



UNIVERSITY OF  
TORONTO



# User-Guided Device Driver Synthesis

**Leonid Ryzhyk**   Adam Walker   John Keys

Alexander Legg   Arun Raghunath   Michael Stumm

Mona Vij

# The joys of driver development

- Drivers are hard to write
- ... and even harder to debug
- They often delay product delivery
- ... and are the most common source of OS failures



# The joys of driver development

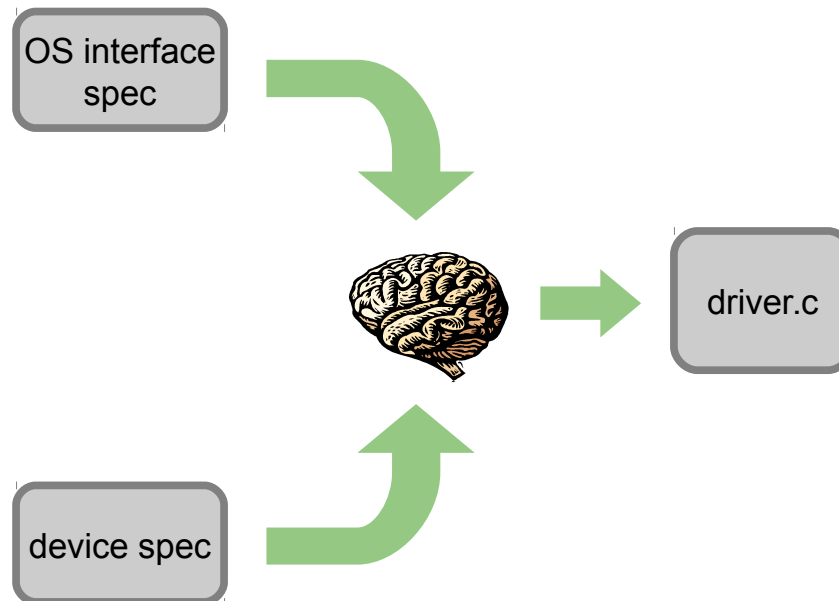
- Drivers are hard to write
- ... and even harder to debug
- They often delay product delivery
- ... and are the most common source of OS failures



Funded by a research grant from Intel

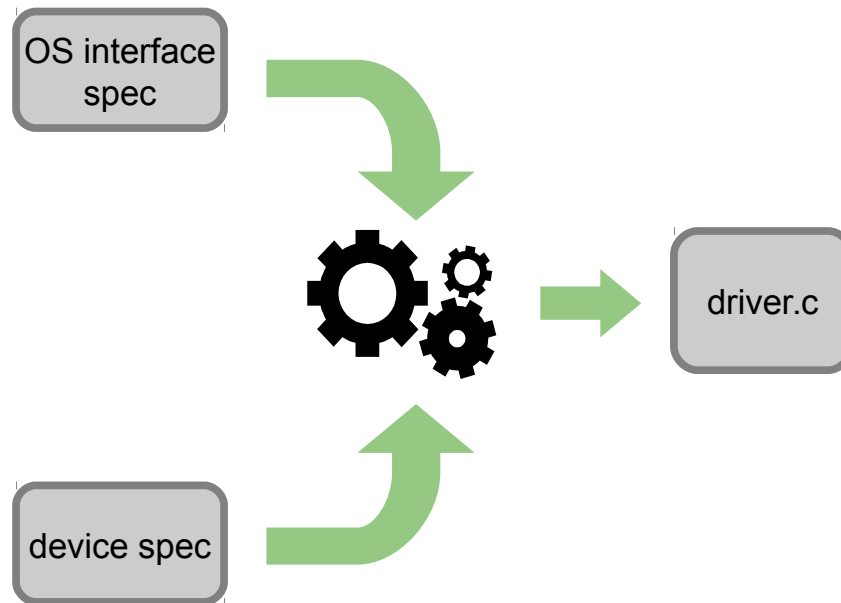
# Observation

- Driver development is a mechanical task
- Can in principle be automated



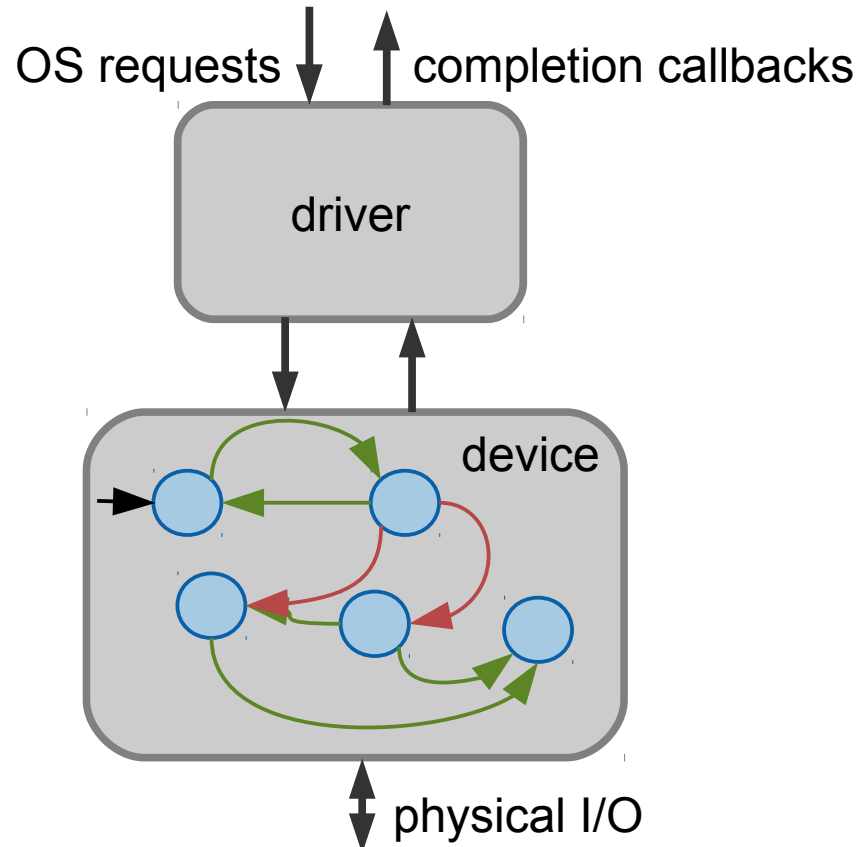
# Observation

- Driver development is a mechanical task
- Can in principle be automated



# Driver Synthesis as a Game

- Driver synthesis can be formalised as a two-player game: *driver* vs (*device* + *OS*)



# Motivation

# Motivation

Addresses an important problem





# Motivation

Addresses an important problem



A simple, neat idea



# Motivation

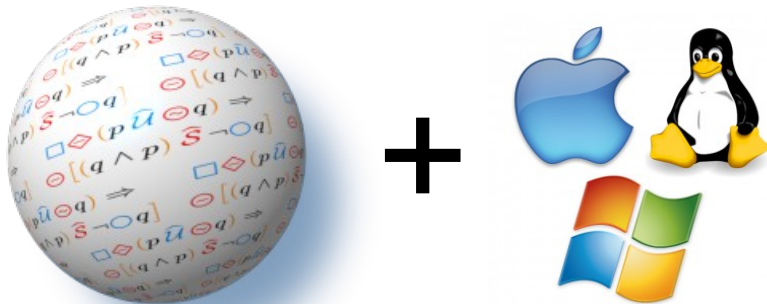
Addresses an important problem



A simple, neat idea



One of few applications of FM to OS (beyond verification)



