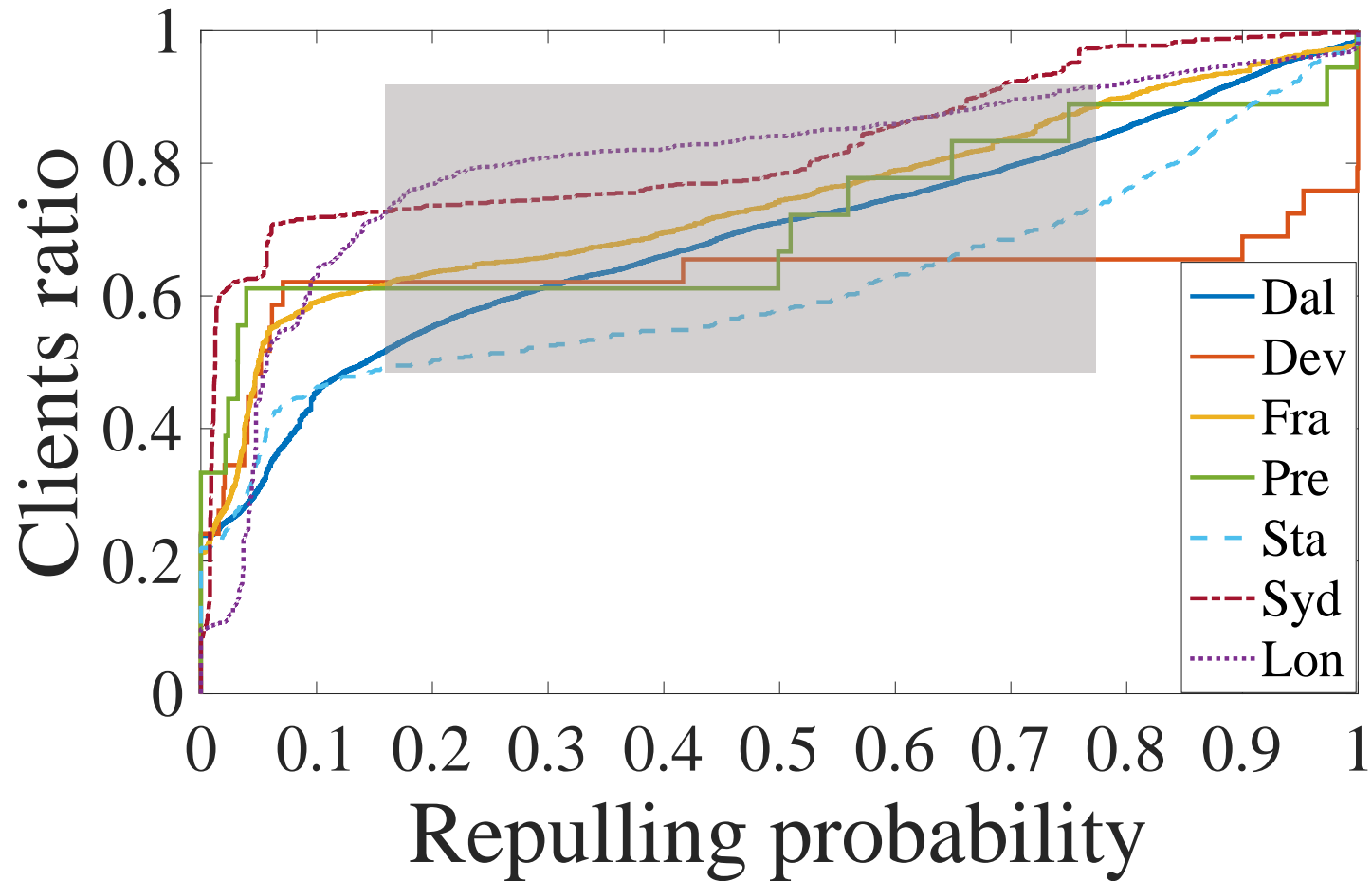


Half of the clients have a repull probability less than 0.2 → many clients pull a layer only once.

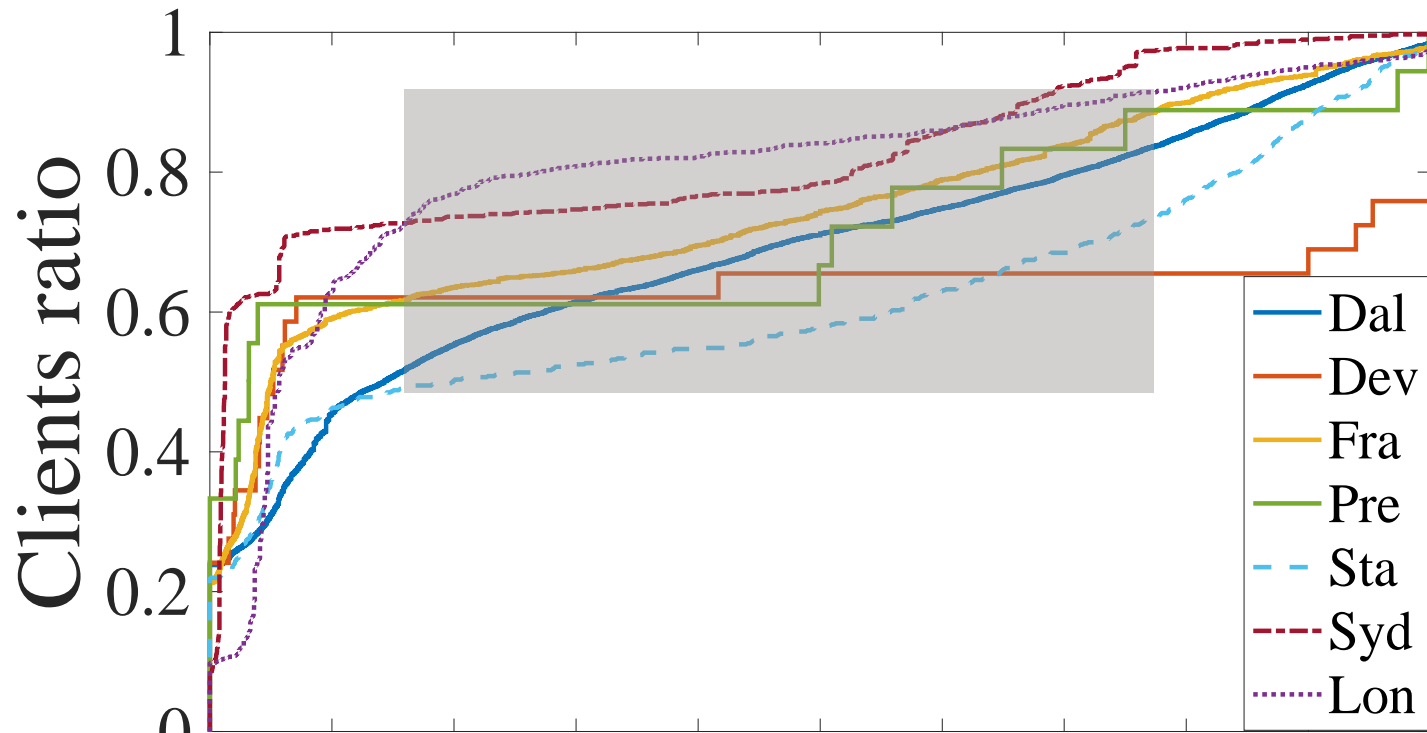
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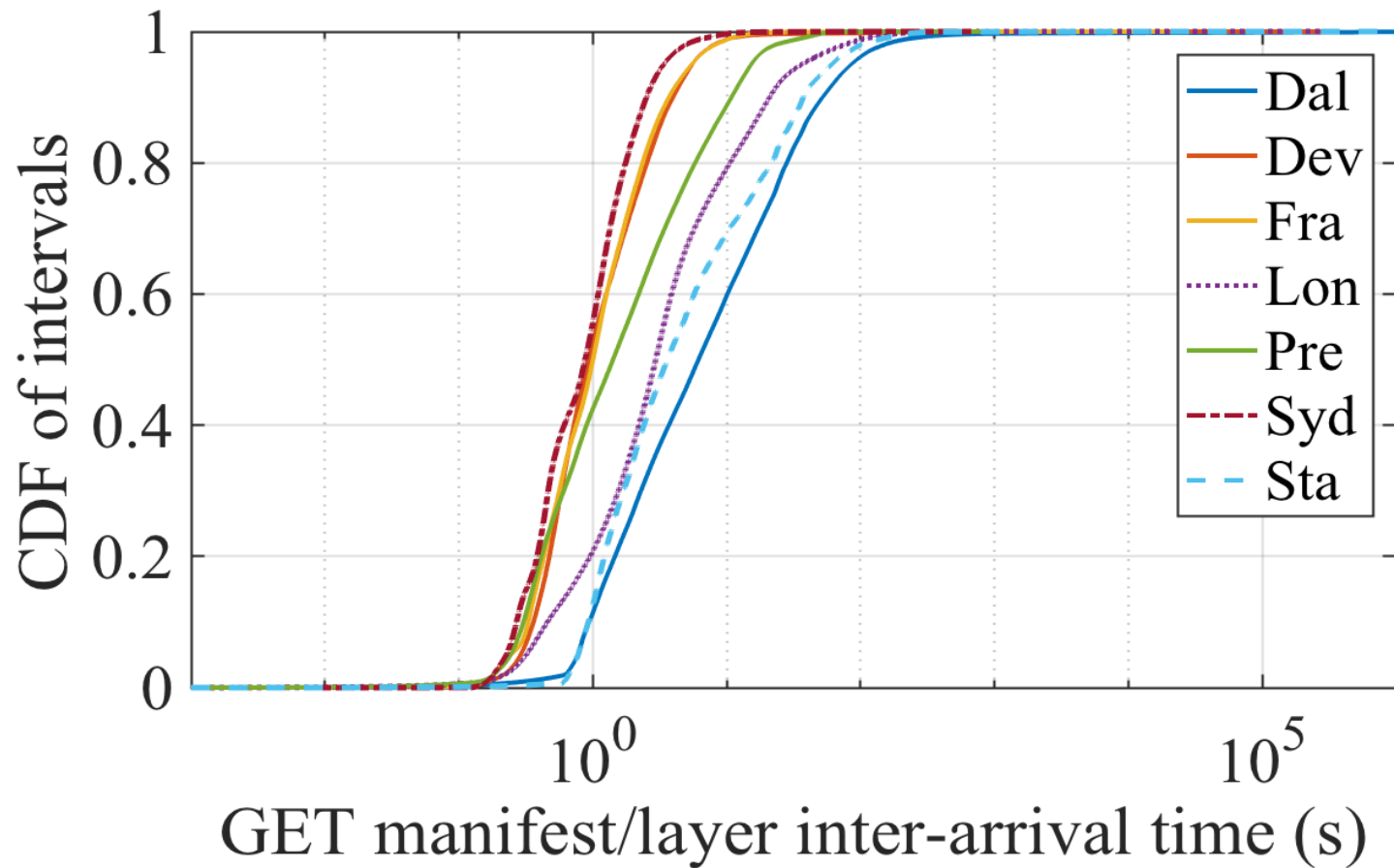


Key observation II-b: User repulling pattern can also be predicted

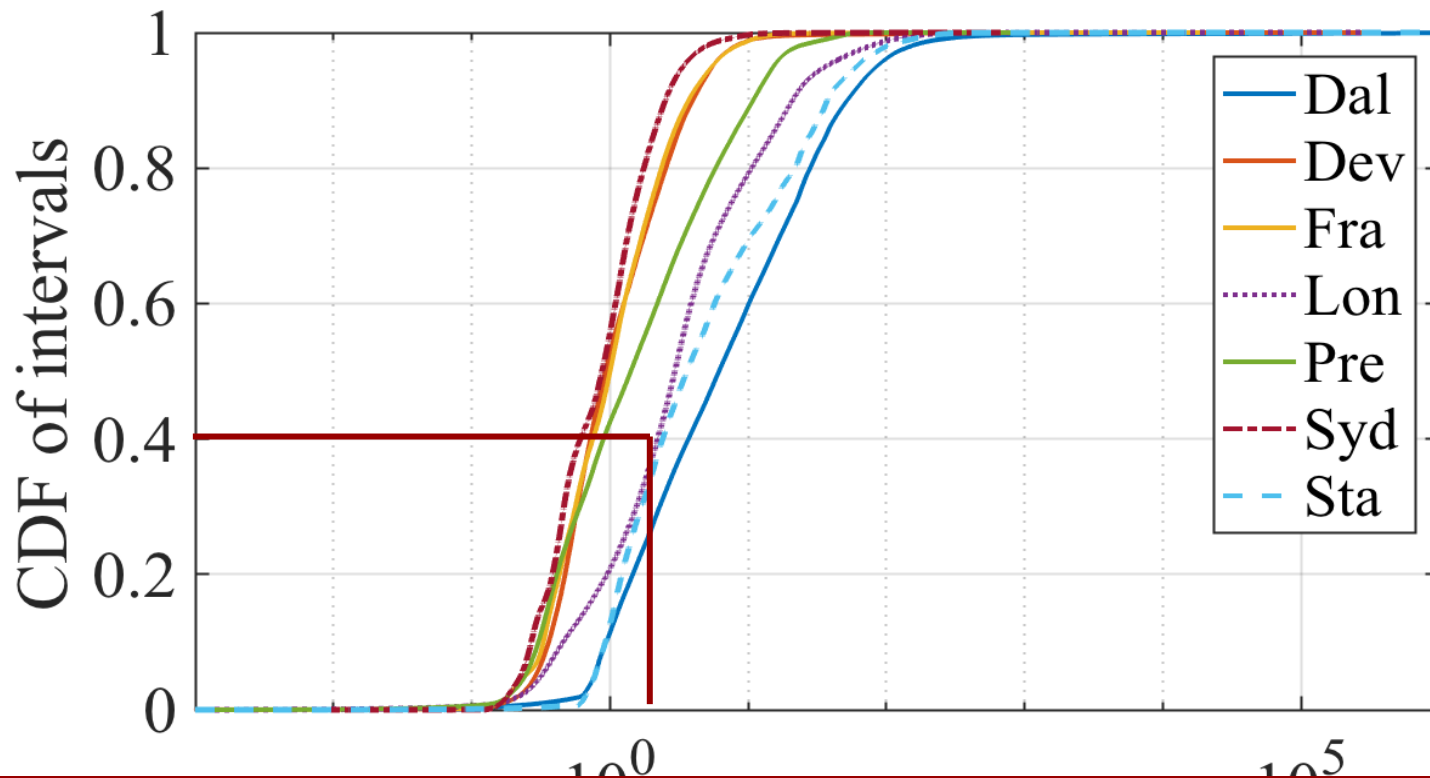


User repulling pattern is either pull-once or always-pull → we can predict which layers to pull.

