

Scalable Error Isolation for Distributed Systems

Diogo Behrens, Sergei Arnautov, Christof Fetzer (TU Dresden)
Marco Serafini (Qatar Computing Research Institute)
Flavio P. Junqueira (Microsoft Research, Cambridge)

May 6, 2015

Motivation



[Amazon Web Services](#) » [Service Health Dashboard](#) » Amazon S3 Availability Event: July 20, 2008

Amazon S3 Availability Event: July 20, 2008

We wanted to provide some additional detail about the problem we experienced on Sunday, July 20th.

At 8:40am PDT, error rates in all Amazon S3 datacenters began to quickly climb and our alarms went off. By 8:50am PDT, error rates were significantly elevated and very few requests were completing successfully. By 8:55am PDT, we had multiple engineers engaged and investigating the issue. Our alarms pointed at problems processing customer requests in multiple places within the system and across multiple data centers. While we began investigating several possible causes, we tried to restore system health by taking several actions to reduce system load. We reduced system load in several stages, but it had no impact on restoring system health.

Amazon

Mesa: Geo-Replicated, Near Real-Time, Scalable Data Warehousing

Ashish Gupta, Fan Yang, Jason Govig, Adam Kirsch, Kelvin Chan
Kevin Lai, Shuo Wu, Sandeep Govind Dhoot, Abhilash Rajesh Kumar, Ankur Agiwal
Sanjay Bhansali, Mingsheng Hong, Jamie Cameron, Masood Siddiqi, David Jones
Jeff Shute, Andrey Gubarev, Shivakumar Venkataraman, Divyakant Agrawal
Google, Inc.

ABSTRACT

Mesa is a highly scalable analytic data warehousing system that stores critical measurement data related to Google's Internet advertising business. Mesa is designed to satisfy

ness critical nature of this data result in unique technical and operational challenges for processing, storing, and querying. The requirements for such a data store are:

Amazon

Mesa: Geo-Replicated, Near Real-Time, Scalable Data Warehousing

Ashish Gupta, Fan Yang, Jason Govig, Adam Kirsch, Kelvin Chan
Kevin Lai, Shuo Wu, Sandeep Govind Dhoot, Abhilash Rajesh Kumar, Ankur Agiwal
Sanjay Bhansali, Mingchong Hong, Jamie Cameron, Maseed Siddiqi, David Jones
Jeff Shute, and Anshul Agrawal

ABSTRACT

Mesa is a highly scalable analytic data warehouse that stores critical measurement data for Amazon's Internet advertising business. Mesa

4.4 Mitigating Data Corruption Problems

Mesa uses tens of thousands of machines in the cloud that are administered independently and are shared among many services at Google to host and process data. For any computation, there is a non-negligible probability that faulty hardware or software will cause incorrect data to be generated and/or stored. Simple file level checksums are not sufficient to defend against such events because the corruption can occur transiently in CPU or RAM. At Mesa's scale, these seemingly rare events are common. Guarding against such corruptions is an important goal in Mesa's overall design.

ult in unique technical and
ing, storing, and querying.
store are:

Motivation



Mesa: Geo-Replicated, Near Real-Time, Scalable Data Warehousing

Ashish Gupta, Fan Yang, Jason Govig, Adam Kirsch, Kelvin Chan
Kevin Lai, Shuo Wu, Sandeep Govind Dhoot, Abhilash Rajesh Kumar, Ankur Agiwal
Sanjay Bhansali, Mingchong Hong, Jamie Cameron, Maseed Siddiqi, David Jones
Jeff Shute, Anand Rajaraman, and Anshul Agrawal

ABSTRACT

Mesa is a highly scalable analytic data store that stores critical measurement data for Amazon's Internet advertising business. Mesa

4.4 Mitigating Data Corruption Problems

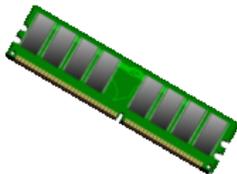
Mesa uses tens of thousands of machines in the cloud that are administered independently and are shared among many services at Google to host and process data. For any computation, there is a non-negligible probability that faulty hardware or software will cause incorrect data to be generated and/or stored. Simple file level checksums are not sufficient to defend against such events because the corruption can occur transiently in CPU or RAM. At Mesa's scale, these seemingly rare events are common. Guarding against such corruptions is an important goal in Mesa's overall design.

ult in unique technical and
ing, storing, and querying.
store are:

CRC for messages!