# Motivation

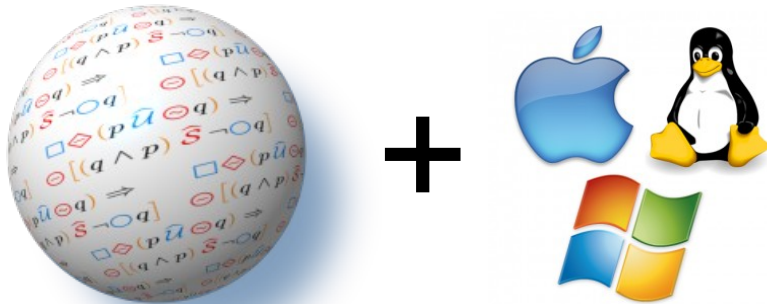
Addresses an important problem



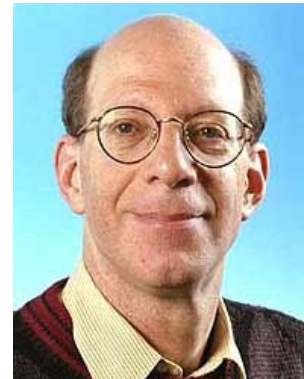
A simple, neat idea

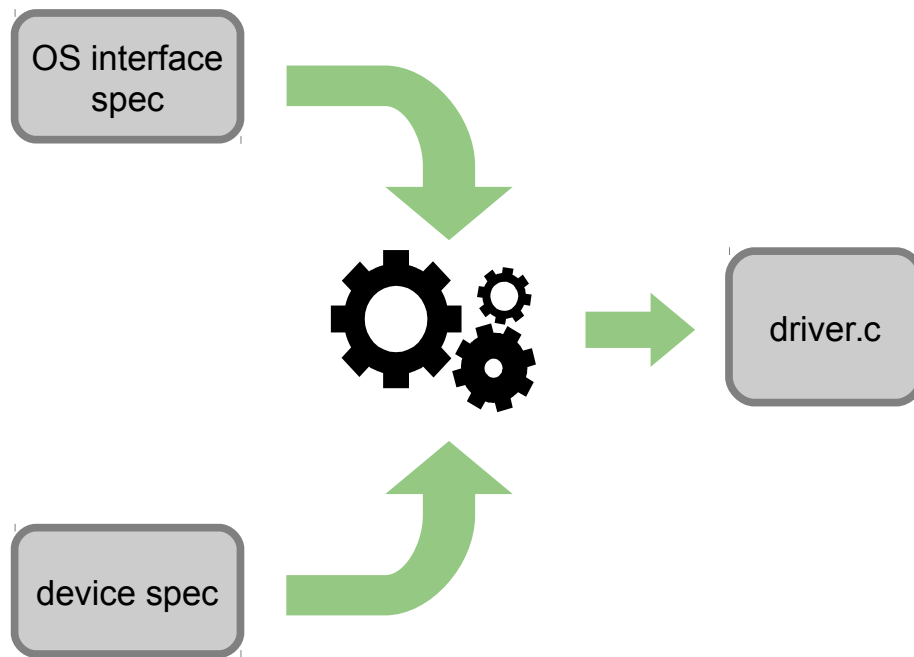


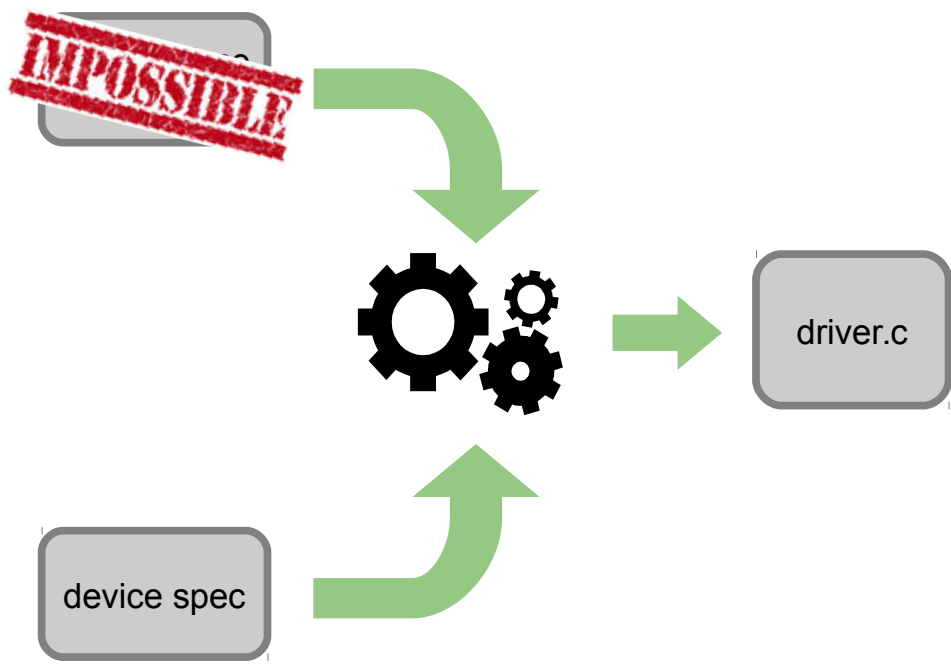
One of few applications of FM to OS (beyond verification)

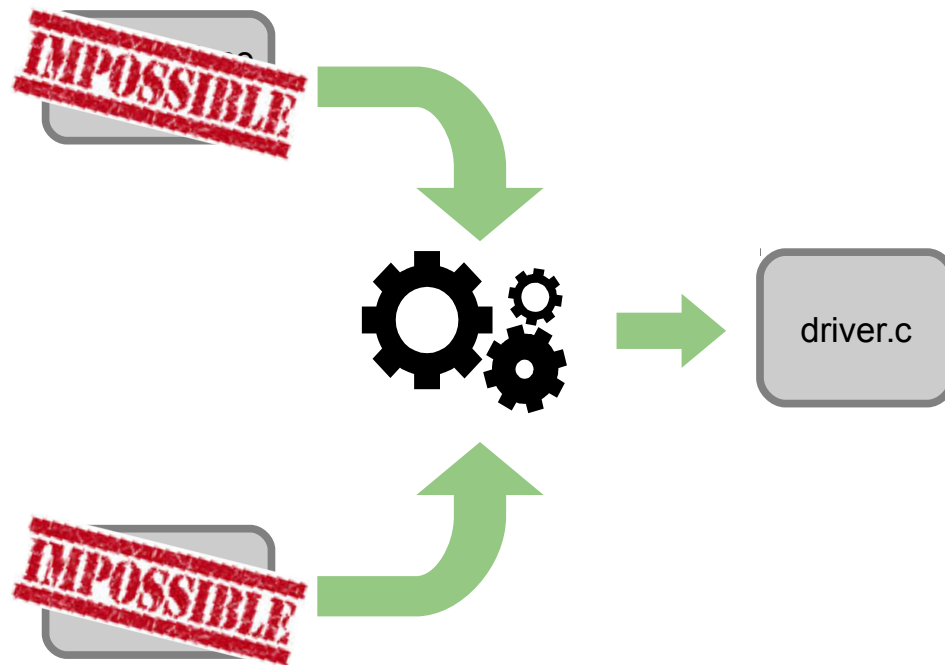


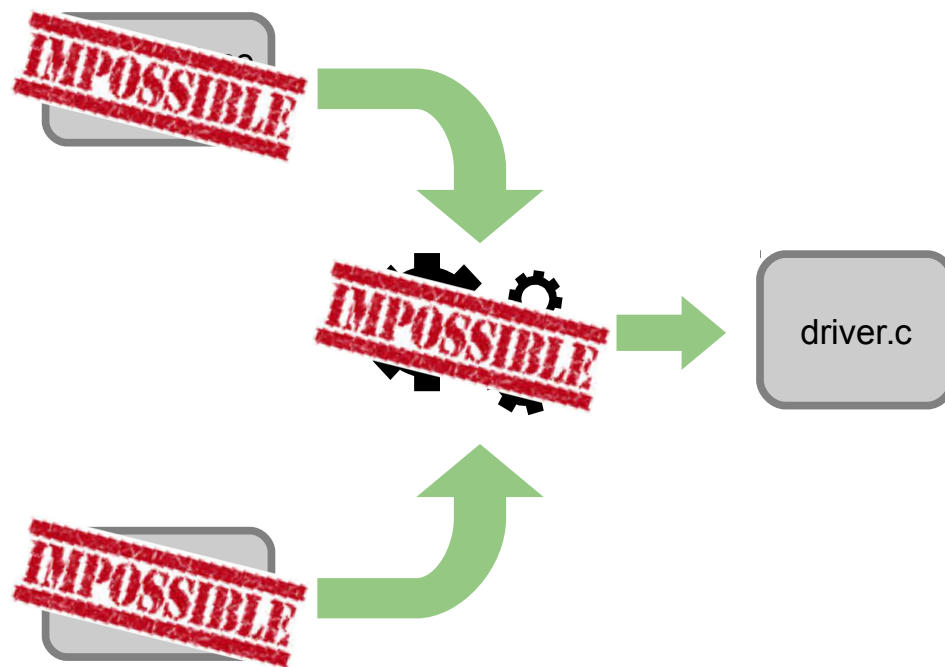
Considered impossible











# Driver Synthesis as a Game





# Driver Synthesis as a Game

```
request:set_time( 19:30:00 )
```



# Driver Synthesis as a Game

```
request:set_time( 19:30:00 )
```

```
write_hours( 19 )
```



# Driver Synthesis as a Game

```
request:set_time( 19:30:00 )
```

```
write_hours( 19 )
```

```
write_minutes( 30 )
```