Key observation II-c: Layer preconstruction is possible

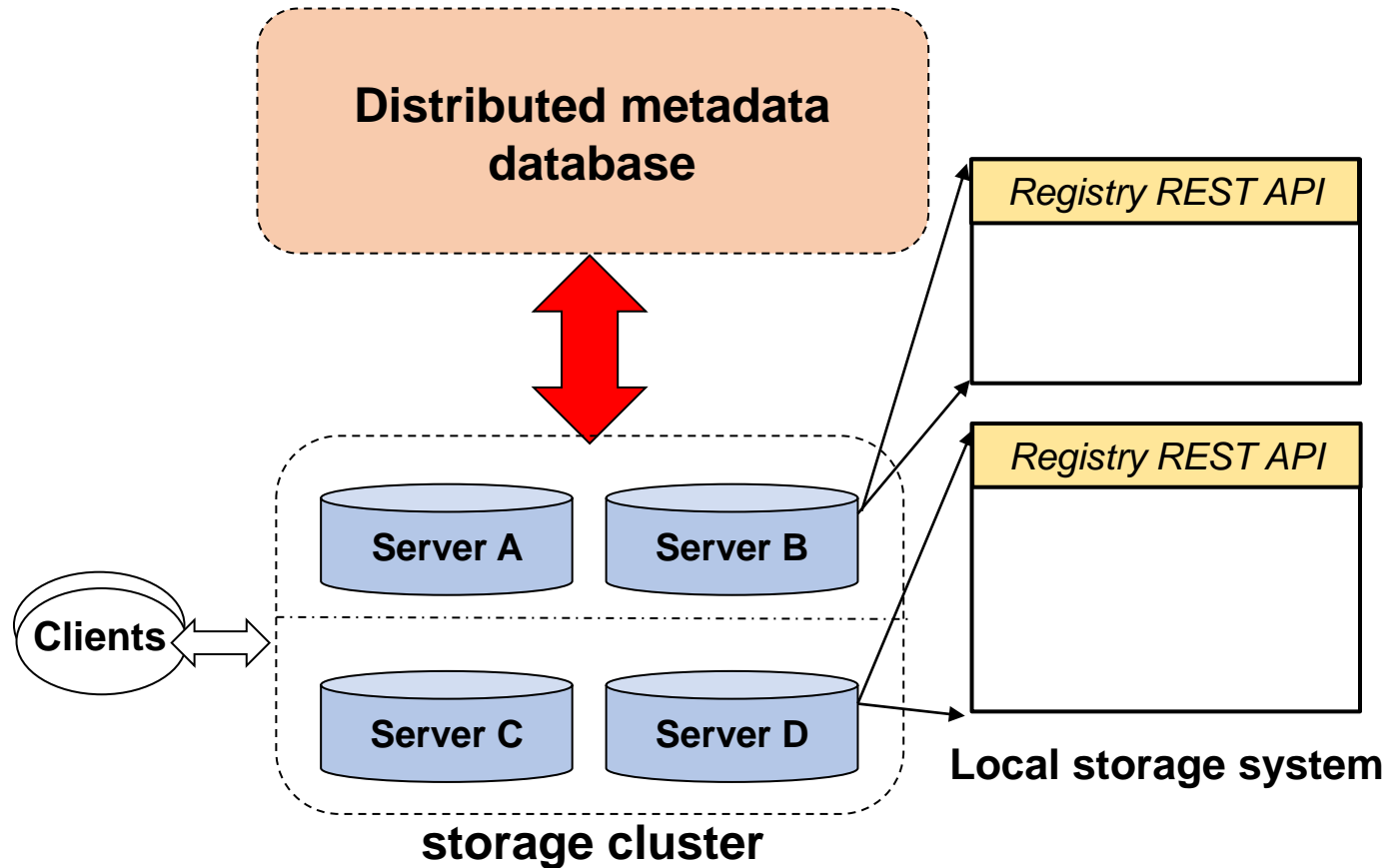


Key observation II-c: Layer preconstruction is possible



Layer preconstruction can significantly reduce layer restore overhead.

DupHunter architecture



Reducing overhead in DupHunter

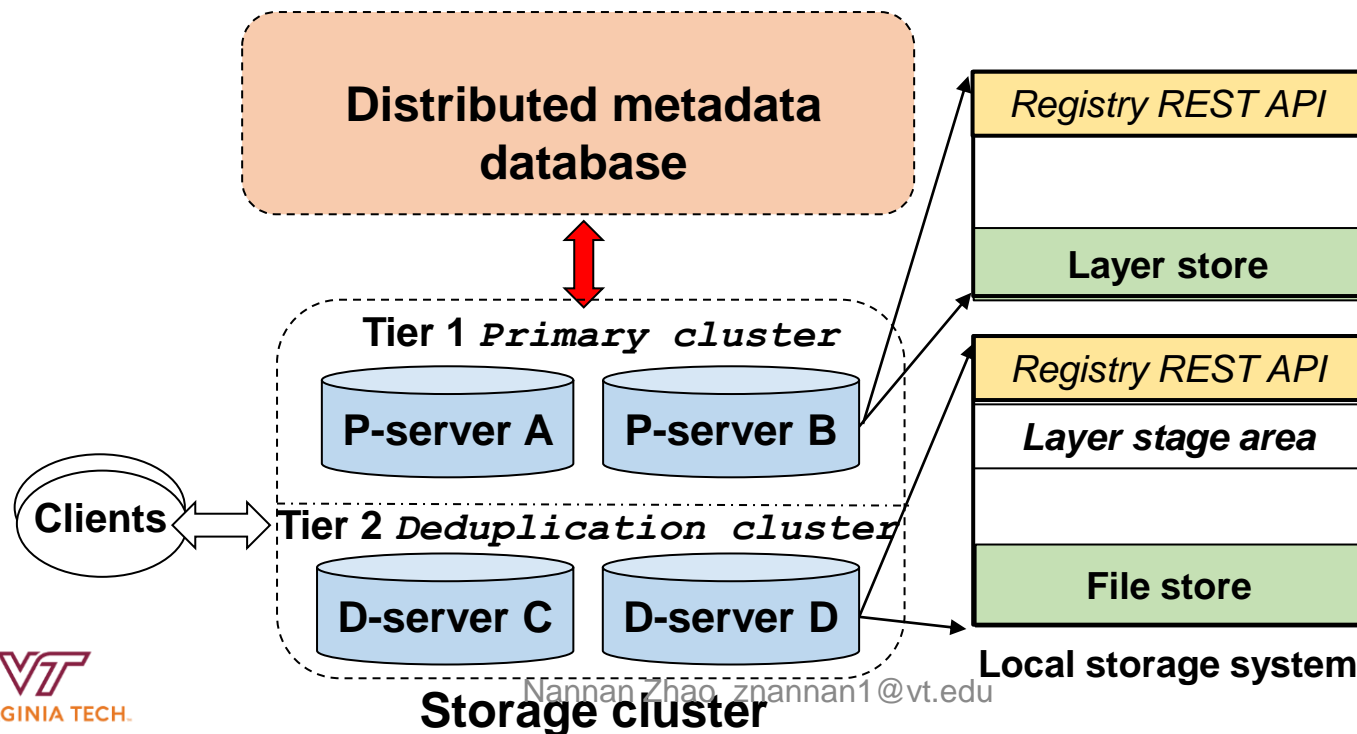
1. Support multiple replica deduplication modes.
2. Facilitate parallel layer reconstruction.
3. Enable proactive layer prefetching/preconstruction.

DupHunter supports multiple replica deduplication modes

- ❑ **B-mode n** : Basic deduplication mode n
 - Keep n layer replicas intact.
 - Deduplicate the remaining $R-n$ layer replicas (R = layer replication level).
- ❑ **S-mode**: Selective deduplication mode
 - The number of intact layer replicas proportional to the layer's popularity.
 - Hot layers have more intact replicas.

