

# Scalable Error Isolation for Distributed Systems

*Diogo Behrens*, Sergei Arnautov, Christof Fetzer (TU Dresden)  
Marco Serafini (Qatar Computing Research Institute)  
Flavio P. Junqueira (Microsoft Research, Cambridge)

May 6, 2015

# Motivation



[Amazon Web Services](#) » [Service Health Dashboard](#) » Amazon S3 Availability Event: July 20, 2008

## **Amazon S3 Availability Event: July 20, 2008**

We wanted to provide some additional detail about the problem we experienced on Sunday, July 20th.

At 8:40am PDT, error rates in all Amazon S3 datacenters began to quickly climb and our alarms went off. By 8:50am PDT, error rates were significantly elevated and very few requests were completing successfully. By 8:55am PDT, we had multiple engineers engaged and investigating the issue. Our alarms pointed at problems processing customer requests in multiple places within the system and across multiple data centers. While we began investigating several possible causes, we tried to restore system health by taking several actions to reduce system load. We reduced system load in several stages, but it had no impact on restoring system health.

Amazon

## Mesa: Geo-Replicated, Near Real-Time, Scalable Data Warehousing

Ashish Gupta, Fan Yang, Jason Govig, Adam Kirsch, Kelvin Chan  
Kevin Lai, Shuo Wu, Sandeep Govind Dhoot, Abhilash Rajesh Kumar, Ankur Agiwal  
Sanjay Bhansali, Mingsheng Hong, Jamie Cameron, Masood Siddiqi, David Jones  
Jeff Shute, Andrey Gubarev, Shivakumar Venkataraman, Divyakant Agrawal  
Google, Inc.

### ABSTRACT

Mesa is a highly scalable analytic data warehousing system that stores critical measurement data related to Google's Internet advertising business. Mesa is designed to satisfy

ness critical nature of this data result in unique technical and operational challenges for processing, storing, and querying. The requirements for such a data store are:

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Mesa is a highly scalable analytic data warehouse that stores critical measurement data for Amazon's Internet advertising business. Mesa

### 4.4 Mitigating Data Corruption Problems

Mesa uses tens of thousands of machines in the cloud that are administered independently and are shared among many services at Google to host and process data. For any computation, there is a non-negligible probability that faulty hardware or software will cause incorrect data to be generated and/or stored. Simple file level checksums are not sufficient to defend against such events because the corruption can occur transiently in CPU or RAM. At Mesa's scale, these seemingly rare events are common. Guarding against such corruptions is an important goal in Mesa's overall design.

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### 4.4 Mitigating Data Corruption Problems

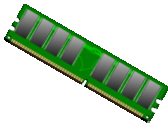
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CRC for messages!



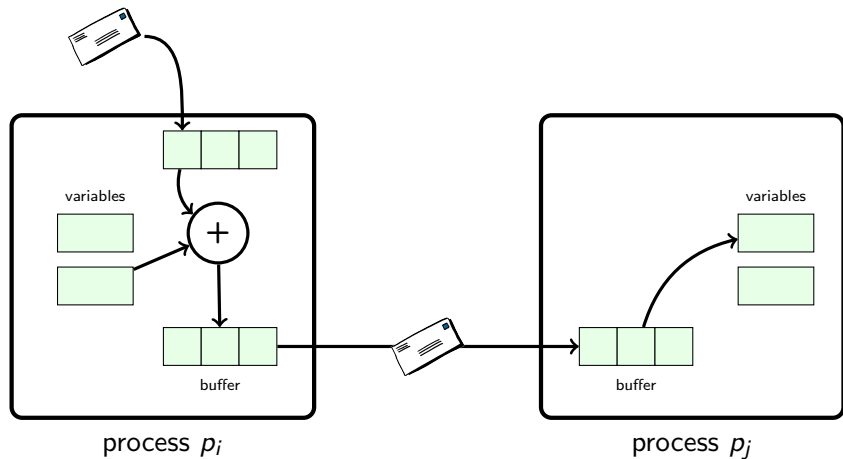
ECC for memory!



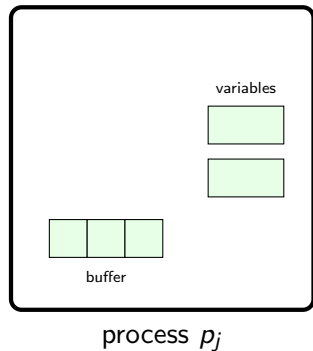
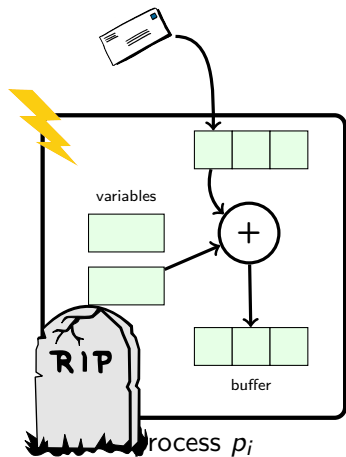
CPU??



# From data corruption to service disruption

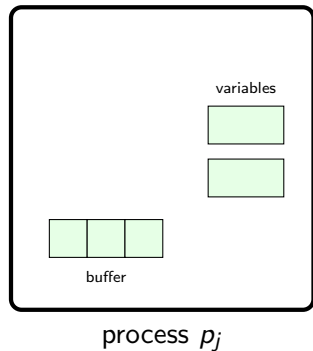
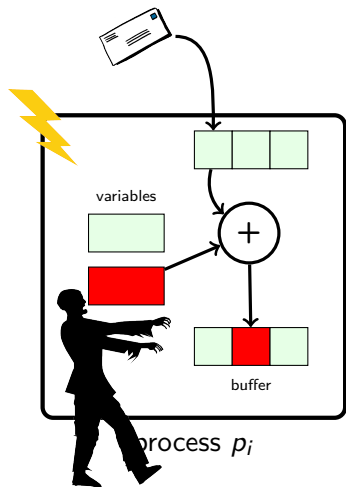