# Driver Synthesis as a Game



```
request:set_time( 19:30:00 )  
write_hours( 19 )  
write_minutes( 30 )  
write_seconds( 00 )
```

# Driver Synthesis as a Game

```
request:set_time( 19:30:00 )
```

```
write_hours( 19 )
```

```
TICK
```



# Driver Synthesis as a Game

```
request:set_time( 19:30:00 )
```

```
write_hours( 19 )
```

```
TICK
```



# Driver Synthesis as a Game



```
request:set_time( 19:30:00 )
```

```
write_hours( 19 )
```

```
TICK
```

```
write_minutes( 30 )
```

```
write_seconds( 00 )
```

# Driver Synthesis as a Game



```
request:set_time(19:30:00)
```

**STOP**

```
write_hours(19)
```

```
write_minutes(30)
```

```
write_seconds(00)
```

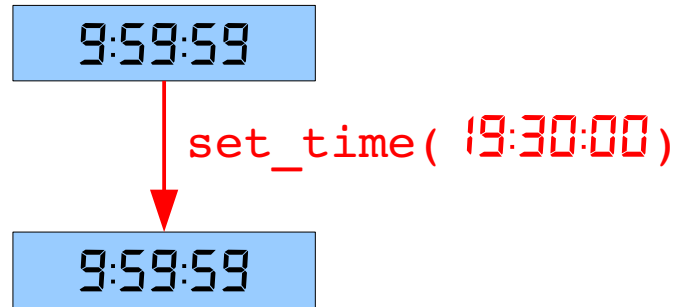
**START**



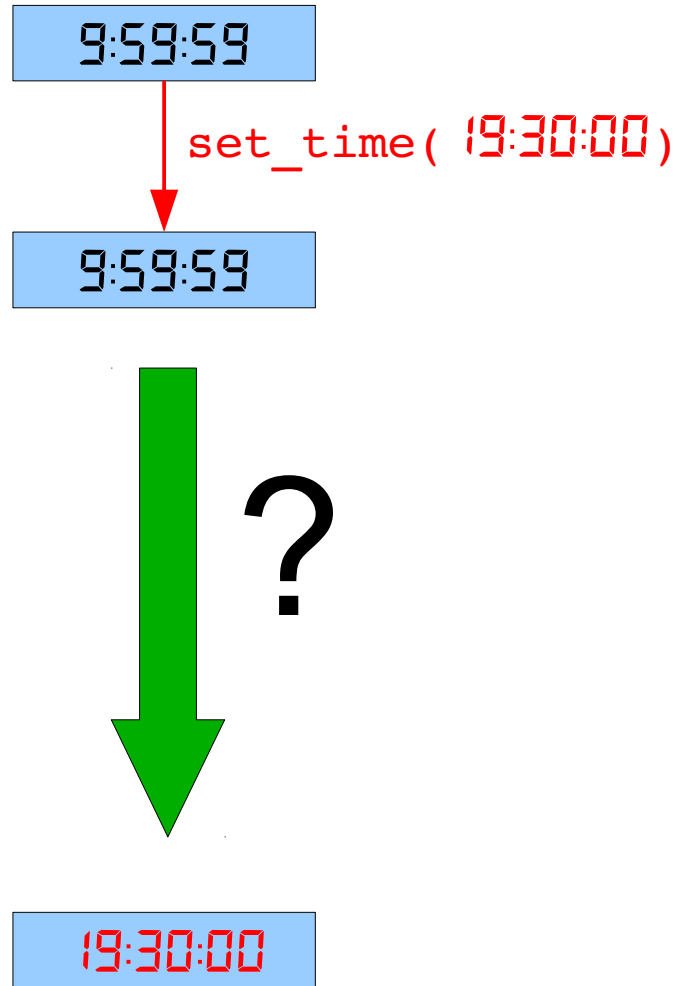