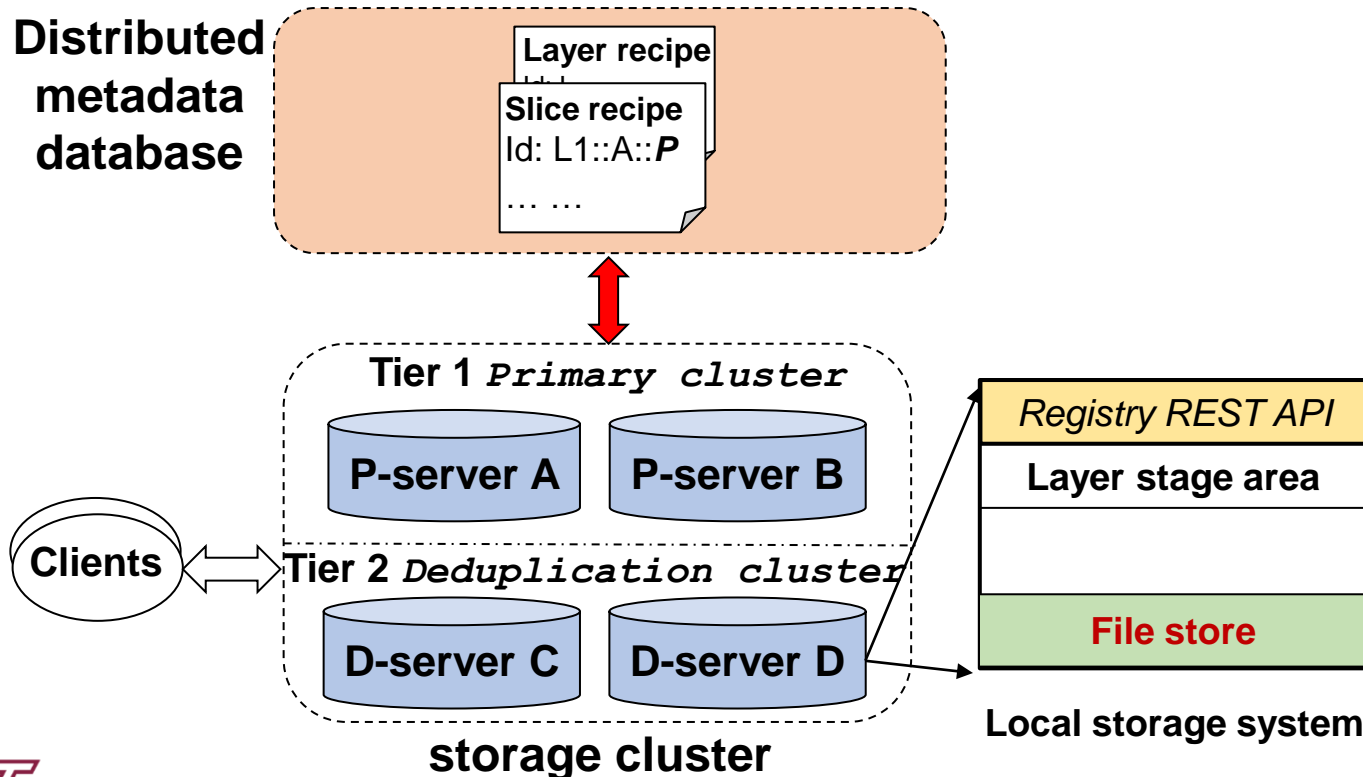
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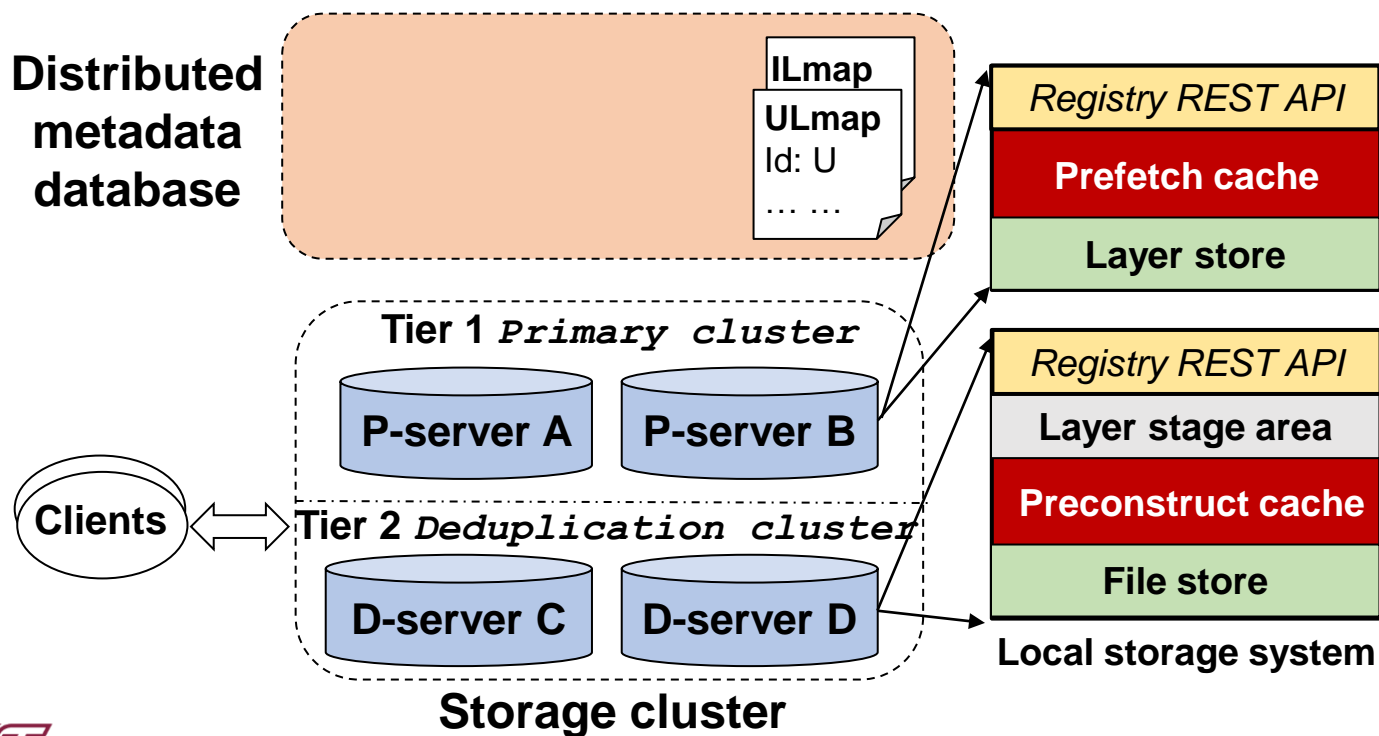
DupHunter facilitates parallel layer reconstruction

- ❑ **Slice:** Set of all the files on a server belonging to a layer.
 - Distributed evenly across the cluster.
 - Speed up layer reconstruction via parallel processing of slices.

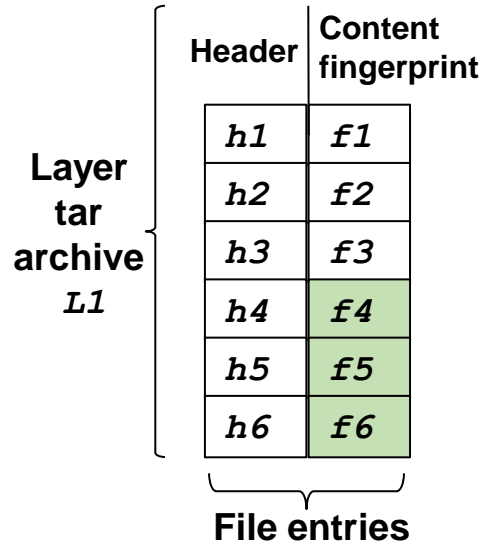


DupHunter enables prefetching/preconstruction of layers

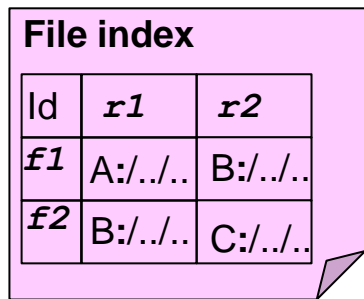
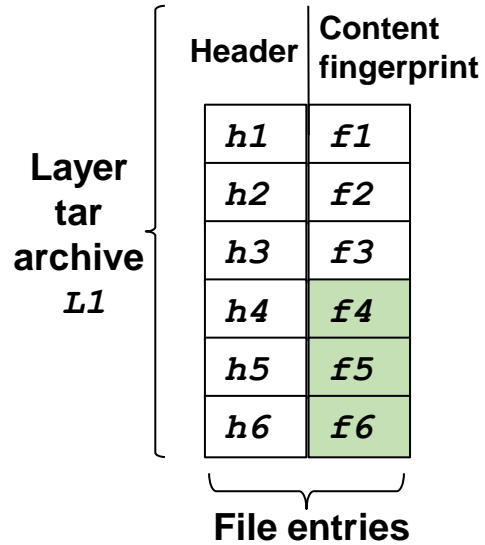
- ❑ **Prefetch cache** to prefetch layers and hide disk I/Os.
- ❑ **Preconstruct cache** to store preconstruct layers and hide layer restore overhead.