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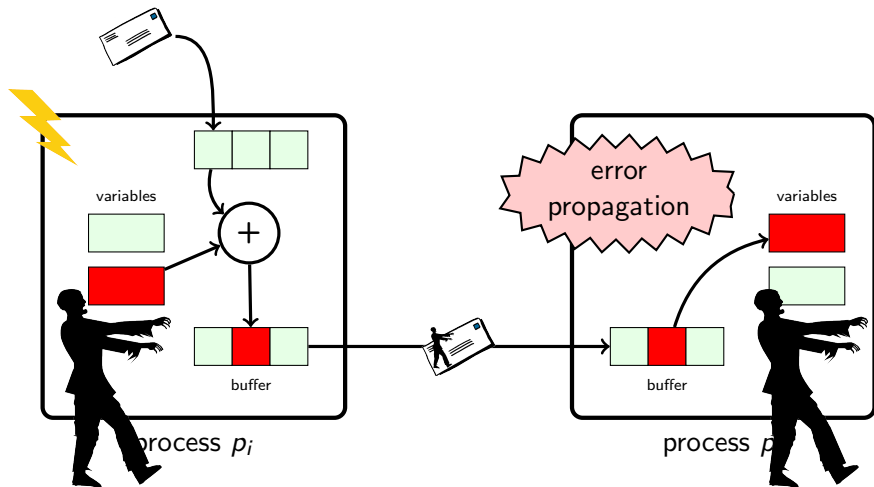




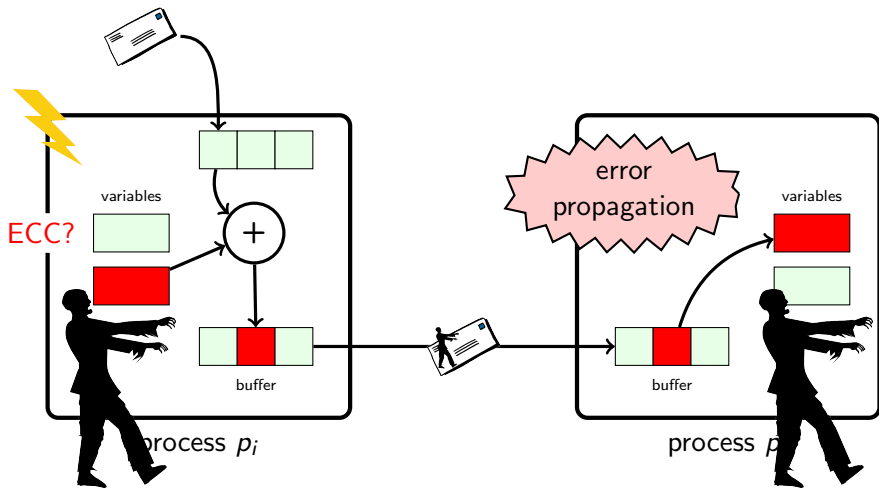
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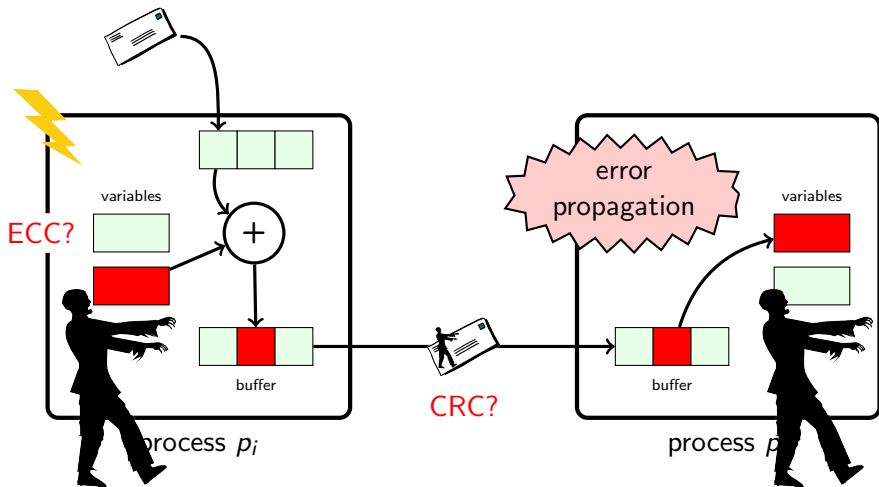
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# From data corruption to service disruption



This talk is about...

# HOW TO KILL A ZOMBIE



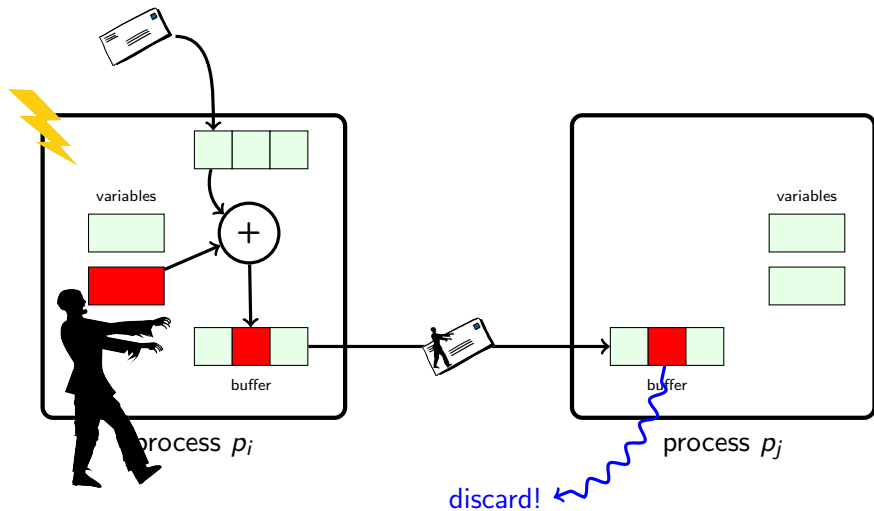
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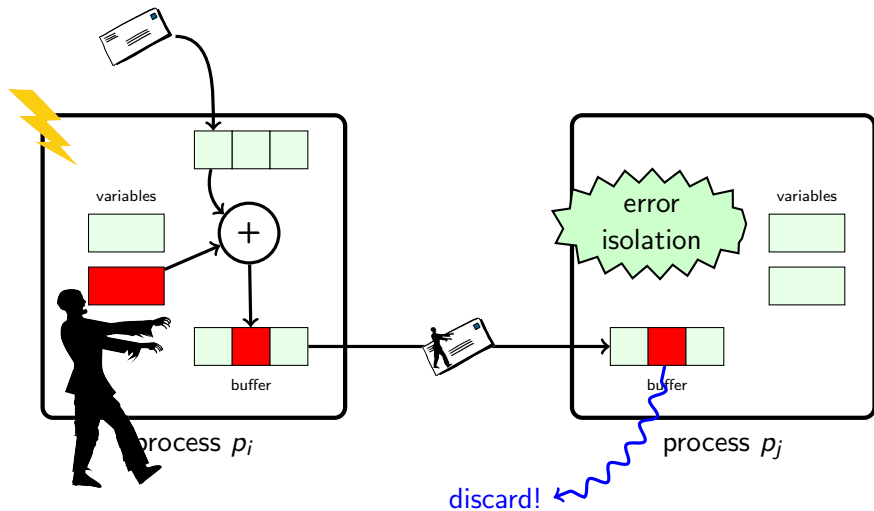
isolate