# Driver Synthesis as a Game

9:59:59

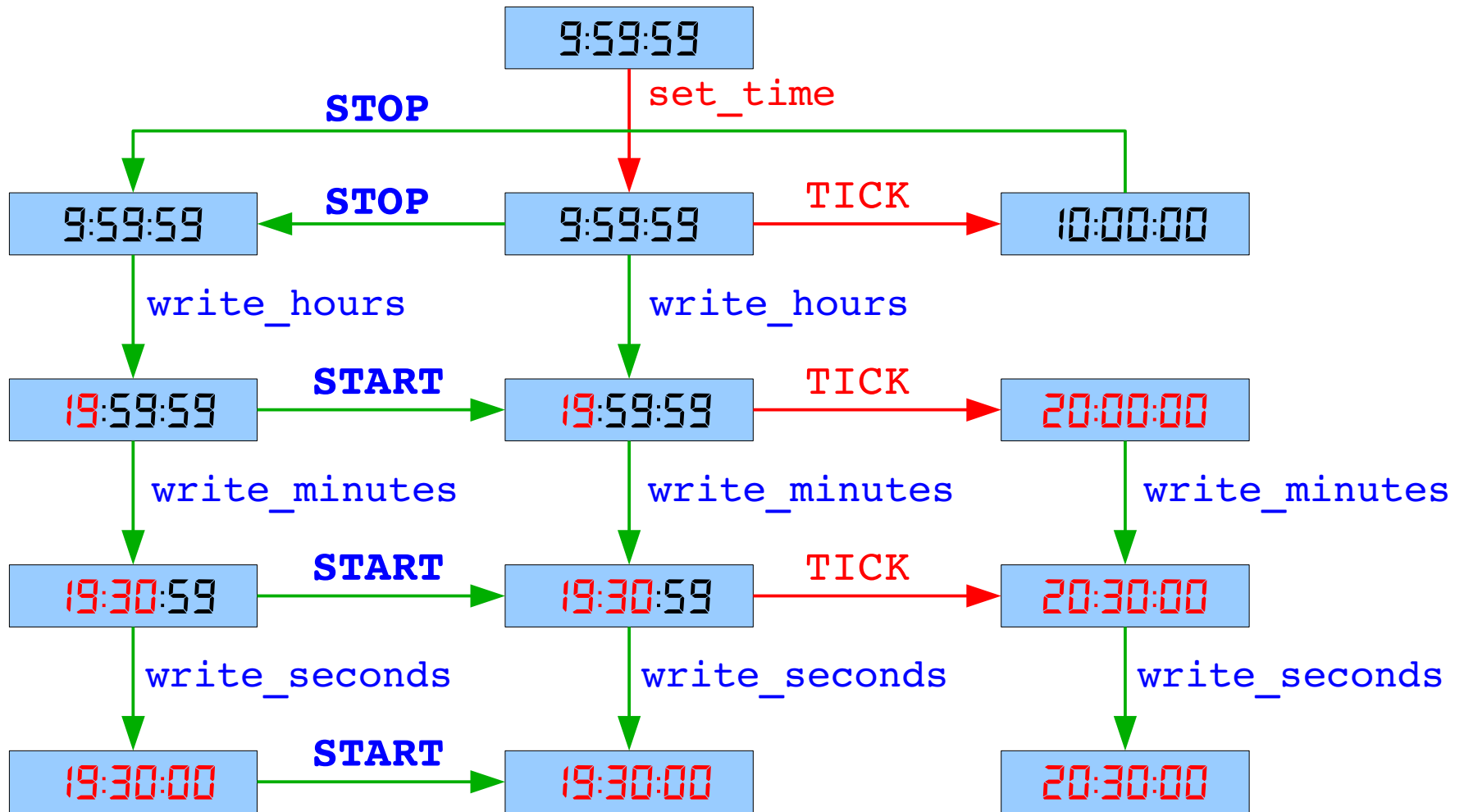
# Driver Synthesis as a Game



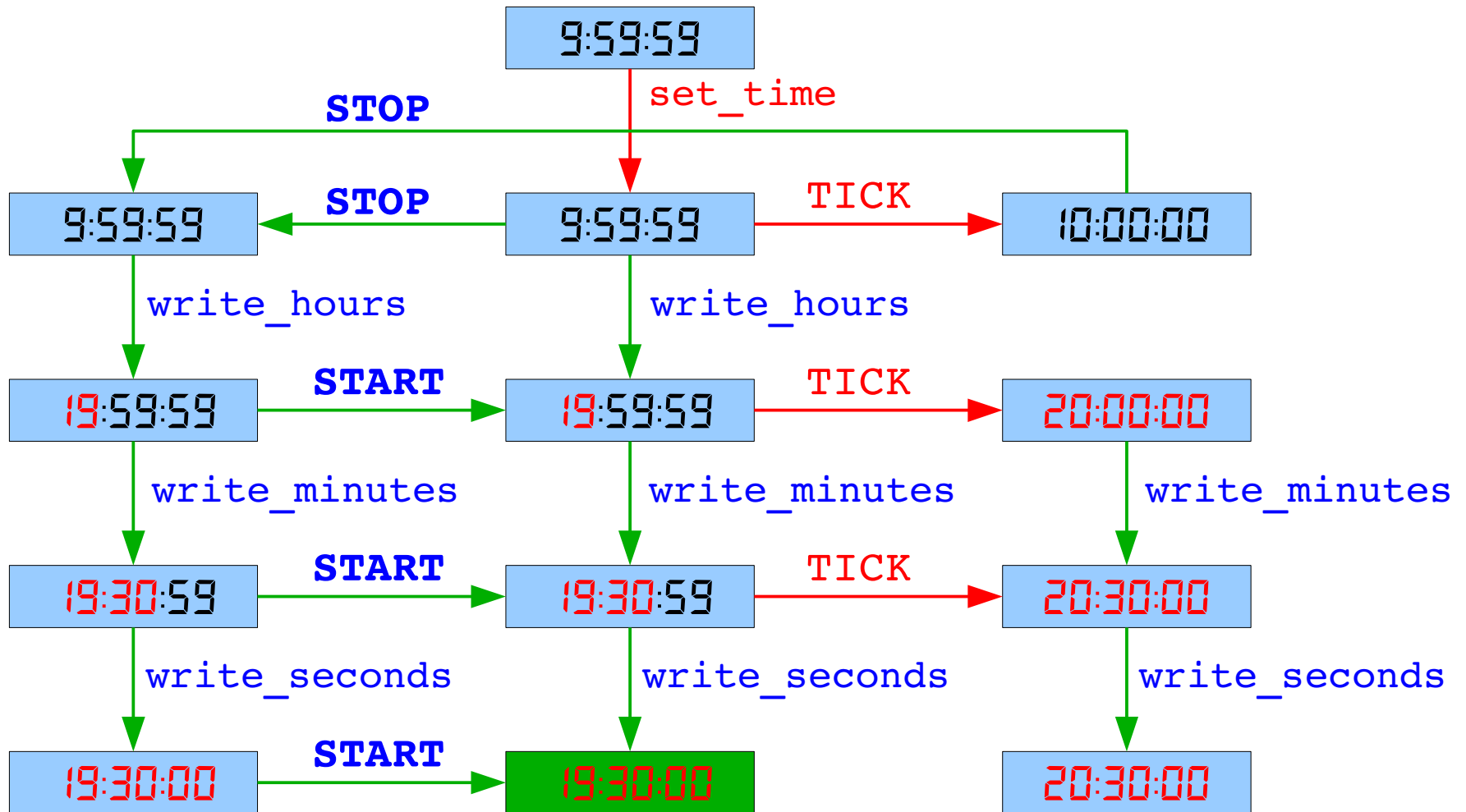
# Driver Synthesis as a Game



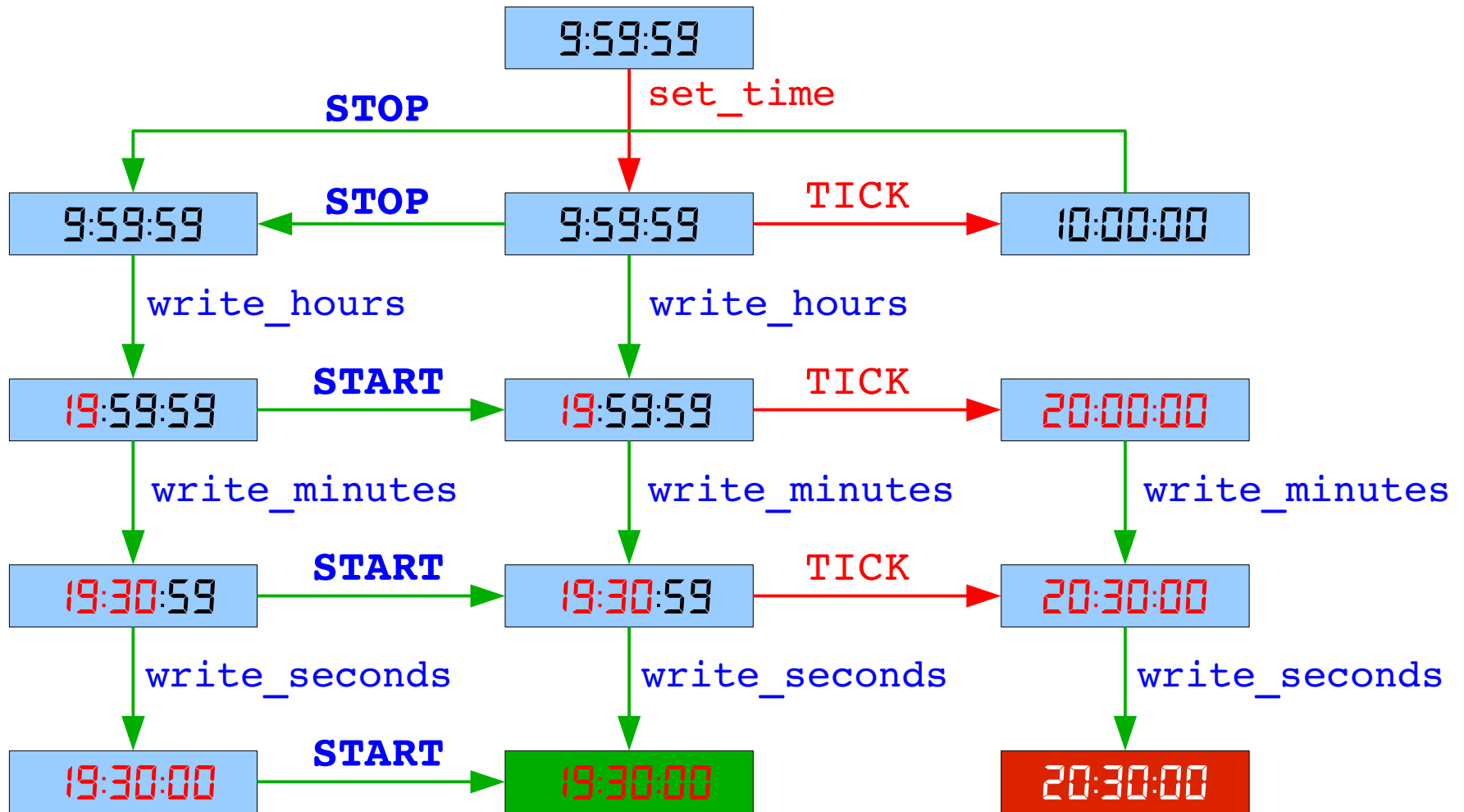
# Driver Synthesis as a Game



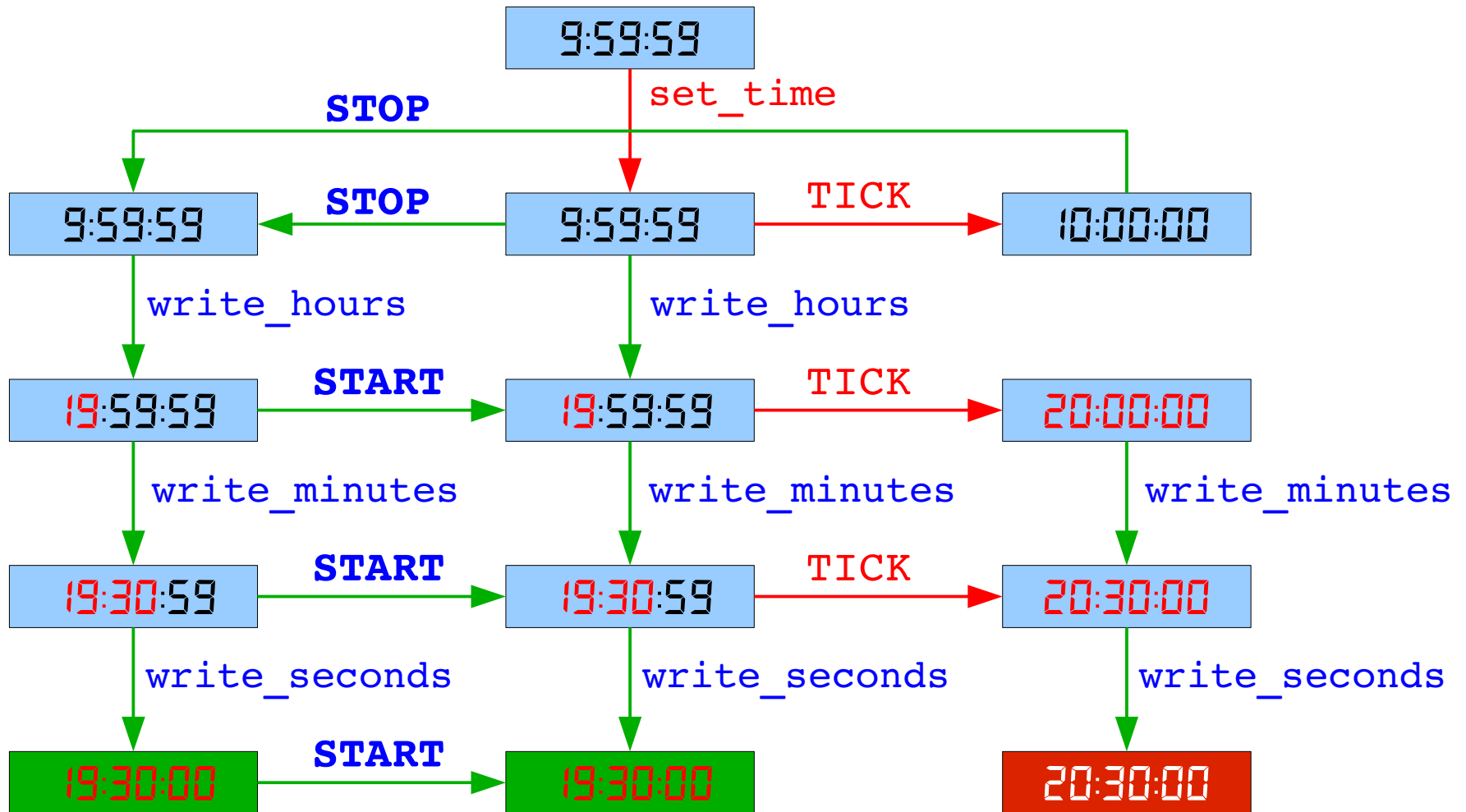
# Driver Synthesis as a Game



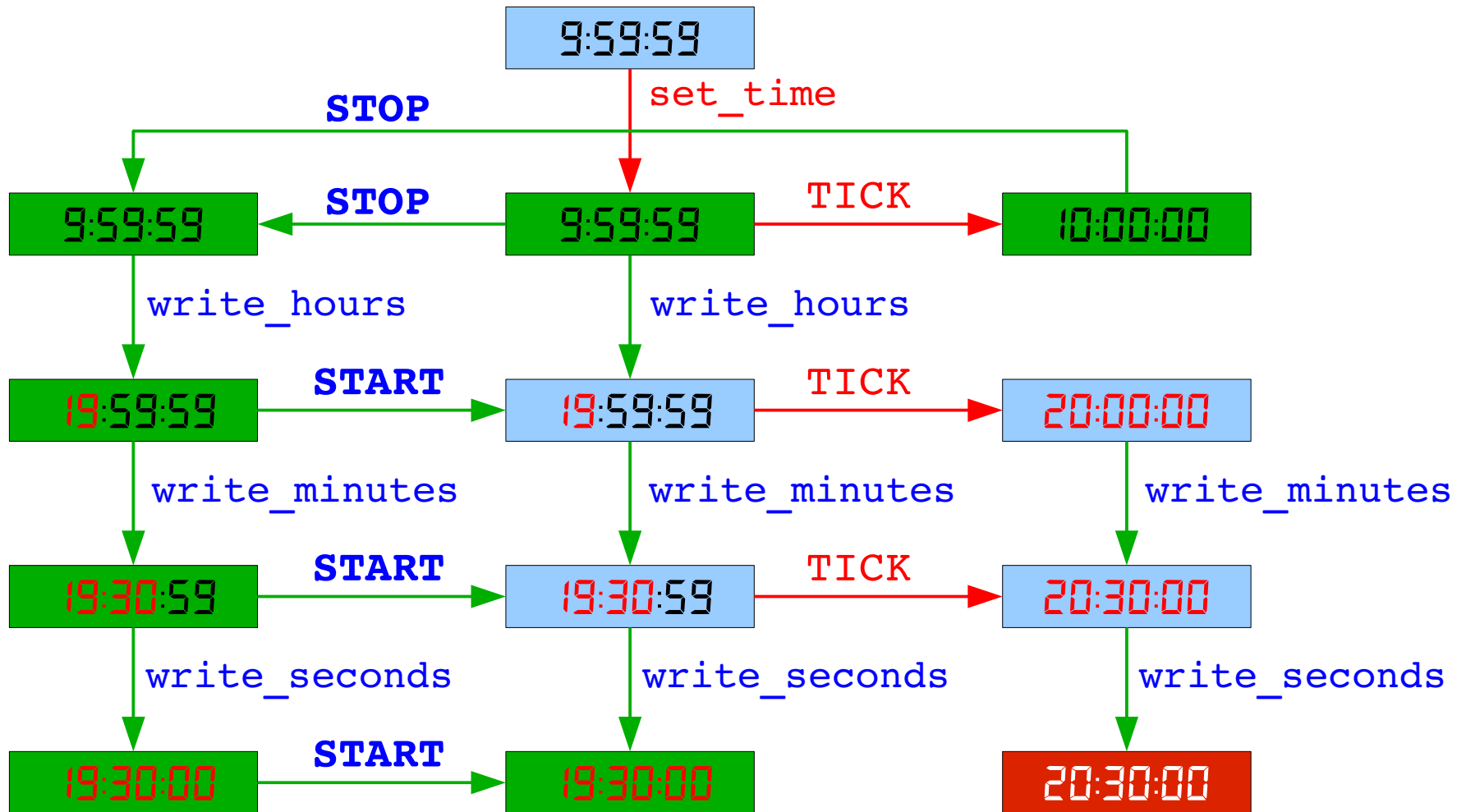
# Driver Synthesis as a Game



# Driver Synthesis as a Game

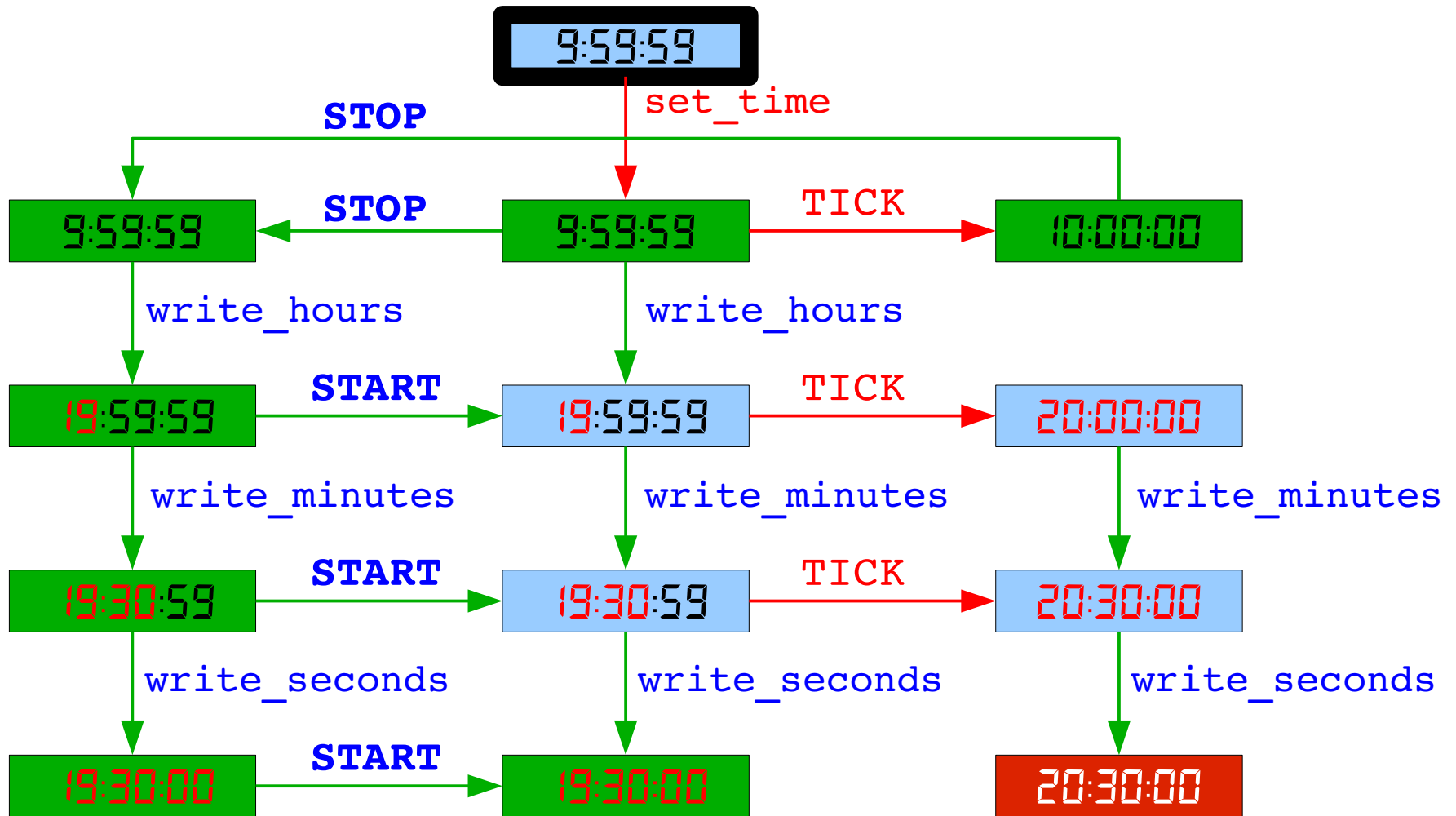


# Driver Synthesis as a Game

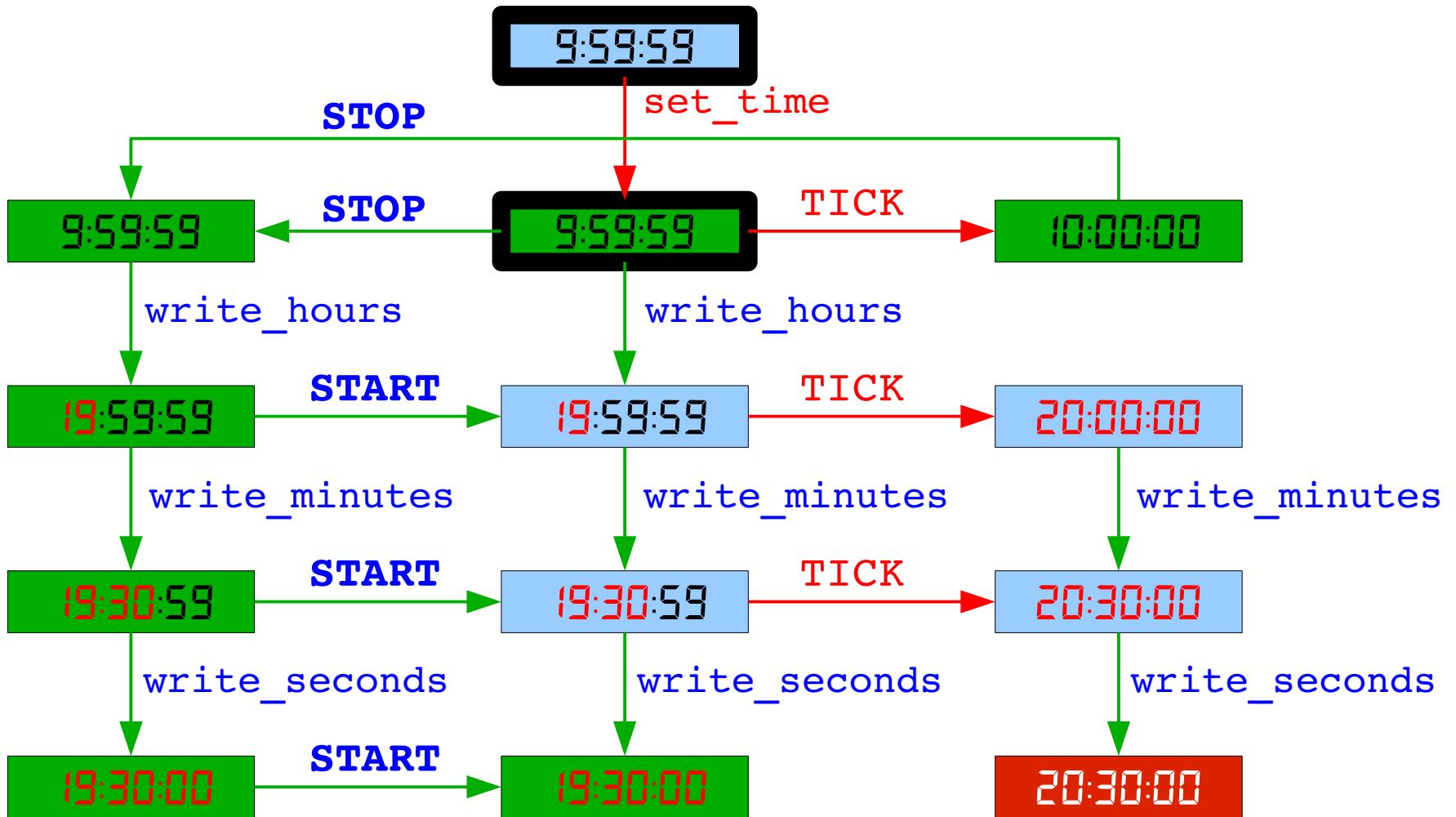




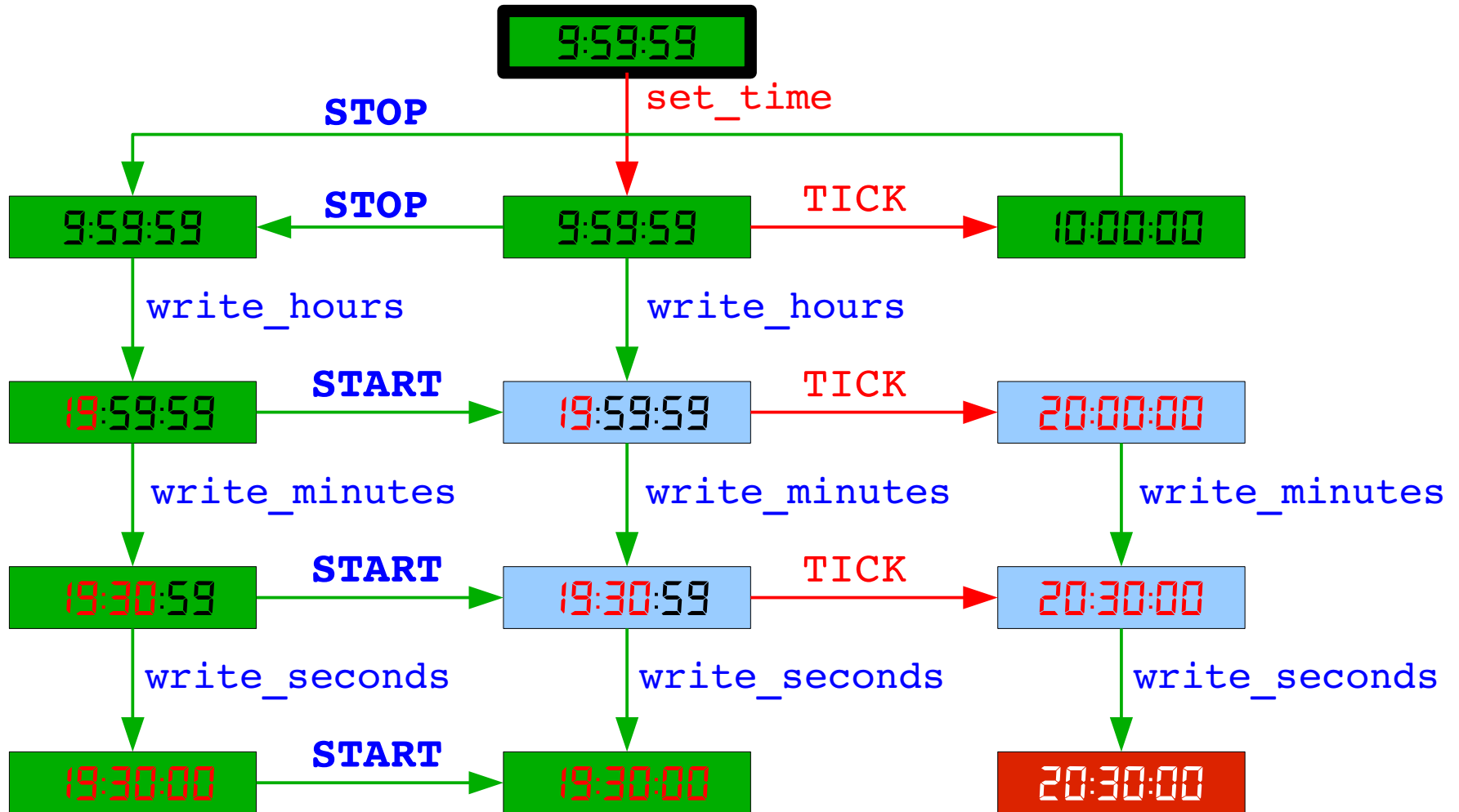
# Driver Synthesis as a Game



# Driver Synthesis as a Game



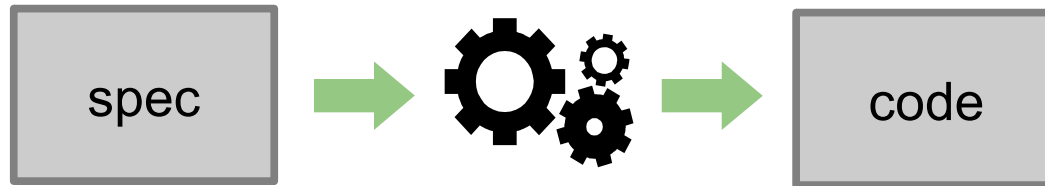