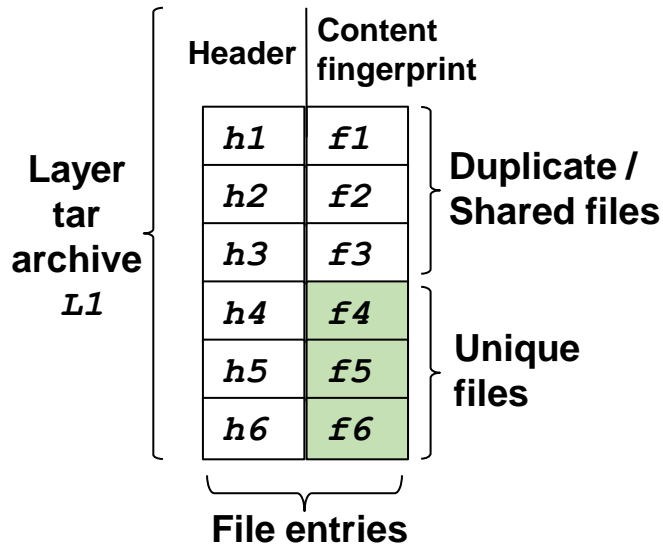
Deduplicating layers



Deduplicating layers

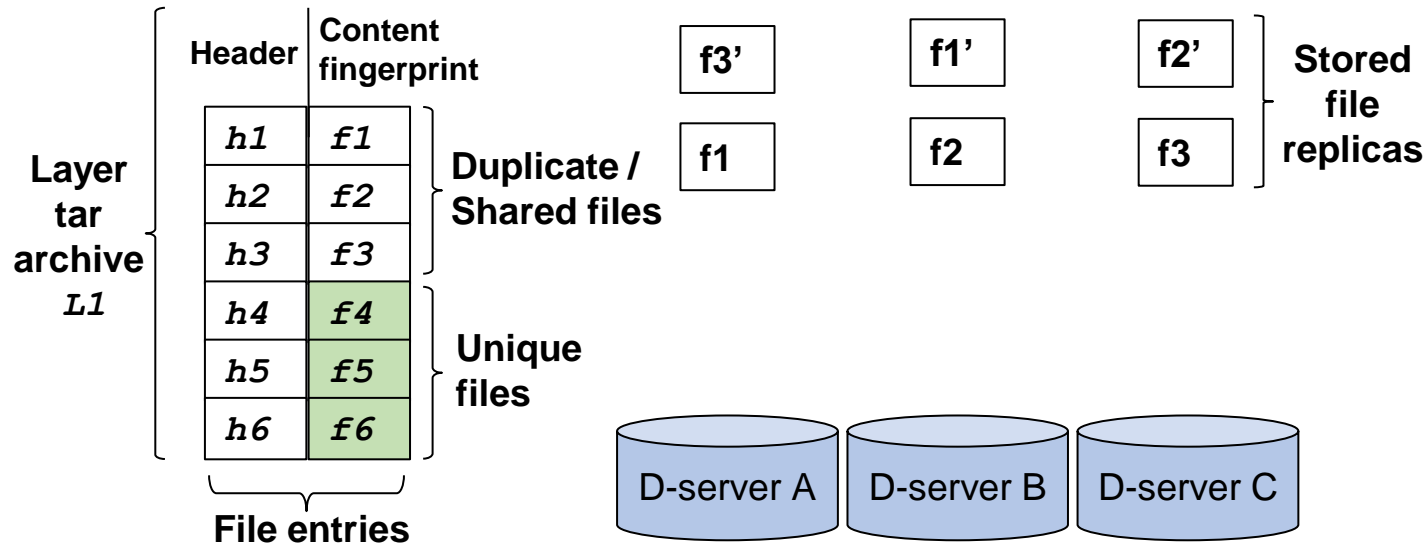


Deduplicating layers



File index		
Id	r1	r2
<i>f1</i>	A:/.../	B:/.../
<i>f2</i>	B:/.../	C:/.../

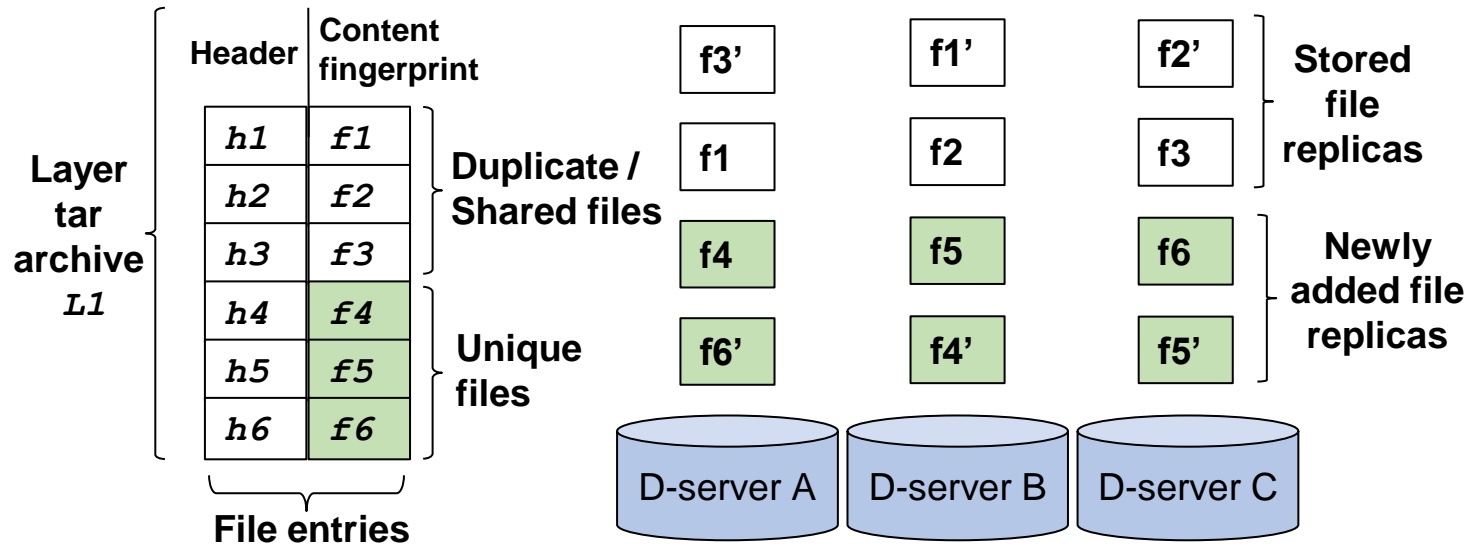
Deduplicating layers



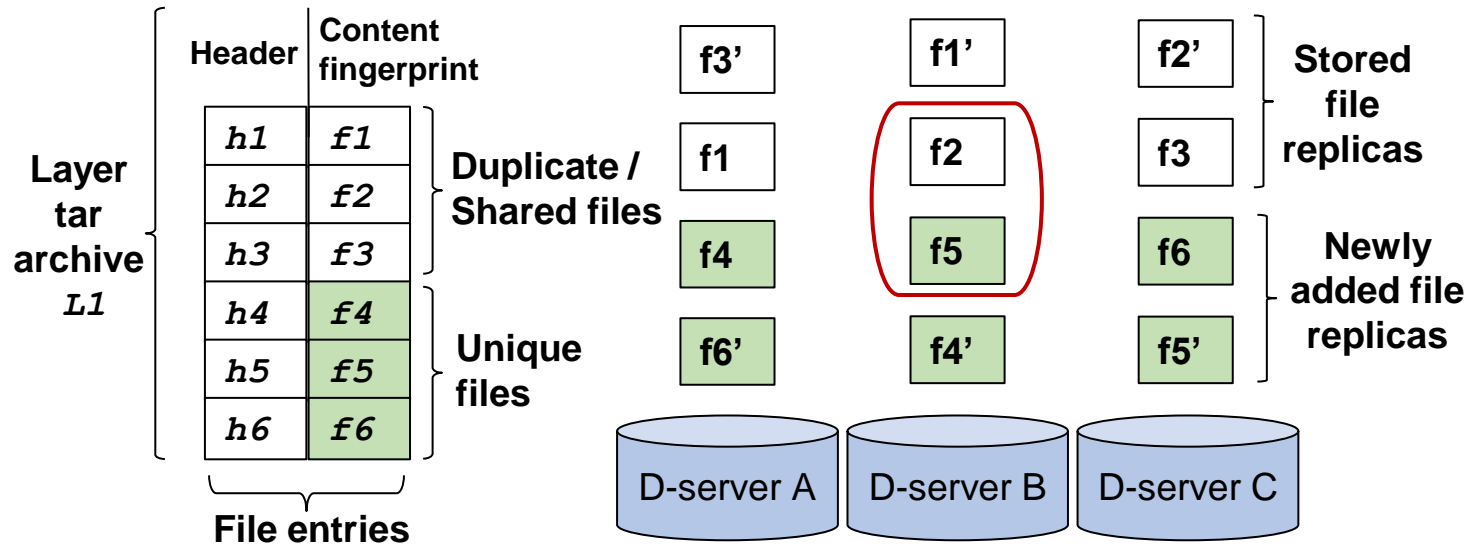
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Deduplicating layers



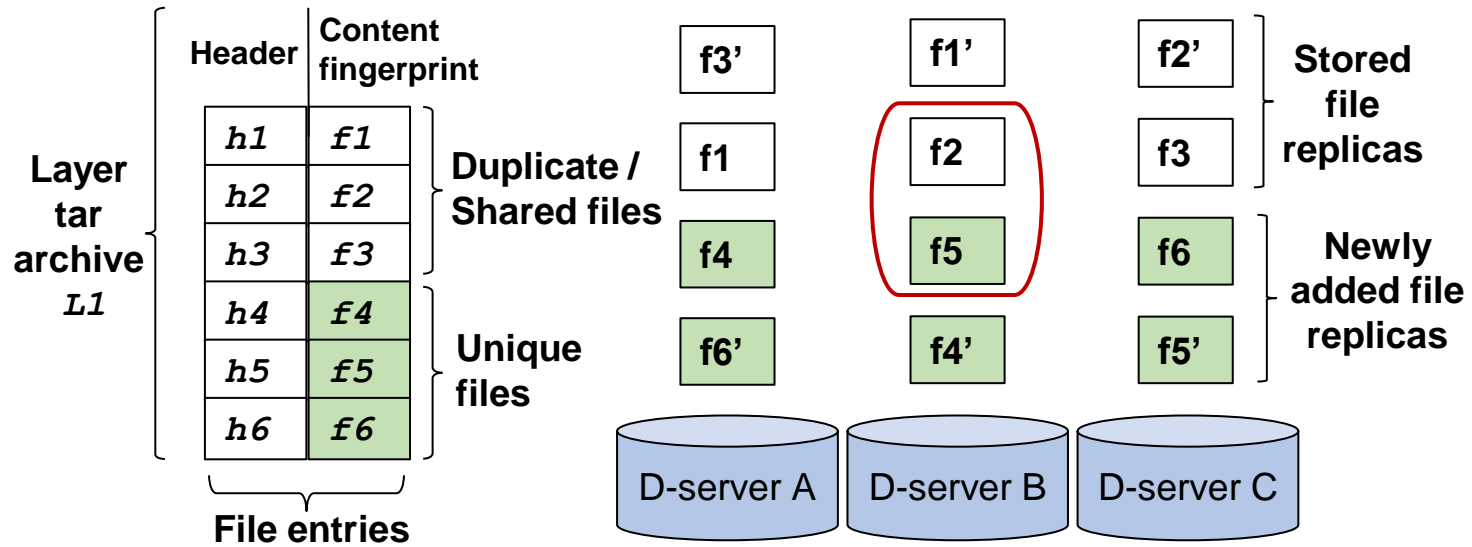
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Deduplicating layers



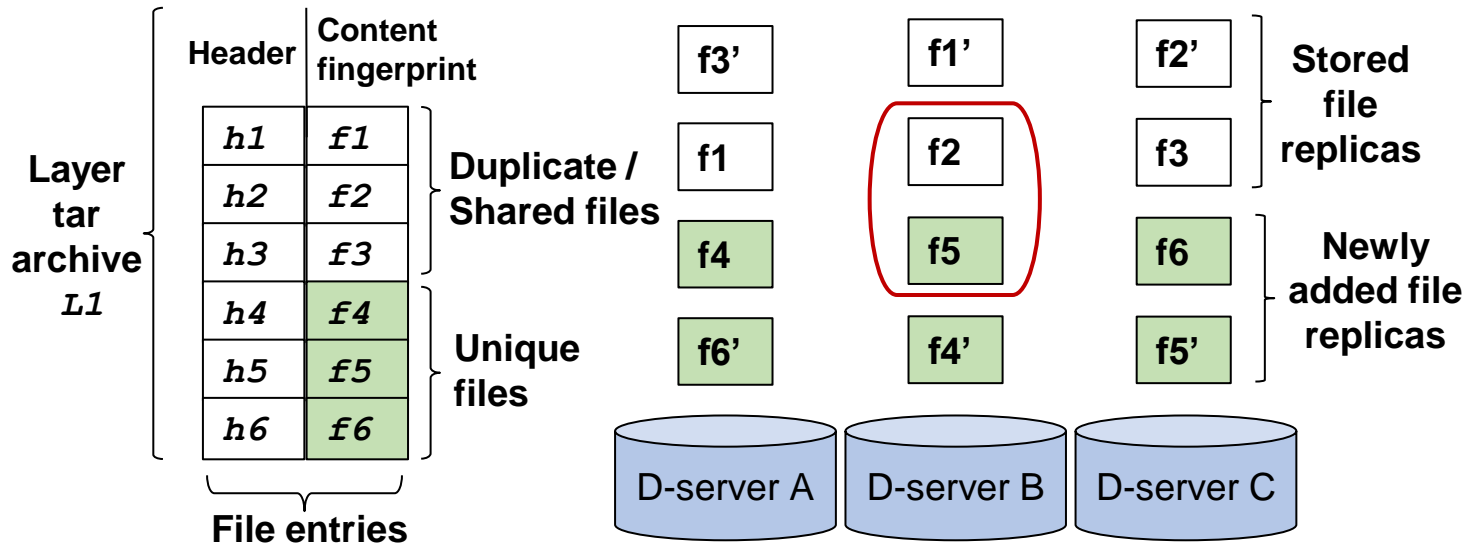
File index

Id	$r1$	$r2$
$f1$	A:/.../	B:/.../
$f2$	B:/.../	C:/.../

Slice recipe
Id: $L1::A::P$

Header	Content pointer
$h2$	$f2$
$h5$	$f5$

Deduplicating layers



File index

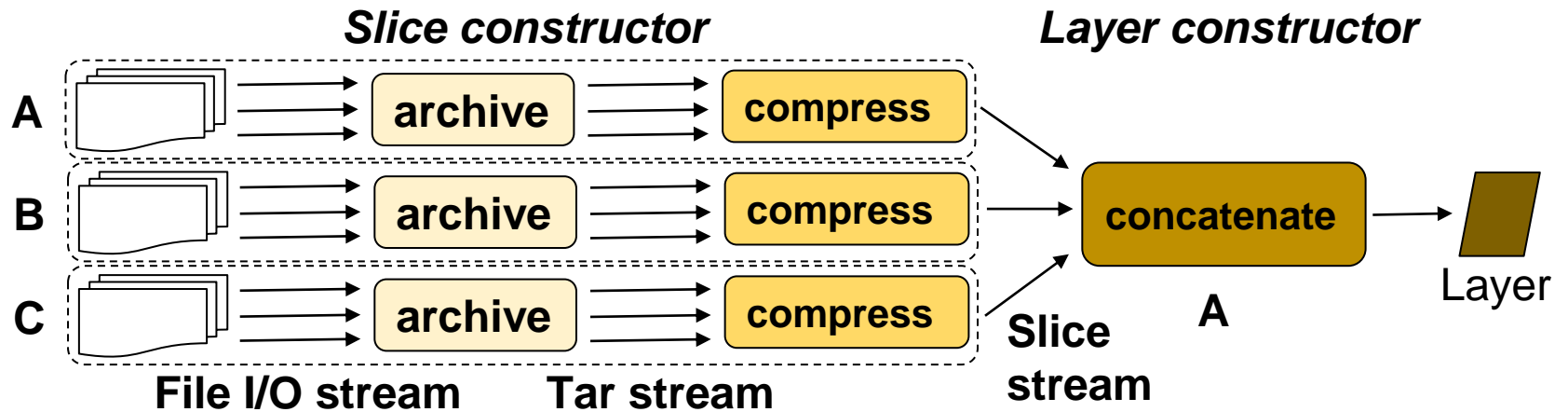
Id	$r1$	$r2$
$f1$	A:/.../	B:/.../
$f2$	B:/.../	C:/.../

Layer recipe
 Id: $L1$
 Master: A
 Workers: [A, B, C]

Slice recipe
 Id: $L1::A::P$

Header	Content pointer
$h2$	$f2$
$h5$	$f5$

Restoring layers



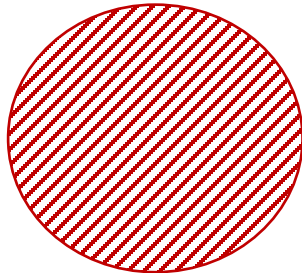
Caching and preconstructing layers

- ❑ Imap: Maps image to its containing layer set.
- ❑ Umap: Maps user to the layers that the user has accessed and the corresponding pull count.

Caching and preconstructing layers

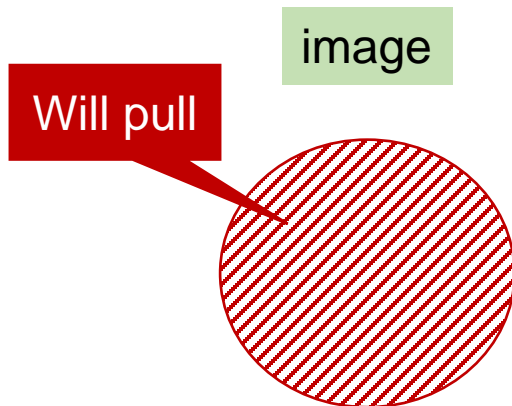
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image



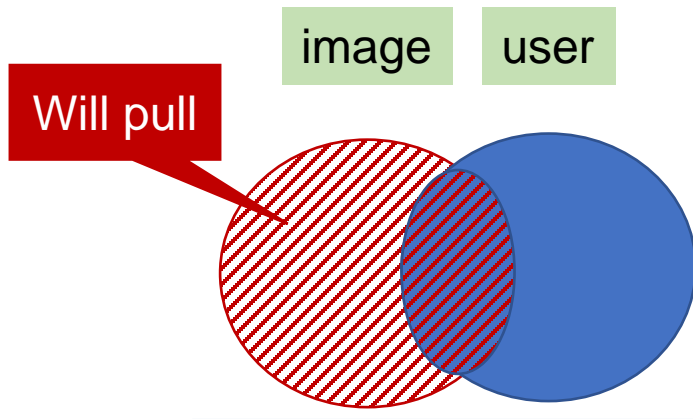
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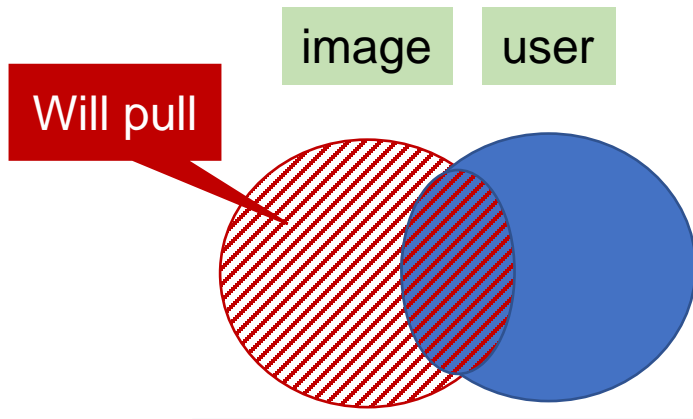
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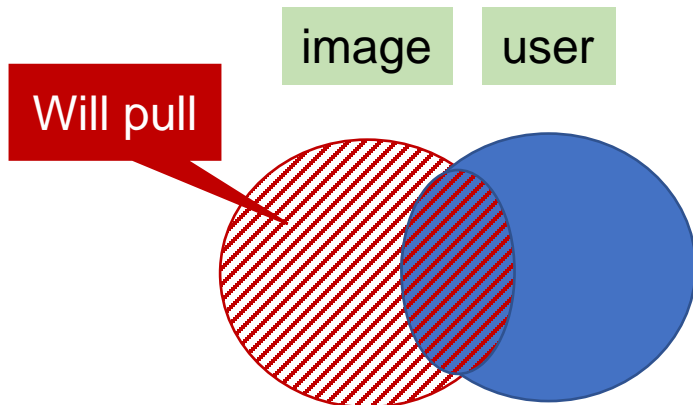
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Caching and preconstructing layers