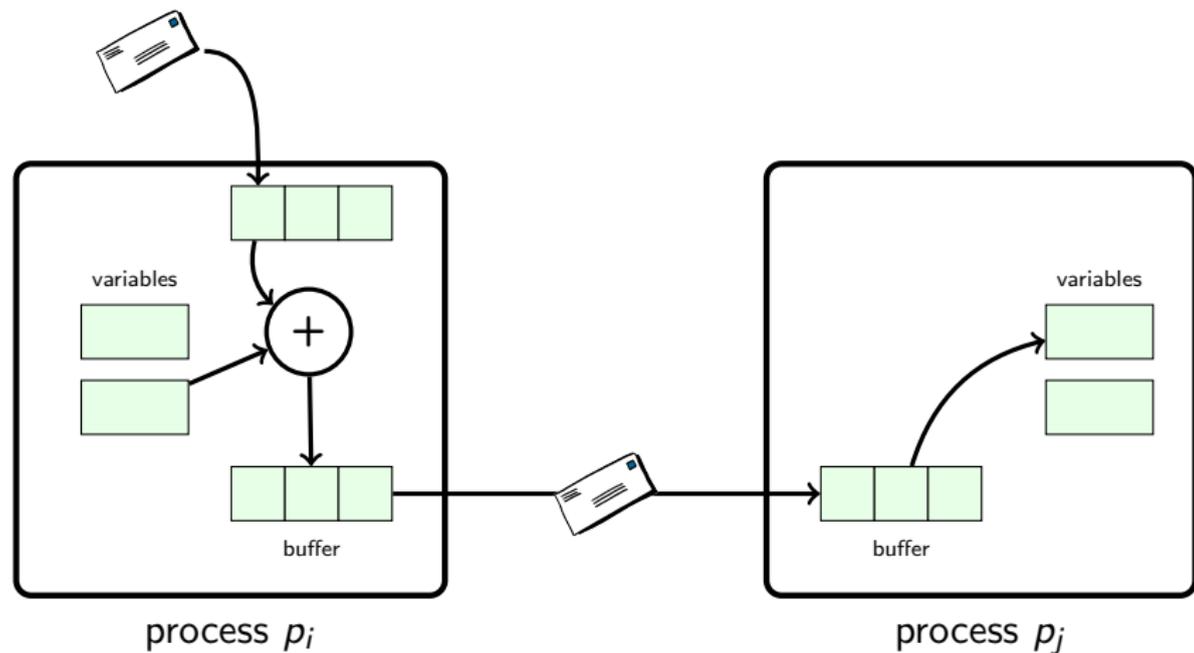
ECC for memory!