# Driver Synthesis as a Game



# Termite Tool Demo

# Push-Button Synthesis (SOSP'09)

- **In theory:**



correct spec => correct implementation

- **In practice:** (based on our experience) taking control away from the developer is not a good idea

# Push-Button Synthesis (SOSP'09)

- Choosing a preferred implementation method is hard (e.g., polling vs interrupts)
- Non-functional properties (power, performance, timing, etc.) are hard to enforce
- Achieving “nice” code structure is hard

# User-Guided Synthesis

- The user is in control
  - can write arbitrary manual code or ...
  - arbitrarily alter automatically generated code
- Synthesiser works as smart auto-complete
  - can generate a statement, a function, or even the whole driver (on demand)
  - never alters user code
  - completes synthesised+manual code to a correct implementation when possible
- The tool enforces correctness

Demo (continued)

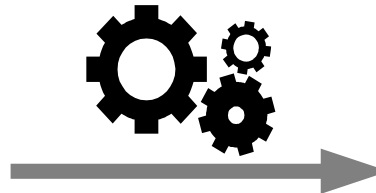


# Guided Synthesis

## Scenario 1: Fully Automatic Synthesis

```
send() {  
    ...  
}  
  
receive() {  
    ...  
}
```

driver template



```
send() {  
    write(ctl, flags);  
    write(irq_en, 0xff);  
    write(cmd, snd);  
}  
  
receive() {  
    write(ctl, flags);  
    write(irq_en, 0xff);  
    write(cmd, rcv);  
}
```

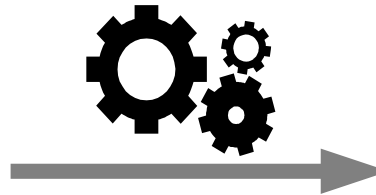
synthesised driver

# Guided Synthesis

## Scenario 2: Hybrid Approach

```
send() {  
    ...  
}  
  
receive() {  
    ...  
}
```

empty driver template



```
send() {  
    write(ctl, flags);  
    ...  
}  
  
receive() {  