# Goal: error isolation



# Goal: error isolation





How to deal with data corruptions?

# DIY: Ad hoc software checks

```
while(1) {
    switch(state) {
        case INIT: {
            // create socket, bind and listen
            fd = socket(AF_INET, SOCK_STREAM, 0);
            if (fd < 0) {
                perror("socket");
                return EXIT_FAILURE;
            }

            // this is important, so that if a process restarts, it can
            // quickly reuse the same port
            int on = 1;
            if (setsockopt(fd, SOL_SOCKET, SO_REUSEADDR, &on, sizeof(on)) < 0) {
                perror("setsockopt");
                return EXIT_FAILURE;
            }

            bzero(&addr, sizeof(addr));
            addr.sin_family = AF_INET;
            addr.sin_addr.s_addr = htonl(INADDR_ANY);
            addr.sin_port = htons(port);

            if (bind(fd, (struct sockaddr*)&addr, sizeof(addr)) < 0) {
                perror("bind");
                return EXIT_FAILURE;
            }

            if (listen(fd, 2) < 0) {
                perror("listen");
                return EXIT_FAILURE;
            }

            // initialize ukv service
            ukv = ukv_init();

            state = ACCT;
            break;
        }

        case RECV: {
            // once a connection is accepted, read the connection
            // until it is closed
            read = recvfrom(cfd, buffer, BUFSIZE, 0, (struct sockaddr*)&caddr, &len);
            if (read <= 0) {
                perror("recvfrom");
                close(cfd);
            }

            state = ACCT;
            break;
        }

        buffer[read] = '\0';
        msg = buffer;

        state = PRDC;
        break;
    }

    case PRDC: {
        r = ukv_recv(ukv, msg);
        if (!r) state = FINI;
        else state = SEND;
        break;
    }

    case SEND: {
        sendto(cfd, r, strlen(r), 0,
              (struct sockaddr*)&caddr, sizeof(caddr));
        ukv_done(ukv, r);
        state = RECV;
        break;
    }
}
}
```



# DIY: Ad hoc software checks

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                close(cfds);
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                break;
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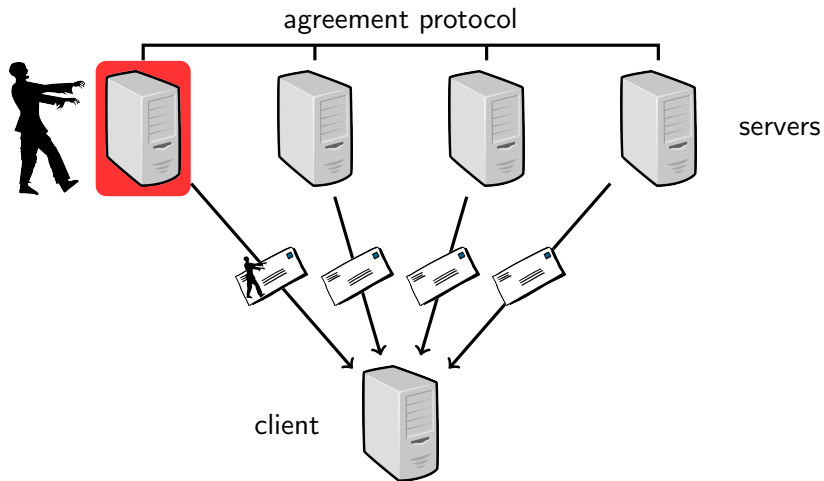
            buffer[read] = '\0';
            msg = buffer;

            state = PROC;
            break;
        }
        case PROC: {
            r = ukv_recv(ukv, msg);
            if (!r) state = FINI;
            else state = SEND;
            break;
        }
        case SEND: {
            sendto(cfds, r, strlen(r), 0,
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            ukv_done(ukv, r);
            state = RECV;
            break;
        }
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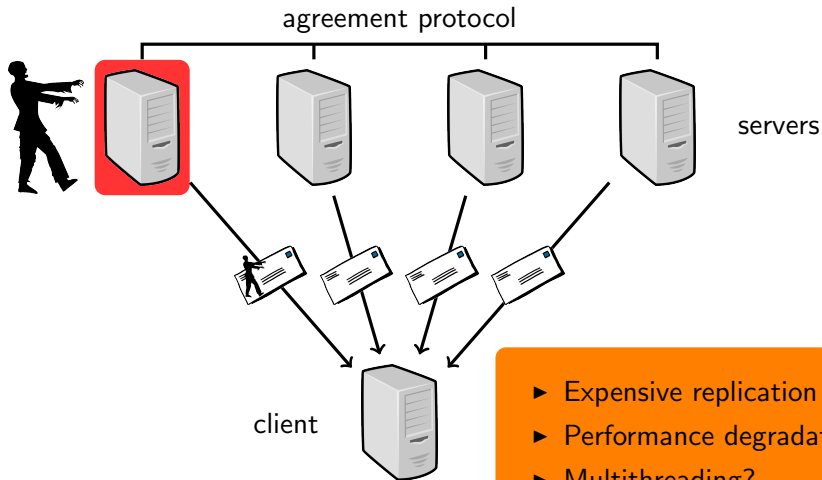
- ▶ Complex, time consuming
- ▶ Which errors to consider?
- ▶ No principled approach