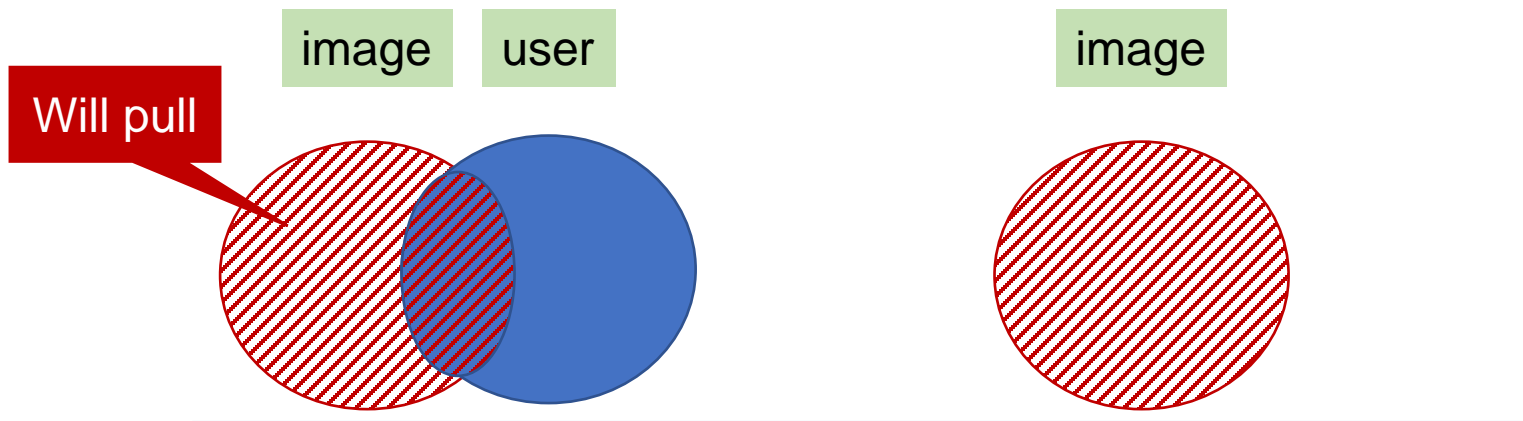
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$$S_{\Delta} = Imap[r.img] - Umap[r.addr]$$

Caching and preconstructing layers

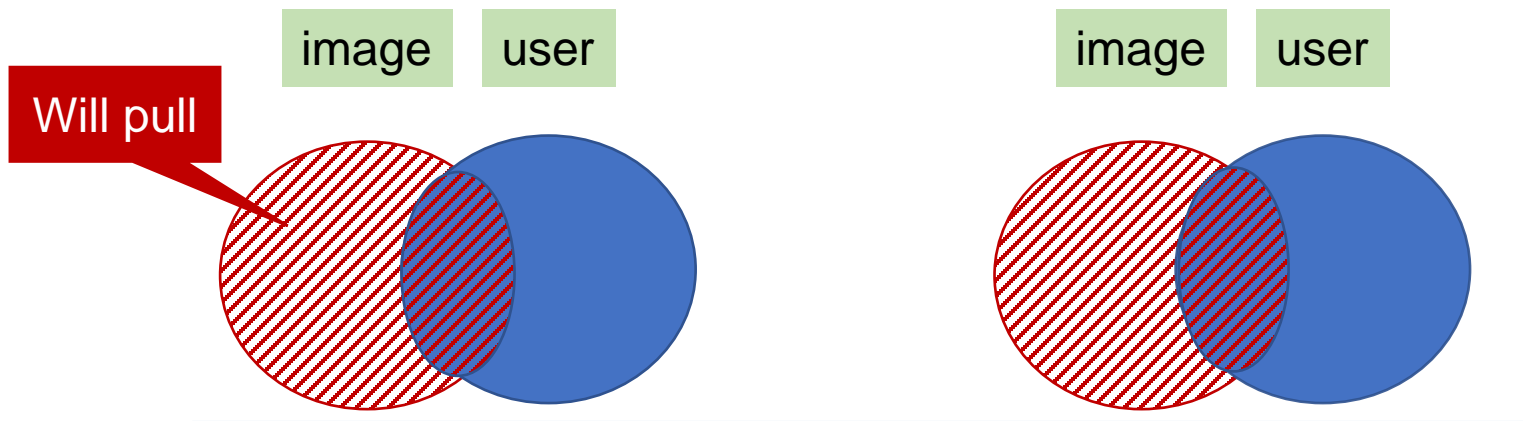
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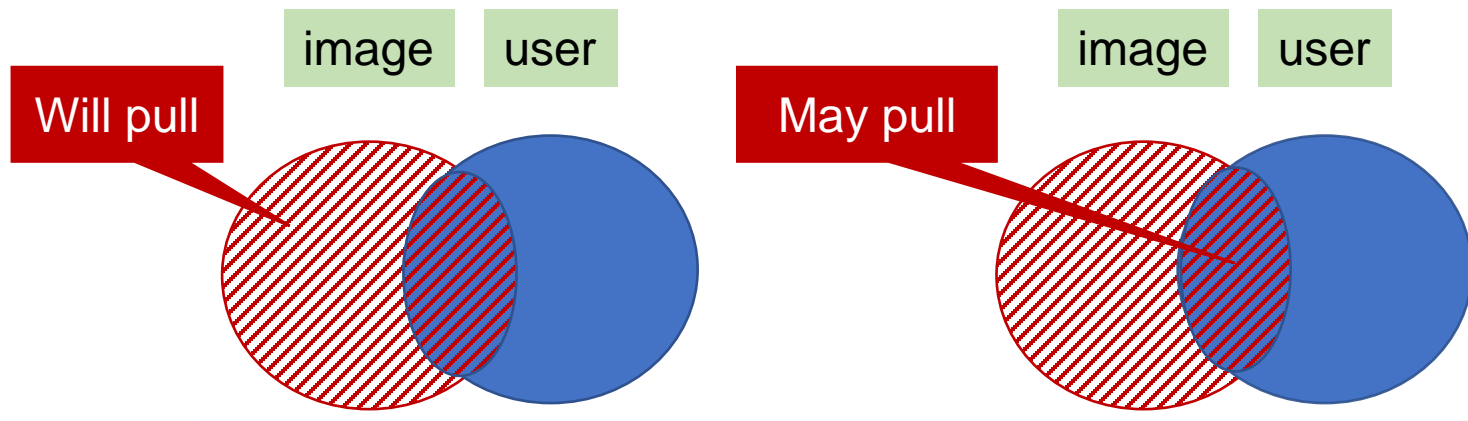
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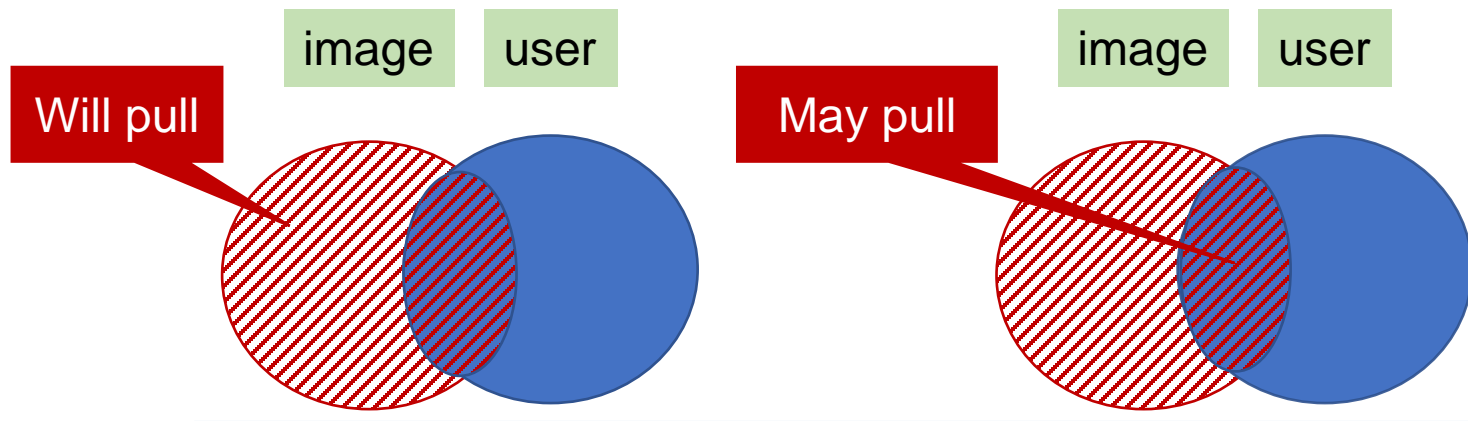
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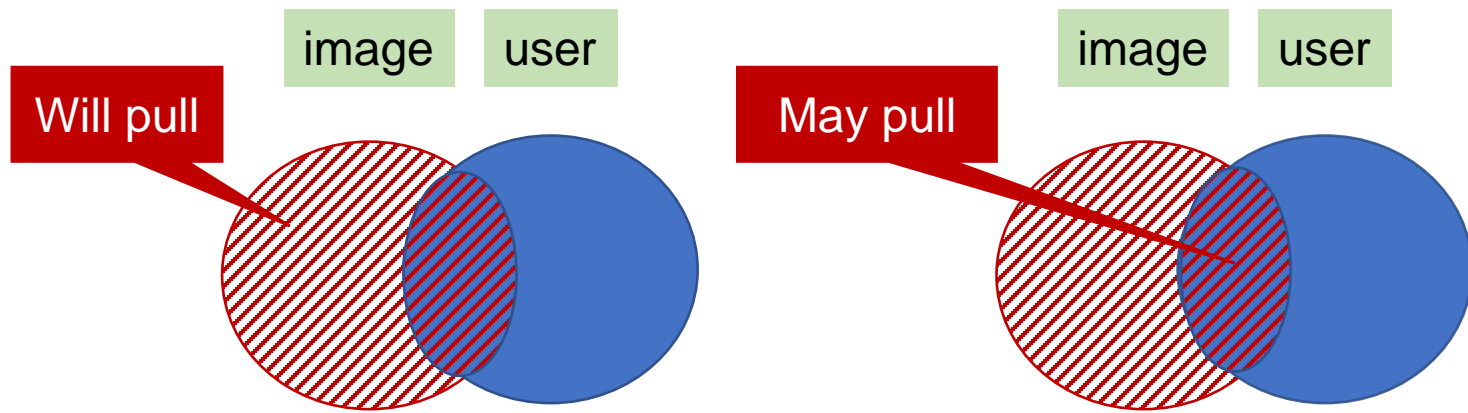
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Caching and preconstructing layers

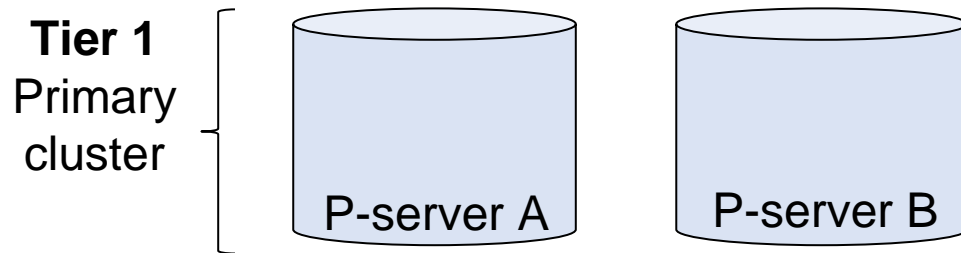
- Imap: Maps image to its containing layer set.
- Umap: Maps user to the layers that the user has accessed and the corresponding pull count.