    ...  
}
```

partially  
synthesised driver

# Guided Synthesis

## Scenario 2: Hybrid Approach

```
send() {  
    write(ctl,0);  
    ...  
}  
  
receive() {  
    ...  
}
```

modified driver template



```
send() {  
    write(ctl,flags);  
    ...  
}  
  
receive() {  
    ...  
}
```

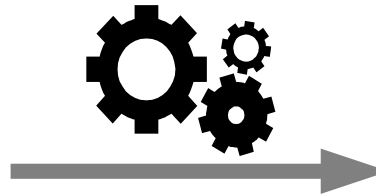
partially  
synthesised driver

# Guided Synthesis

## Scenario 2: Hybrid Approach

```
send() {  
    write(ctl,0);  
    ...  
}  
  
receive() {  
    ...  
}
```

modified driver template

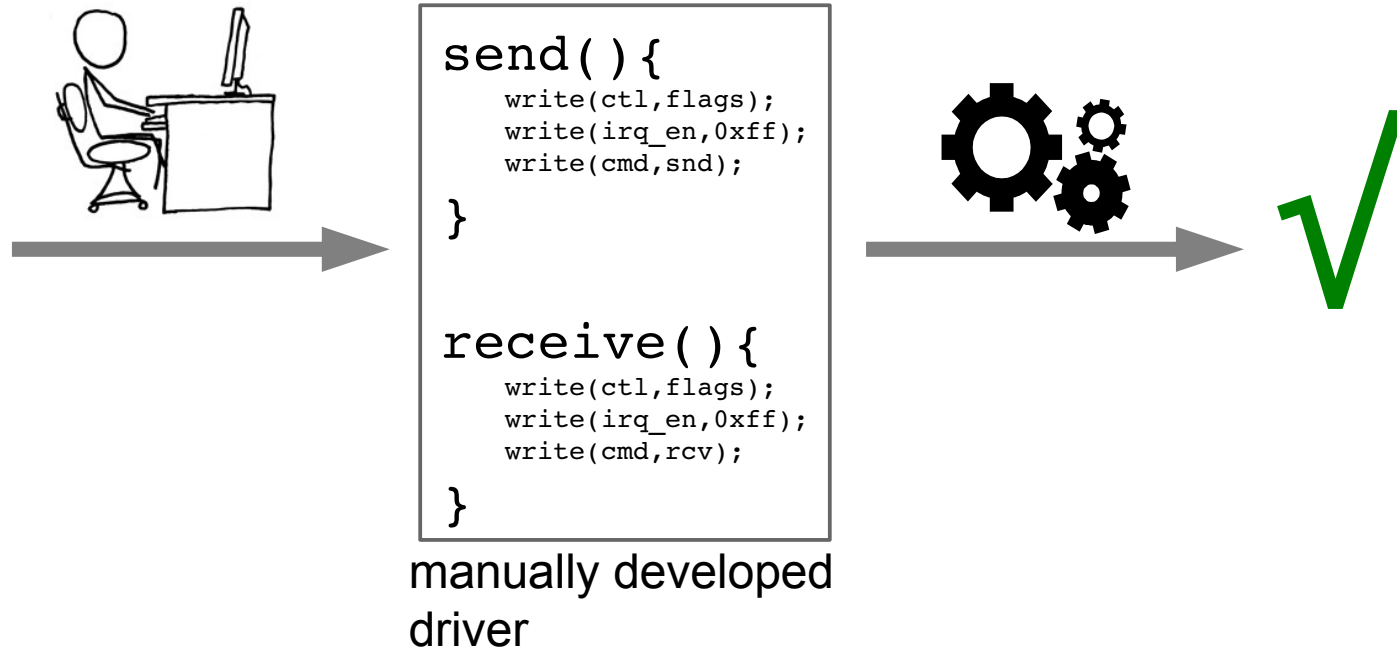


```
send() {  
    write(ctl,flags);  
    write(irq_en,0xff);  
    write(cmd,snd);  
}  
  
receive() {  
    write(ctl,flags);  
    write(irq_en,0xff);  
    write(cmd,rcv);  
}
```