# Principled approach: Byzantine fault tolerance



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# Principled approach: Local hardening

- ▶ **Instruction duplication (SWIFT, CGO'05)**
  - + compiler technique
  - not designed for distributed systems
  - last-mile faults (no error isolation)

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- + compiler technique
- not designed for distributed systems
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- ▶ **PASC (ATC'12)**

- + achieves error isolation
- large memory overhead (2x)
- no support for multithreading



# Scalable Error Isolation

A new approach



## **Local hardening**

No additional messages exchanged;  
Local redundancy in space and time

# Scalable Error Isolation (SEI)



## Local hardening

No additional messages exchanged;  
Local redundancy in space and time



## End-to-end

CRCs for communication and **computation**

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## End-to-end

CRCs for communication and **computation**



## Formal guarantees

Fault model and correctness proof

# Scalability dimensions



## **Memory scalability**

Small footprint (ECC or other error codes)



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## **Thread scalability**

Support for multithreaded applications

# Scalability dimensions



## Memory scalability

Small footprint (ECC or other error codes)



## Thread scalability

Support for multithreaded applications

`main()`

## Codebase scalability

Compiler technique reduces developer work





## Overview of SEI

Requirements, fault model, and algorithm



## Challenges

Support for multithreaded applications

foo()

## Implementation: libsei

Library for C-based programs



## Evaluation

Fault coverage and performance overhead



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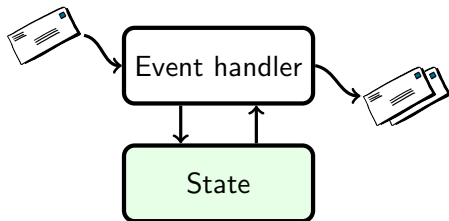
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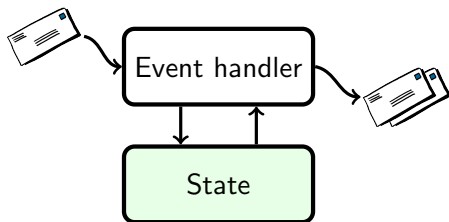
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Fault coverage and performance overhead

- ▶ **Event based – message passing**



## ▶ Event based – message passing

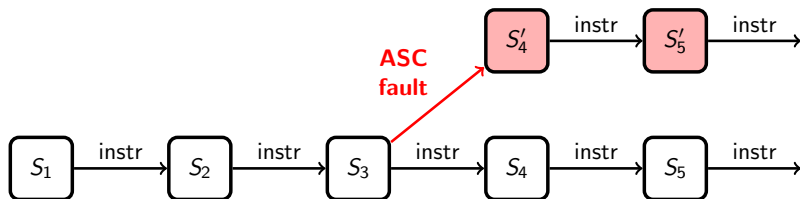


## ▶ Multithreaded applications

- Critical sections to access shared variables
- Hierarchical locking (consistent order) to avoid deadlocks

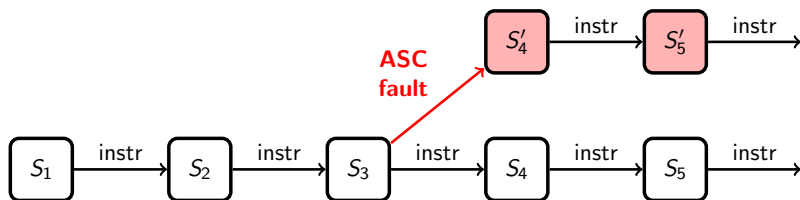
# Arbitrary State Corruption (ASC) Model

Faults corrupt any number of variables



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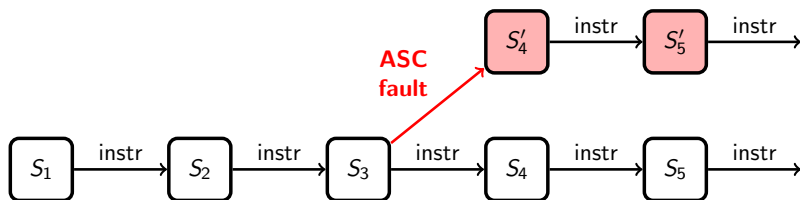


**Assumptions:**

- ▶ **Fault frequency:**  
at most one 1 fault per event handler

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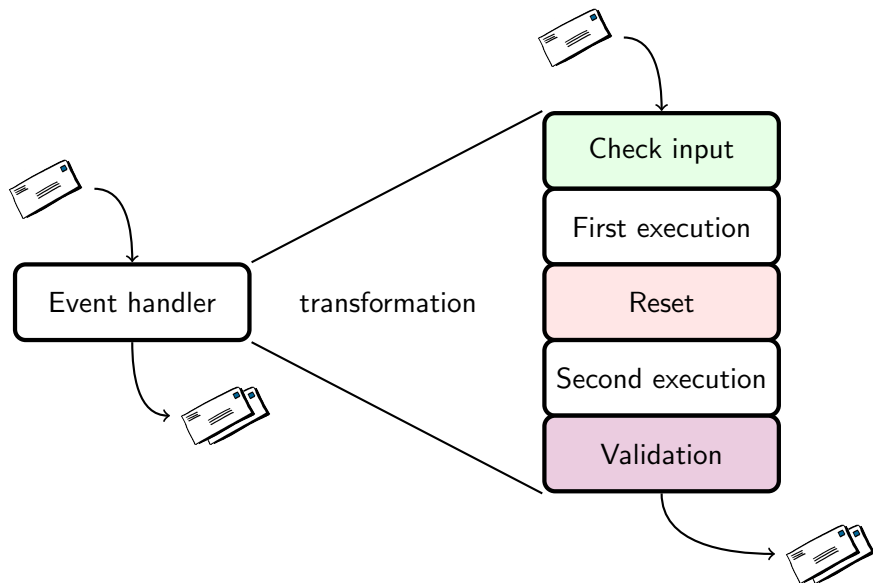
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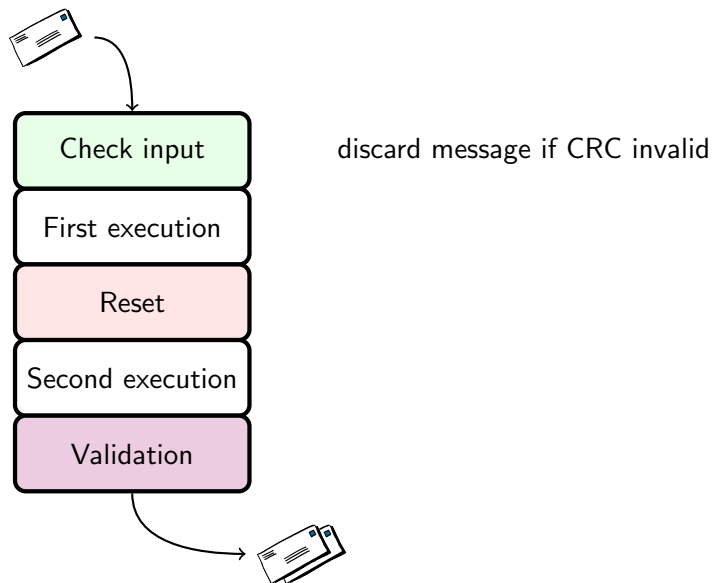
- ▶ **Fault frequency:**  
at most one 1 fault per event handler
- ▶ **Corruption coverage:**  
detection codes work, e.g., ECC, CRC