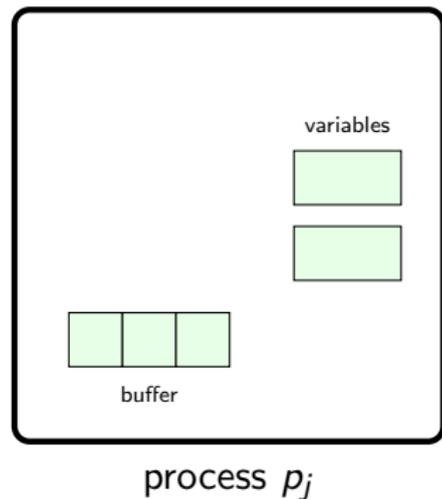
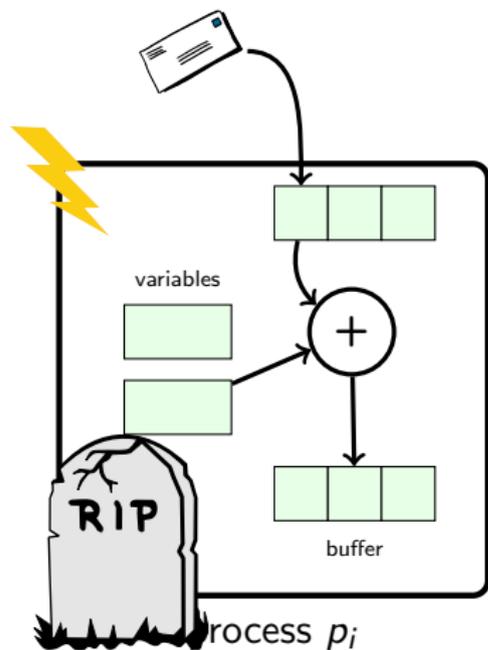
CPU??



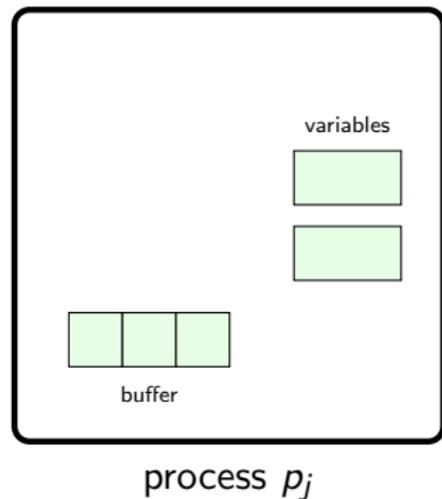
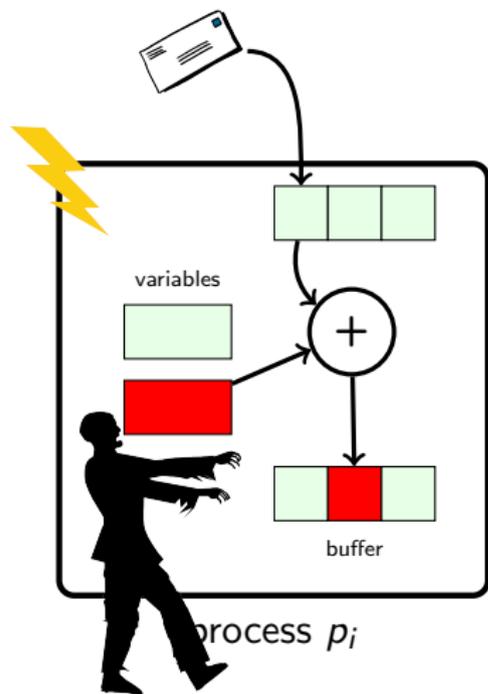
From data corruption to service disruption