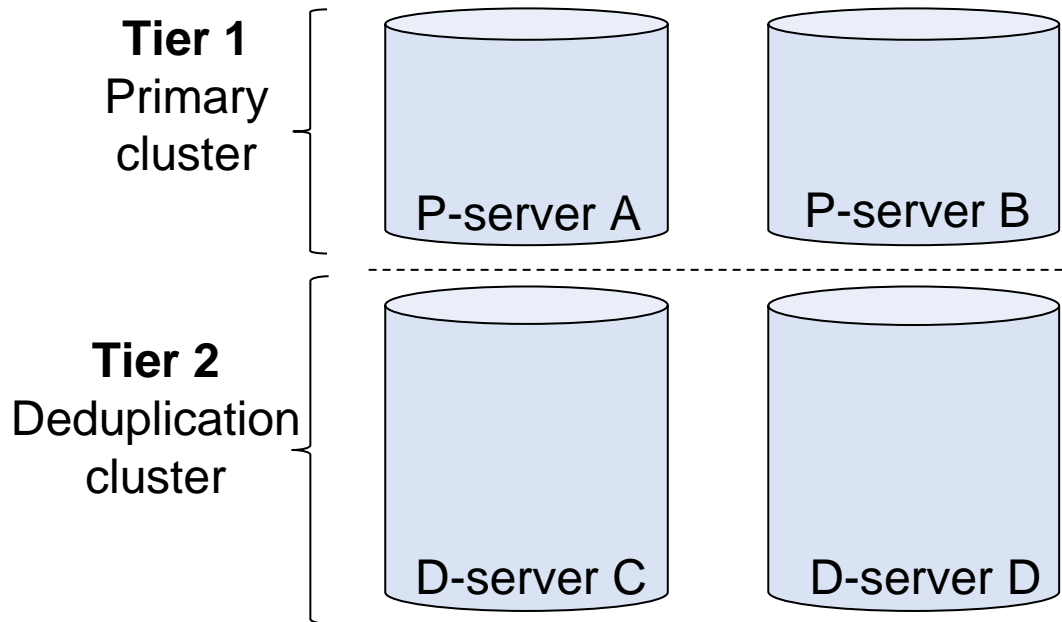
$$S_{\Delta} = Imap[r.img] - Umap[r.addr]$$