# Hardening with SEI

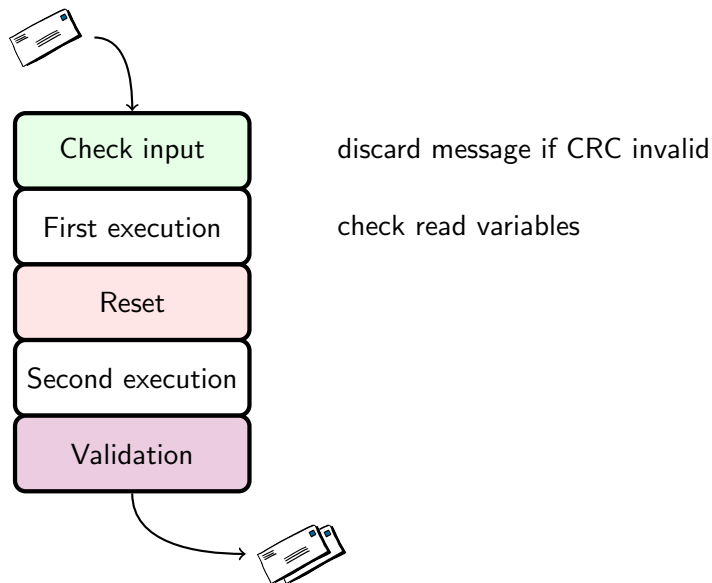




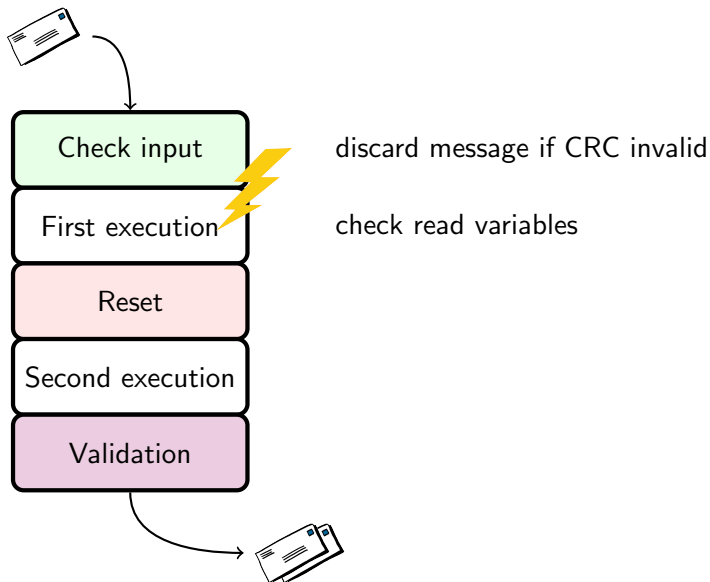
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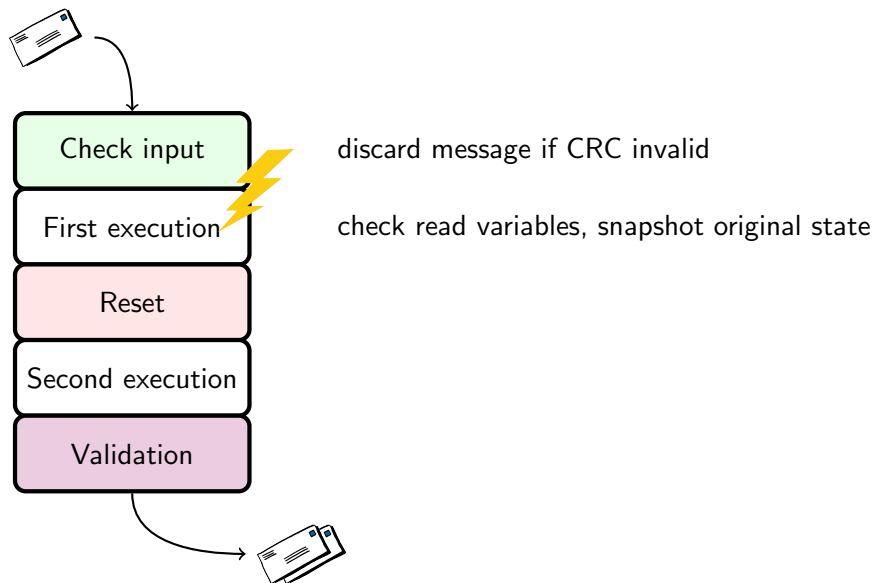
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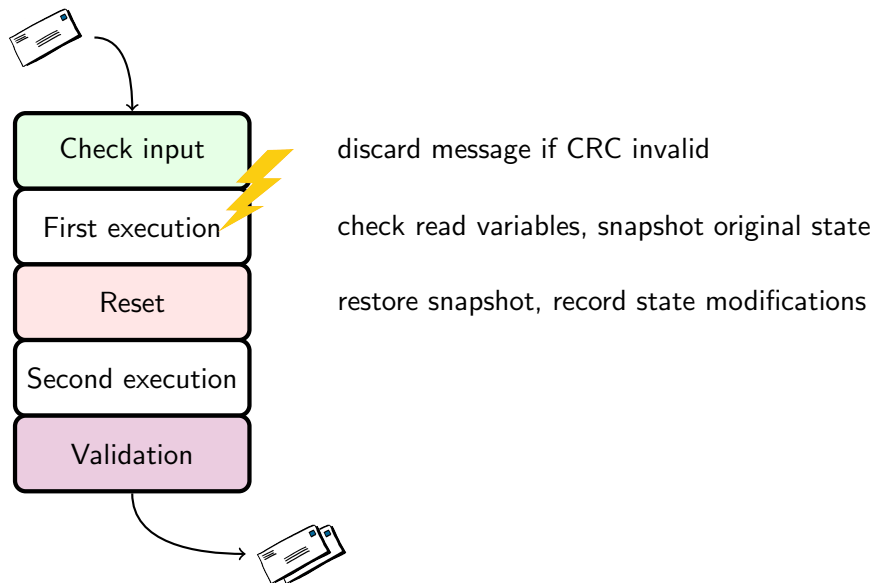