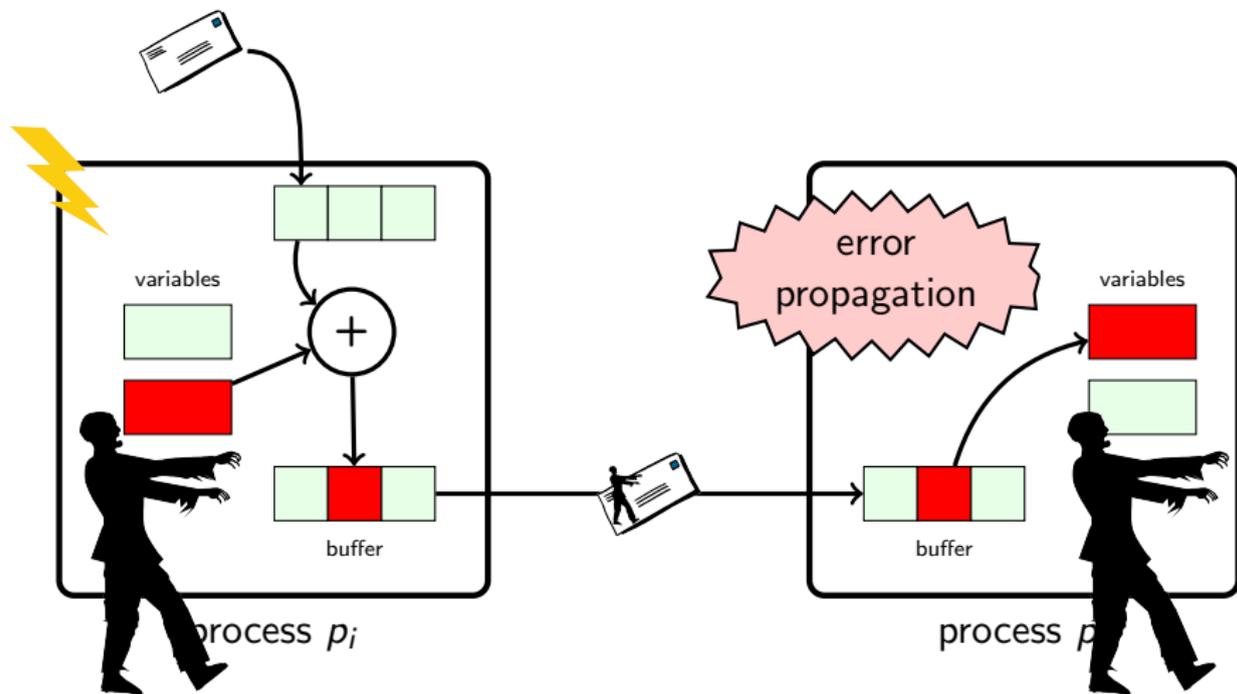
From data corruption to service disruption



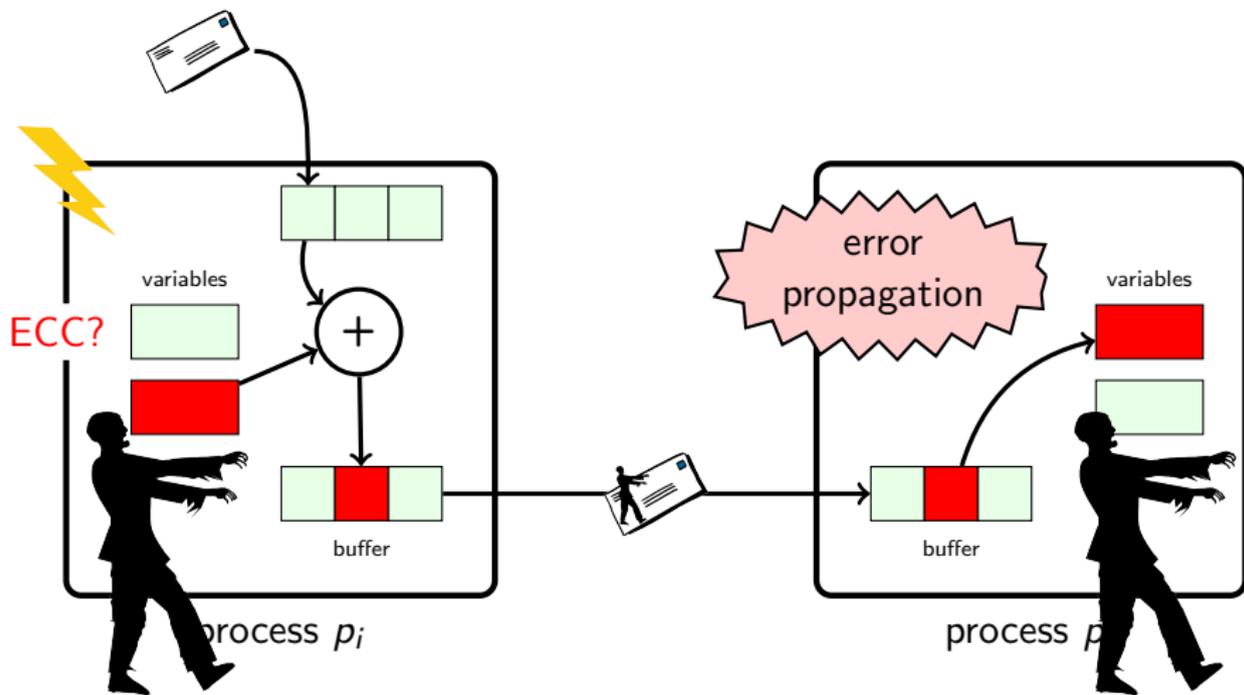
From data corruption to service disruption