$$S_{\cap} = Imap[r.img] \cap Umap[r.addr]$$

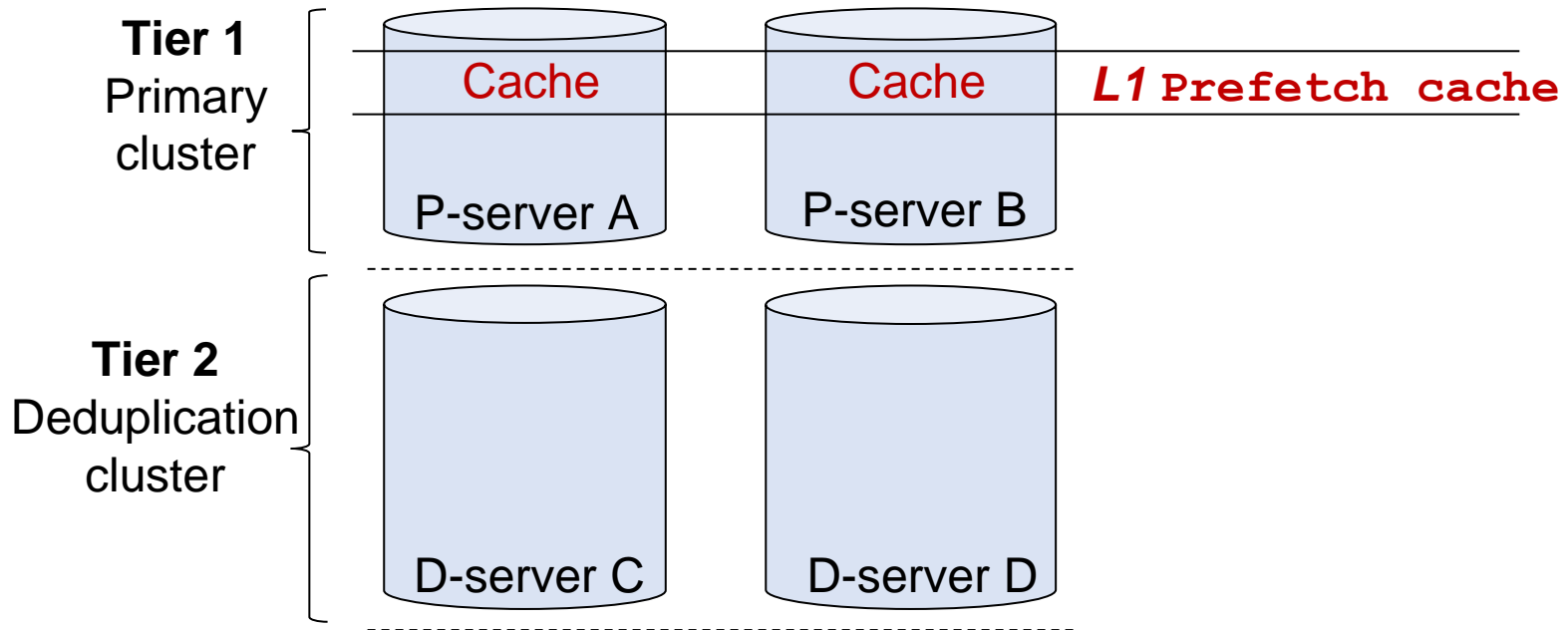
Cache handling in tiered storage



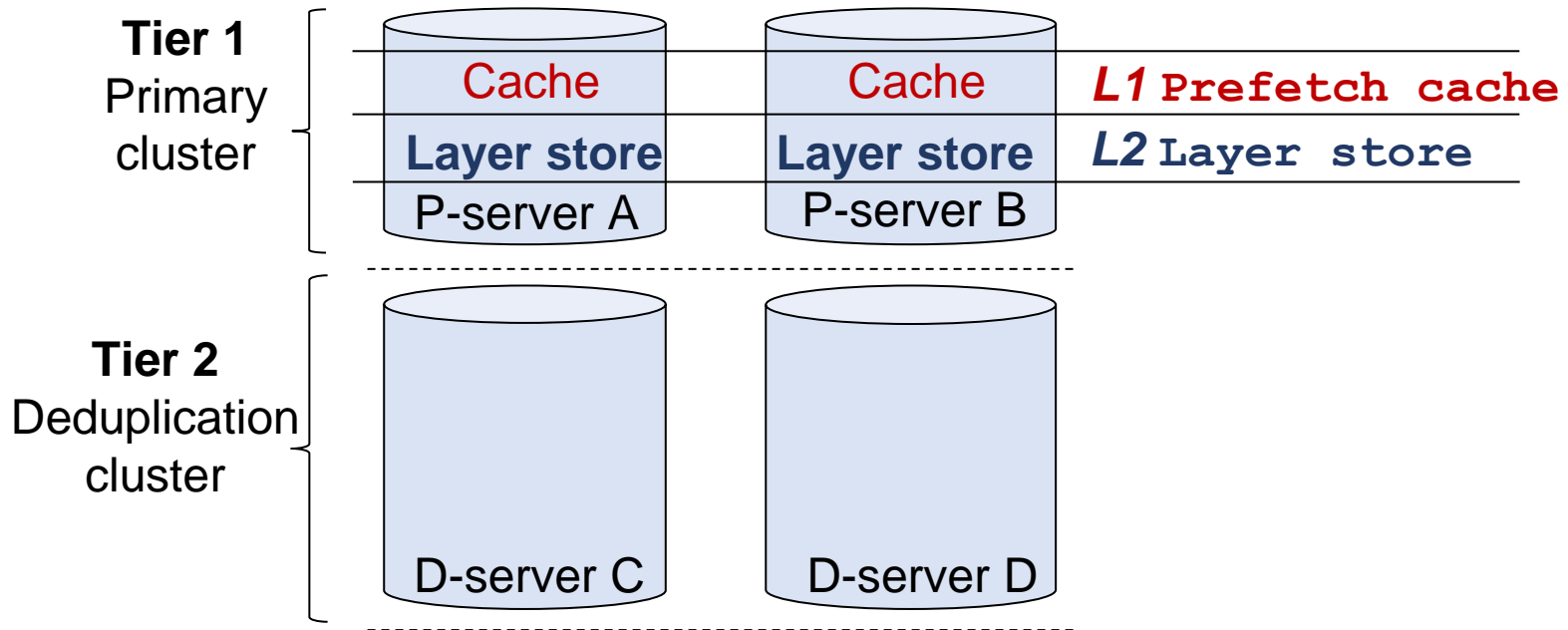
Cache handling in tiered storage



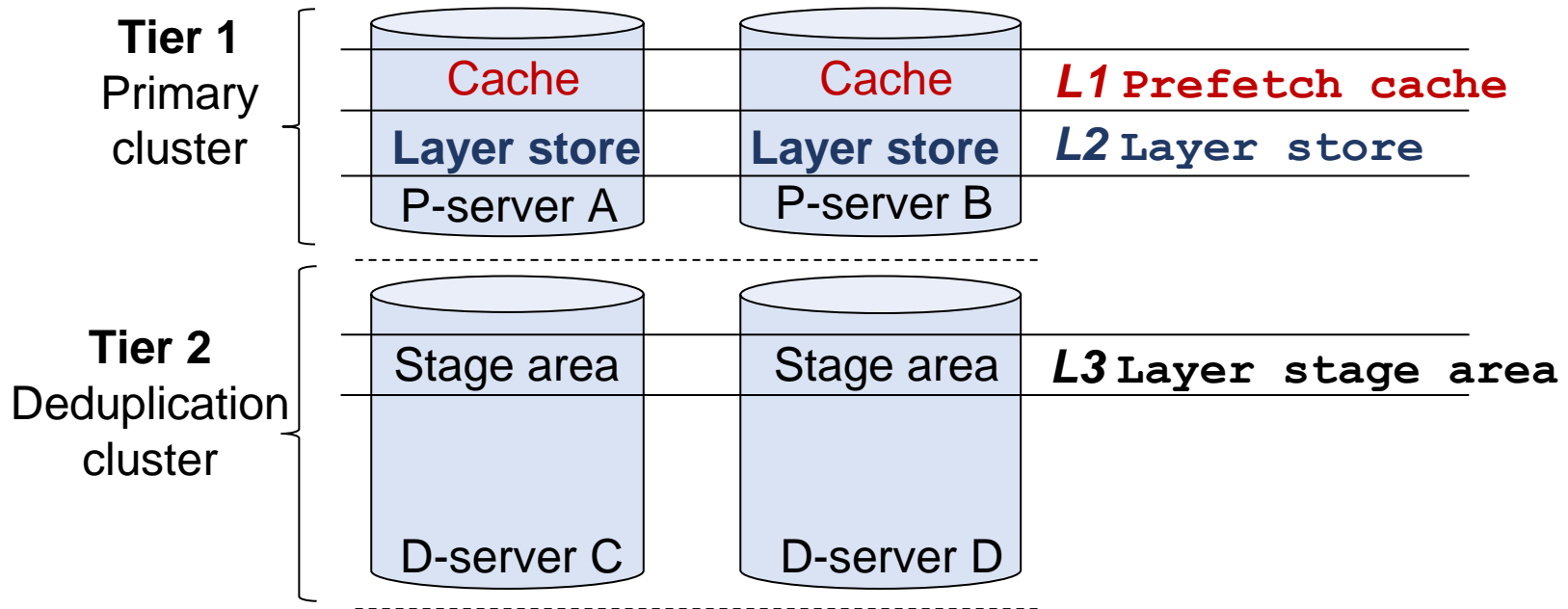
Cache handling in tiered storage



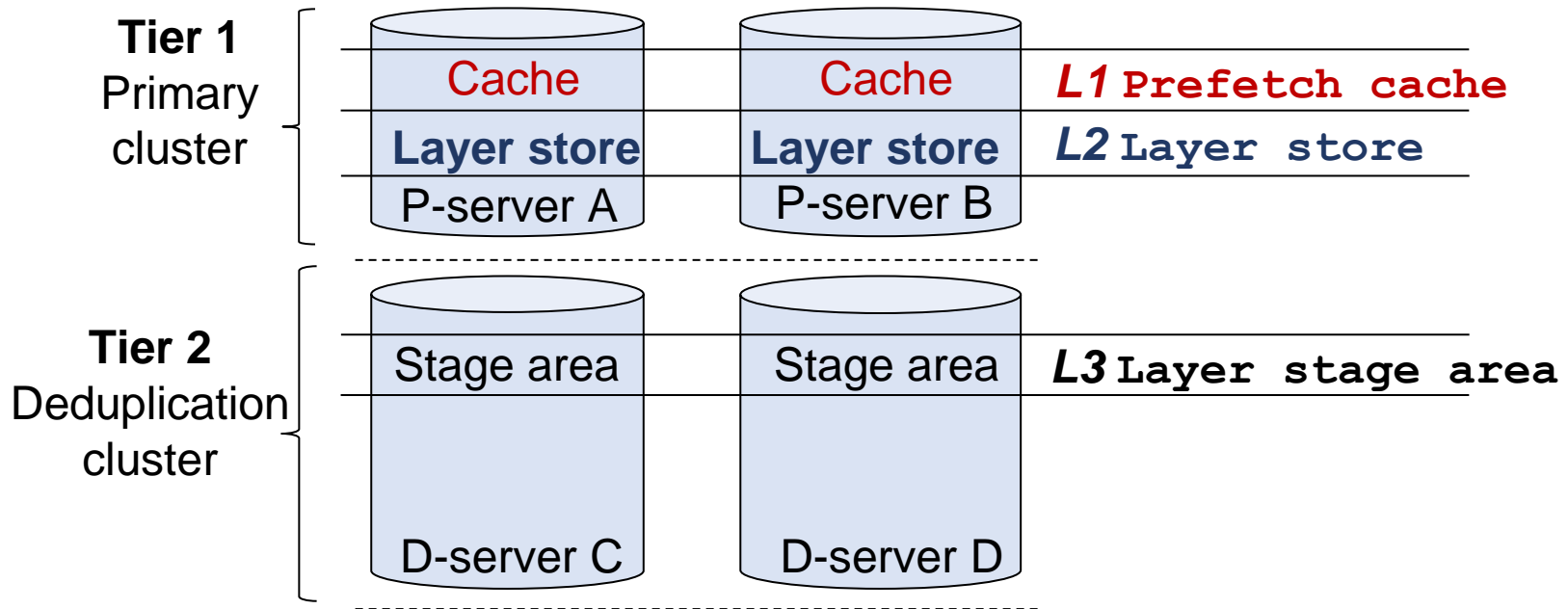
Cache handling in tiered storage



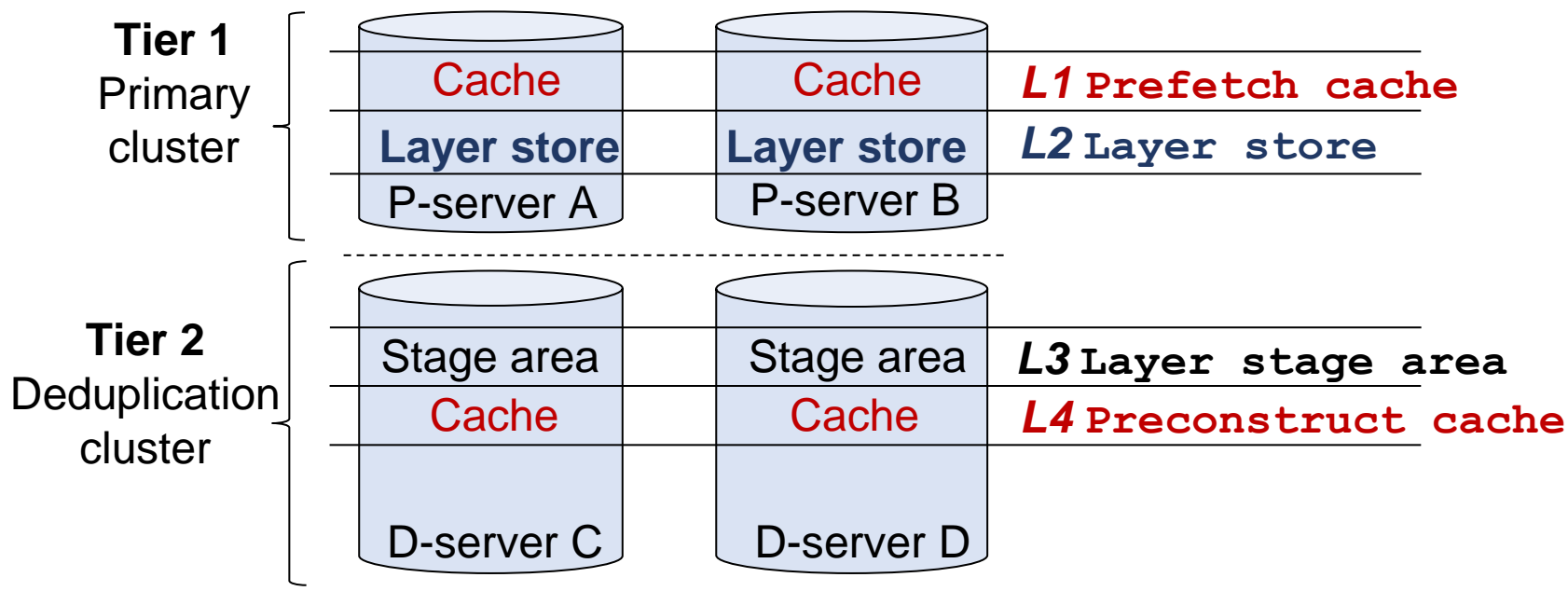
Cache handling in tiered storage



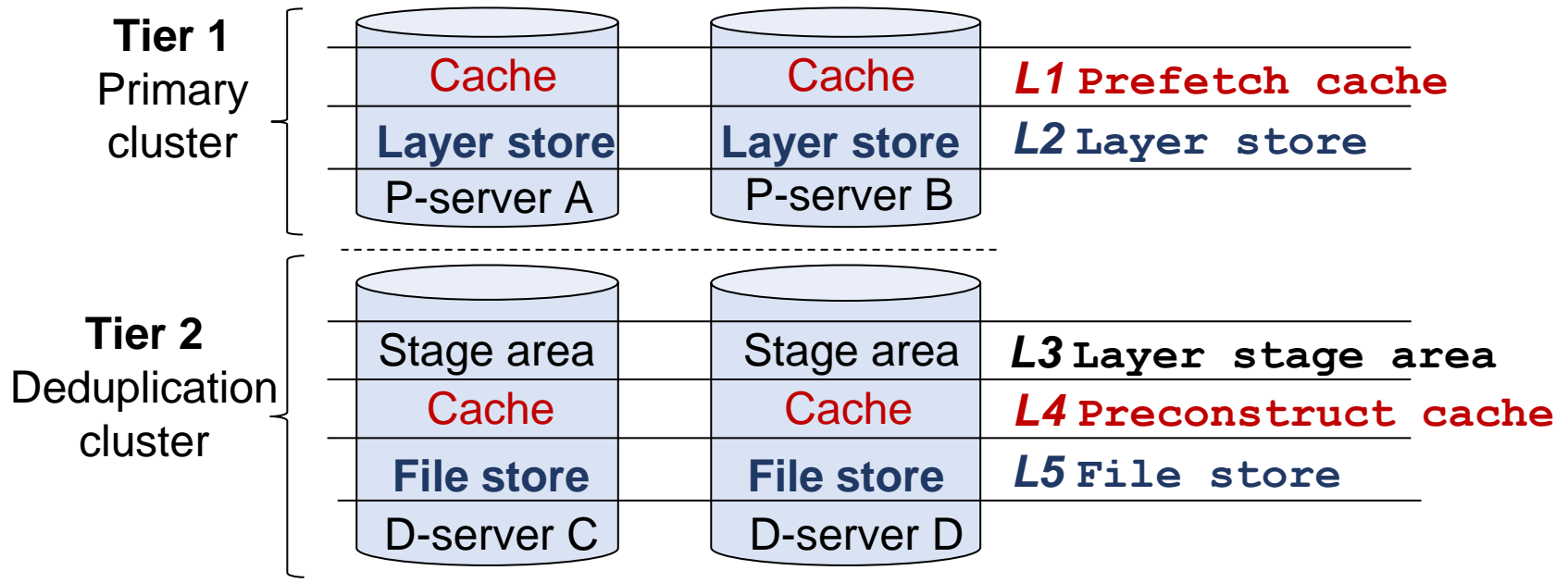
Cache handling in tiered storage



Cache handling in tiered storage



Cache handling in tiered storage



Evaluation

❑ Workloads used:

- Traces from IBM registries: Dal, Fra, Lon, and Syd availability zones
- Dataset from Docker Hub

❑ Schemes studied:

- **Baseline**: No deduplication
- **B-mode n** : n (1-3) replicas are preserved; $3 - n$ deduplicated
- **S-mode**: intact layer replicas proportional to the layer's popularity
- **B-mode 0**: deduplicate all layer replicas, under a given replication policy
 - **GF-R**: global file-level deduplication
 - **GF+LB-R**: global file-level deduplication and local block-level deduplication
 - **GB-EC**: global block-level deduplication under erasure coding

Deduplication ratio vs. performance

Mode	Dedup. ratio	Performance improvement (P-servers)
B-mode 1	1.5	1.6×
S-mode	1.3	2×
B-mode 2	1.2	2.6×
B-mode 3	1	2.8×

B-mode 0	Dedup ratio	Performance degradation (D-servers)
	GF-R (Global file-level [3 replicas])	
	2.1	-1.03 ×
	GF+LB-R (Global file- and local block-level [3 replicas])	
	3.0	-2.87 ×
	GB-EC (Global block-level [Erasure coding])	
6.9	-6.37 ×	

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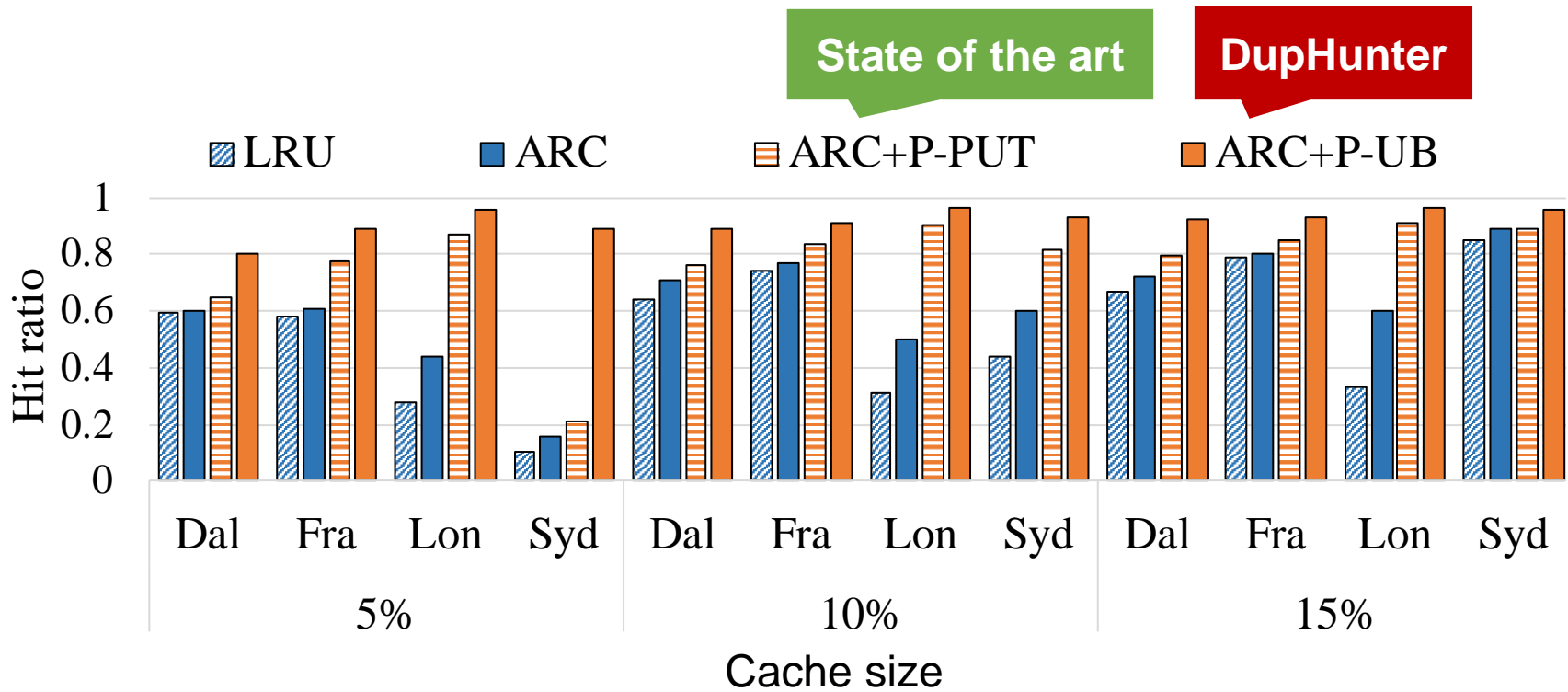
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Deduplication ratio vs. performance