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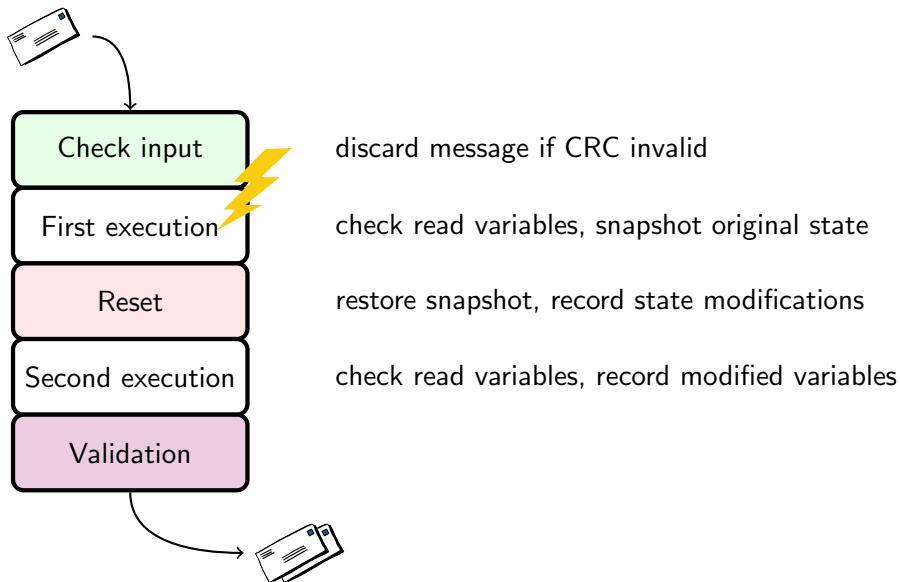
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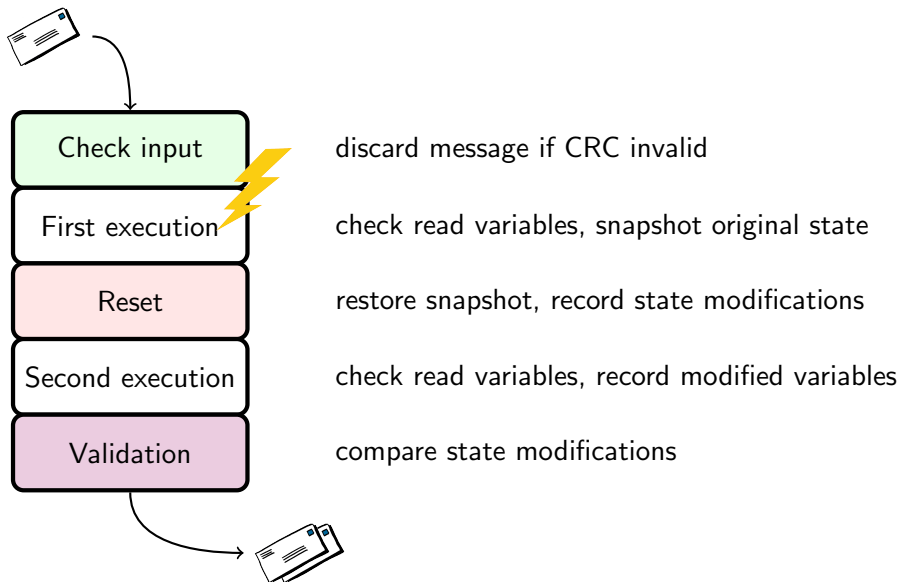
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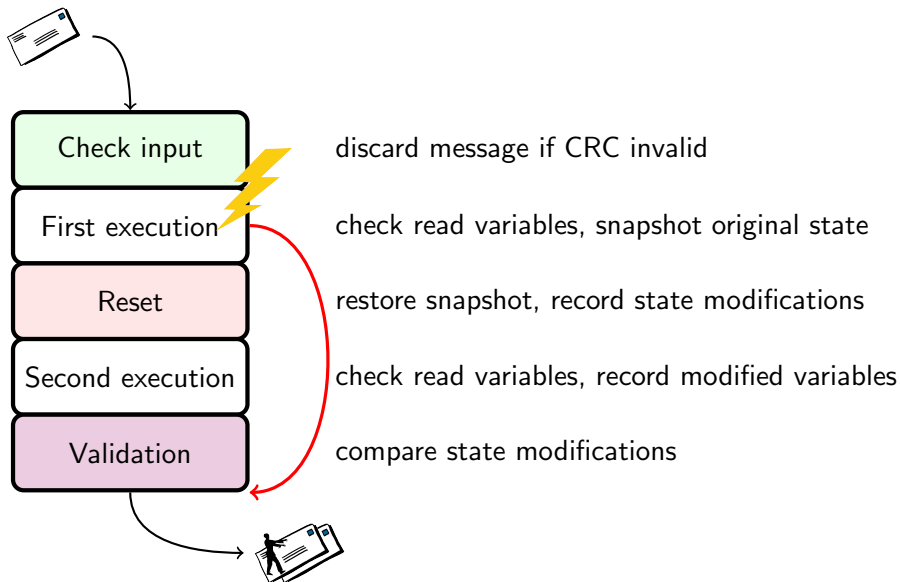
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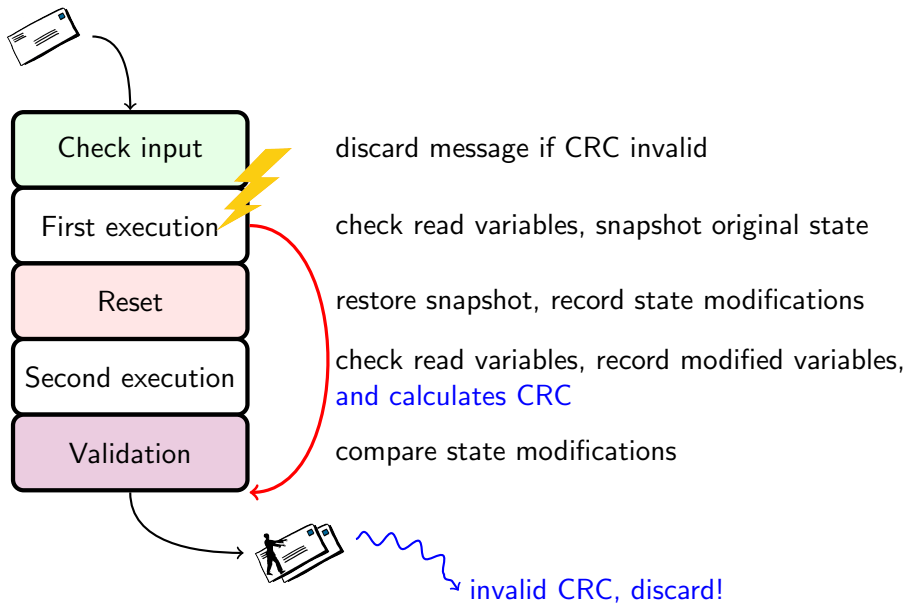