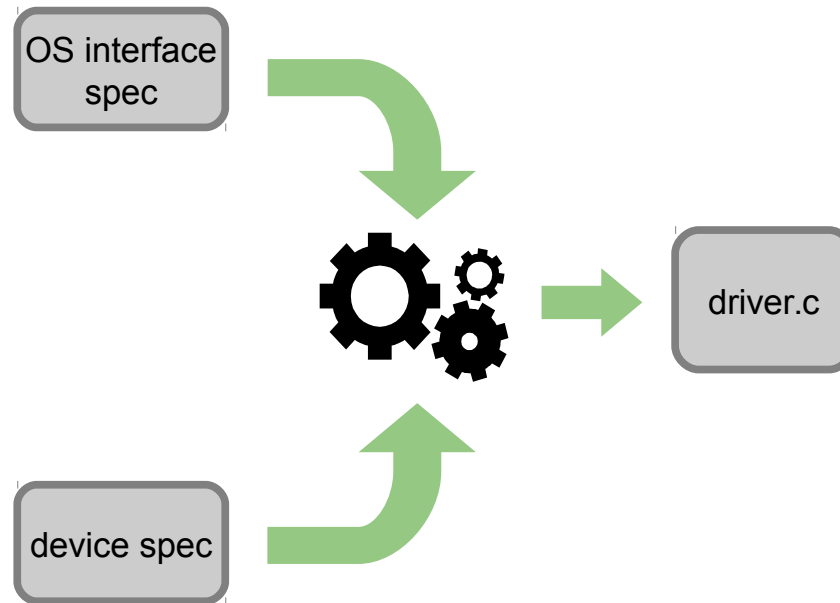
synthesised driver

# Guided Synthesis

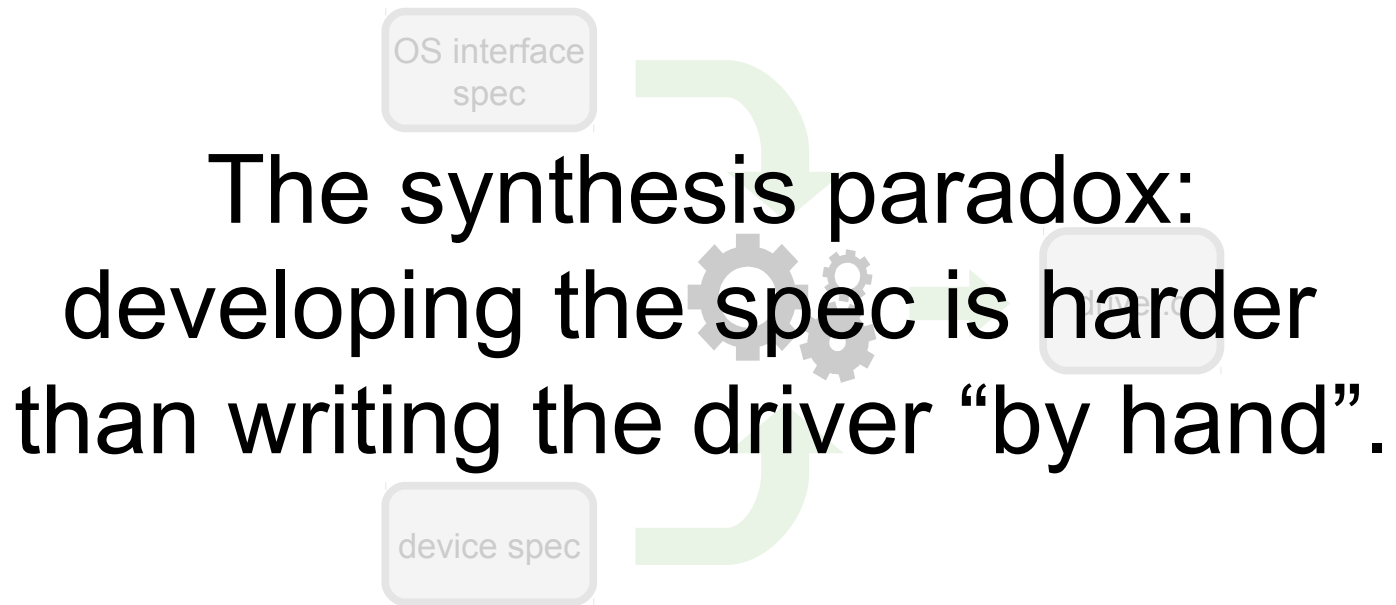
## Scenario 3: Verification



# Obtaining Specs for Driver Synthesis



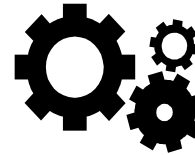
# Obtaining Specs for Driver Synthesis



# Obtaining Specs for Driver Synthesis

OS specs are **generic**, i.e.,  
made once for a **class** of devices

OS interface  
spec

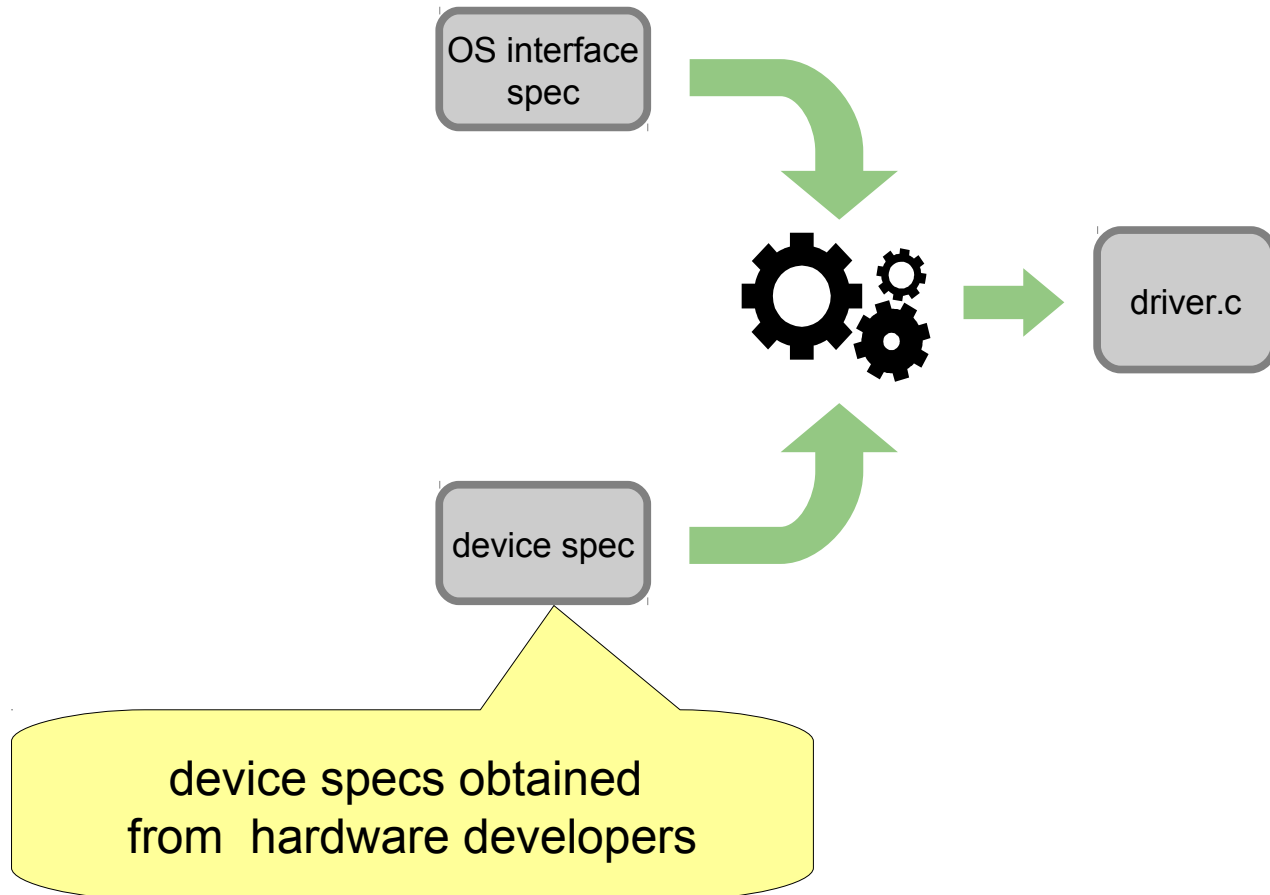


device spec

driver.c



# Obtaining Specs for Driver Synthesis



# Synthesised Drivers

Device	Synthesis time (s)	locs
Real-time clock	74	56
IDE	71	94
STM32F103RB UART	309	74
exynos 5 UART	177	35
STM32F103RB I2C	39	119
exynos 5 I2C	40	77
webcam	190	113
SPI	15	27

# Synthesised Drivers

Device	Synthesis time (s)	locs
Real-time clock	74	56
IDE	71	94
STM32F103RB UART	309	74
exynos 5 UART	177	35
STM32F103RB I2C	39	119
exynos 5 I2C	40	77
webcam	190	113
SPI	15	27

# Scope and Limitations

- Focus on synthesising device control logic
  - Resource allocation, binding to OS interfaces, etc., must be written manually or synthesised using different techniques
- Sequential synthesis
  - Synchronisation synthesis as a separate step (jointly with CU Boulder and IST Austria)
- No DMA support
  - WiP

# Summary

- Termite automates tedious driver development
- The user has full control over the source code, but Termite enforces correctness

`https://github.com/termite2`

`http://termite2.org`

# Summary

- Termite automates tedious driver development
- The user has full control over the source code, but Termite enforces correctness
- **Driver synthesis is less impossible than previously believed**

`https://github.com/termite2`

`http://termite2.org`