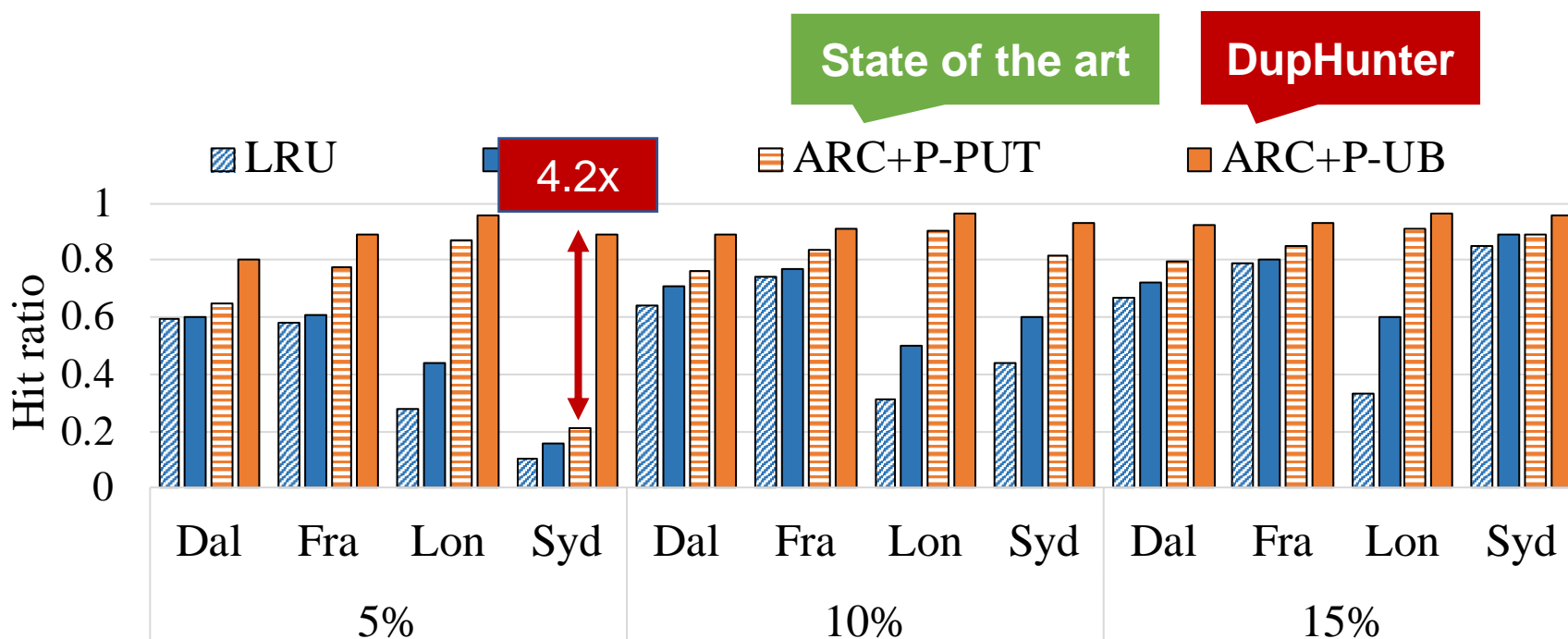
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Prefetch cache hit ratio

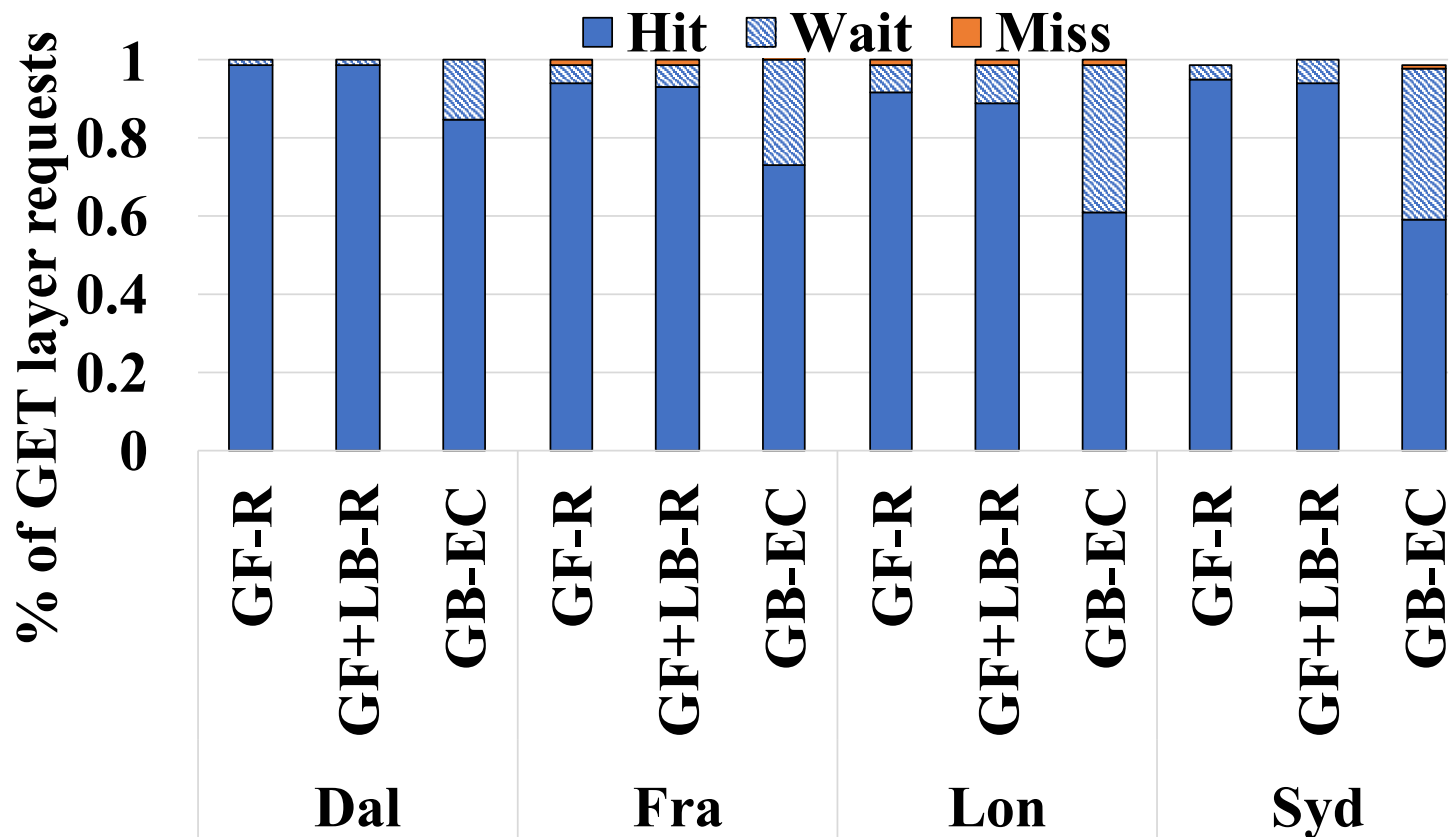


Prefetch cache hit ratio

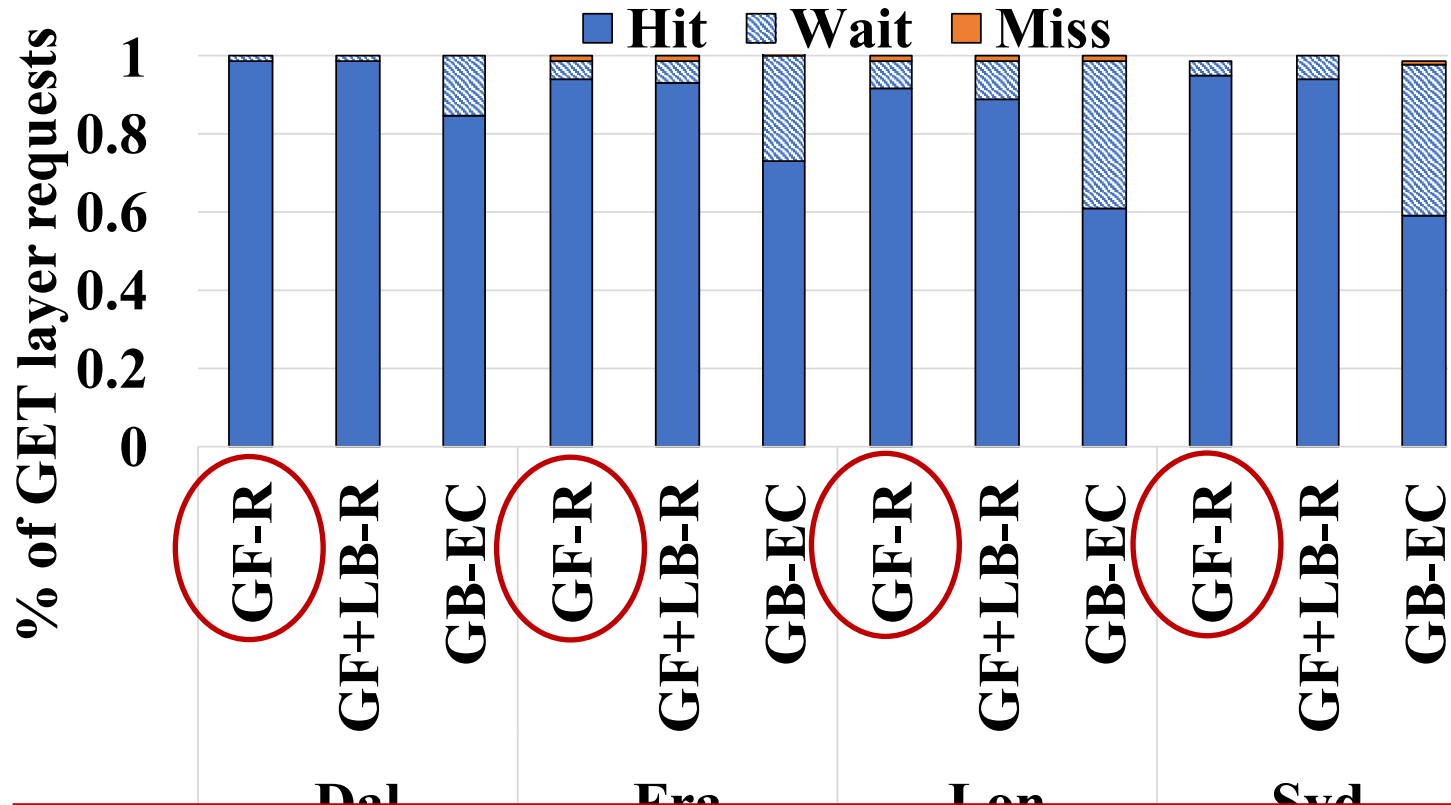


Duphunter can provide high hit ratio while reducing tail latency.

Preconstruct cache hit ratio



Preconstruct cache hit ratio

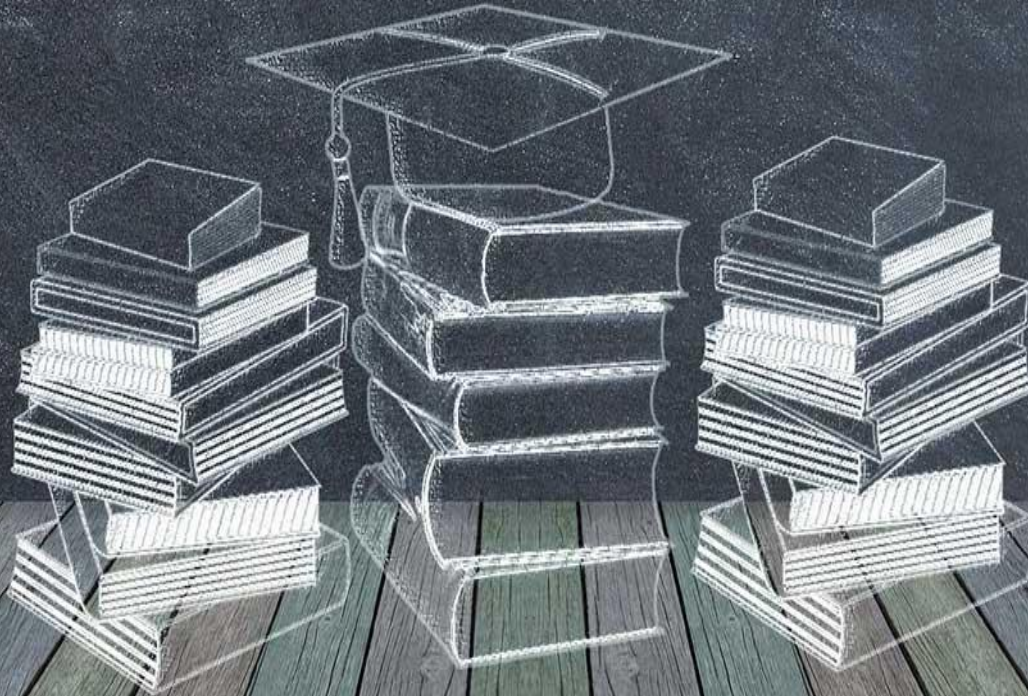


Global file level dedeuplication also has the lowest wait and miss ratios.

Summary

- ❑ DupHunter exploits the redundancy in container images along with predictable user access patterns to achieve high space savings with low layer restore overhead.
 - *It supports multiple replica deduplication modes.*
 - *It facilitates parallel layer reconstruction.*
 - *It offers proactive layer prefetching/preconstruction.*
- ❑ DupHunter reduces storage space needs by up to **6.9x** and can reduce the GET layer latency up to **2.8x** compared to the state of the art.
- ❑ DupHunter is available at <https://github.com/nnzhaocs/DupHunter>.

THANK YOU



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