# Hardening with SEI





# Hardening with SEI





## Overview of SEI

Requirements, fault model, and algorithm



## Challenges

Support for multithreaded applications

foo()

## Implementation: libsei

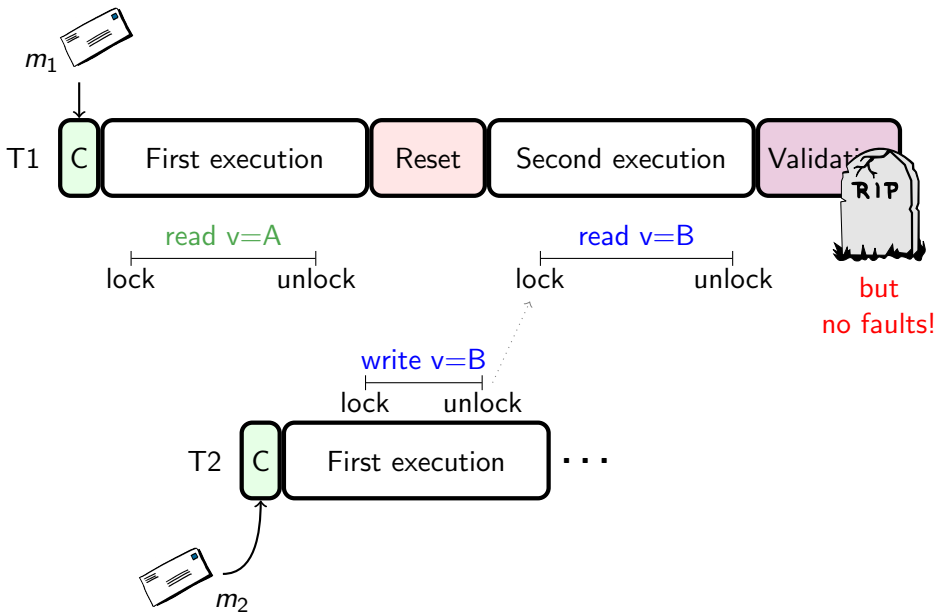
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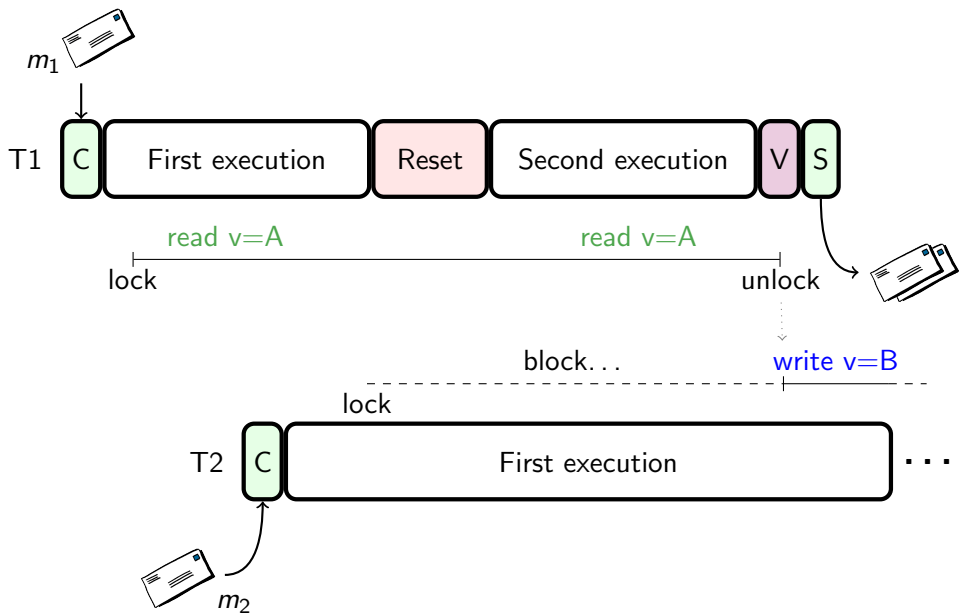
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# Deterministic event handling with multithreading



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# libsei: SEI implementation in C

[bitbucket.org/db7/libsei](http://bitbucket.org/db7/libsei)

```
while(1) {
    ilen = recv_msg(msg, &crc);

    do_something_here(msg);
    omsg = create_message(&olen);

    send_msg(omsg, olen, CRC(omsg, olen));
}
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- ▶ **Annotate event handler**  
with `__begin` and `__end`
- ▶ **Annotate messages**  
`__output*` for annotation  
`__crc_pop` for next CRC

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state updates within handler  
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- ▶ **libsei does the rest**
  - executes handler twice
  - calculates CRCs
  - validates state updates



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- ▶ Deadwood
  - DNS recursive server
  - Single-threaded
  - See paper for results

# Fault coverage: targeted software fault injection

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<b>Fault group</b>	<b>Variant</b>	<b>Undetected</b>	<b>SEI-detected</b>	<b>Crash/other</b>
Control flow	native	9.66%	-	90.34%
	SEI	0.06%	14.70%	85.23%
Data flow	native	44.18%	-	55.82%
	SEI	0.15%	57.55%	42.29%



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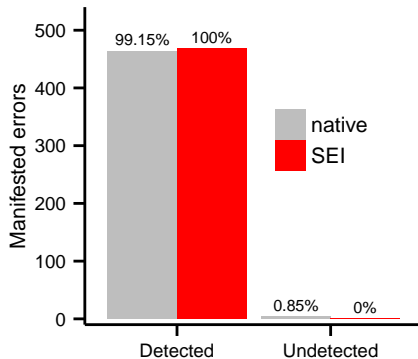


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	SEI	0.15%	57.55%	42.29%

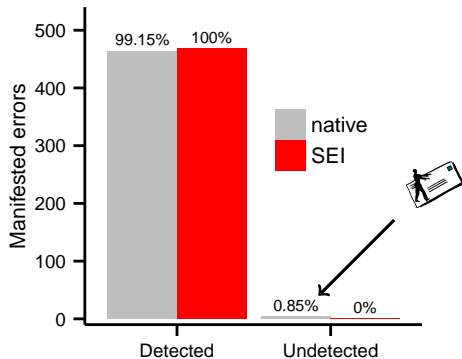
SEI: two orders of magnitude fewer undetected errors

# Fault coverage: CPU undervolting

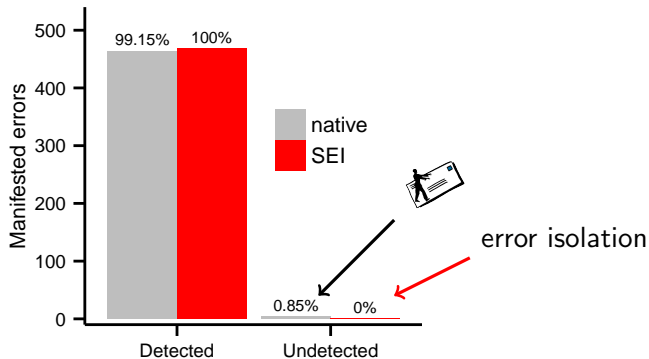
# Fault coverage: CPU undervolting



# Fault coverage: CPU undervolting



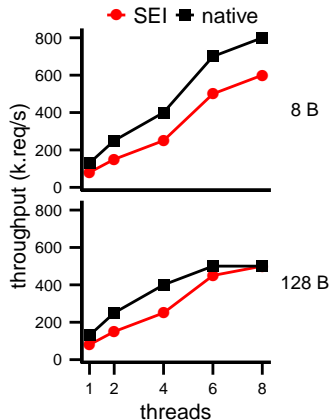
# Fault coverage: CPU undervolting



**SEI: no undetected errors**

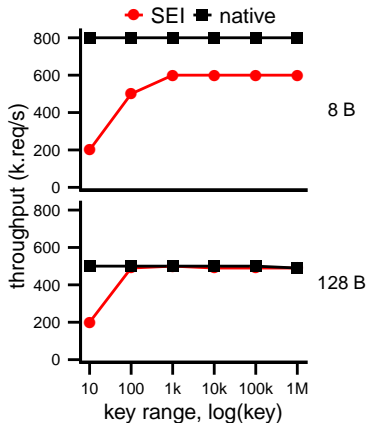
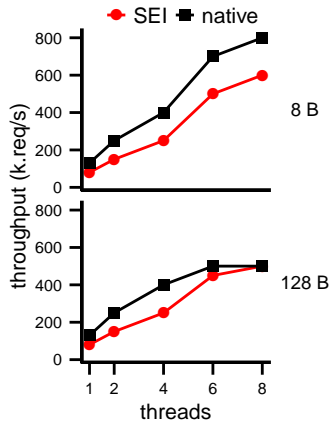
## memcached performance: threads and key range

# memcached performance: threads and key range

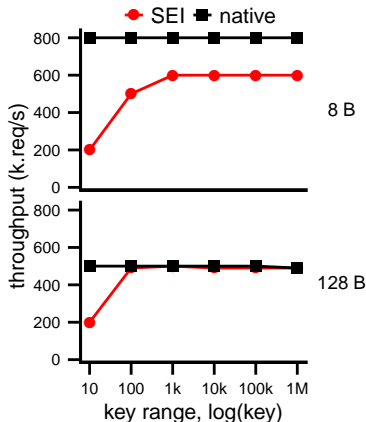
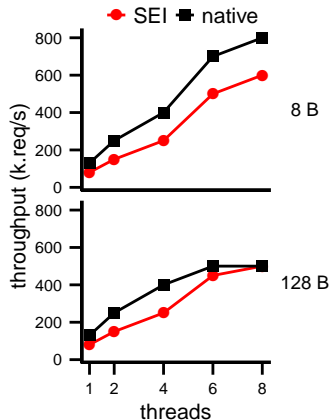




# memcached performance: threads and key range



# memcached performance: threads and key range



SEI: little overhead with  $\geq 128$  B and ranges of  $\geq 100$  keys

- ▶ **Algorithm: Scalable Error Isolation (SEI)**
  - Local and end-to-end
  - Effective against data corruptions
- ▶ **Implementation: libsei**
  - No memory overhead with ECC
  - Little performance overhead with non-CPU intensive applications
  - Implementation is open source

# Thank you! Questions?

Source code and technical report:

<http://bitbucket.org/db7/libsei>