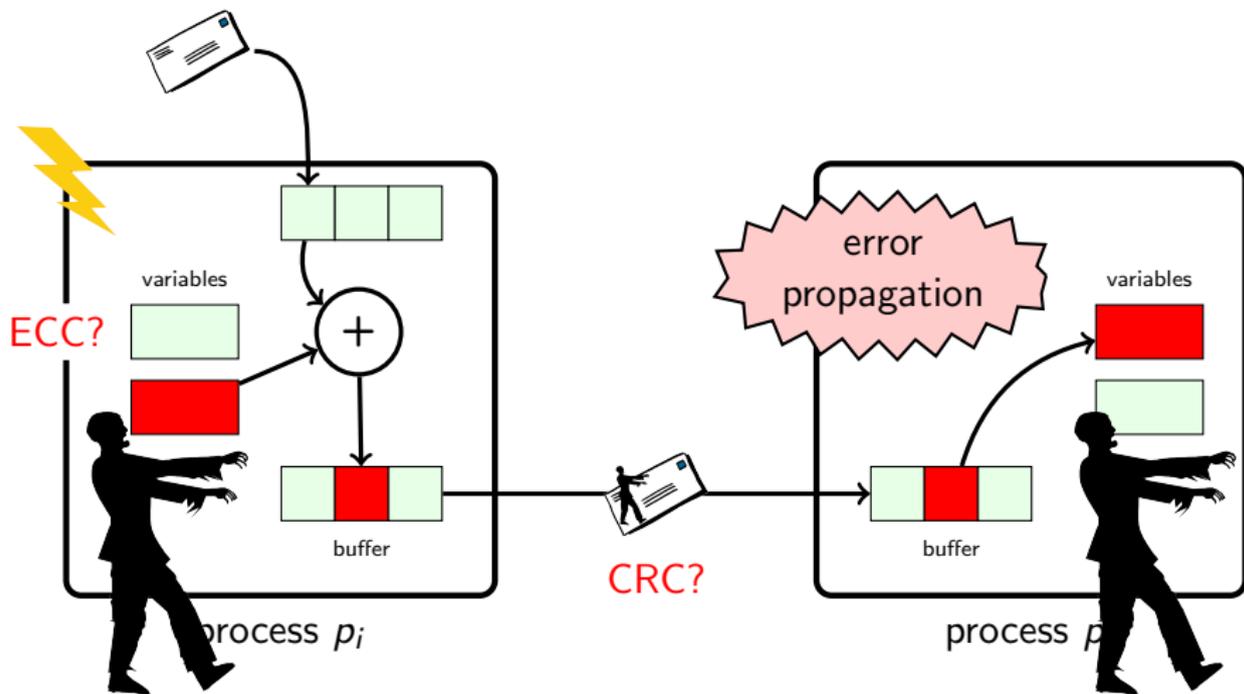
From data corruption to service disruption



From data corruption to service disruption



From data corruption to service disruption



This talk is about. . .

HOW TO KILL A ZOMBIE



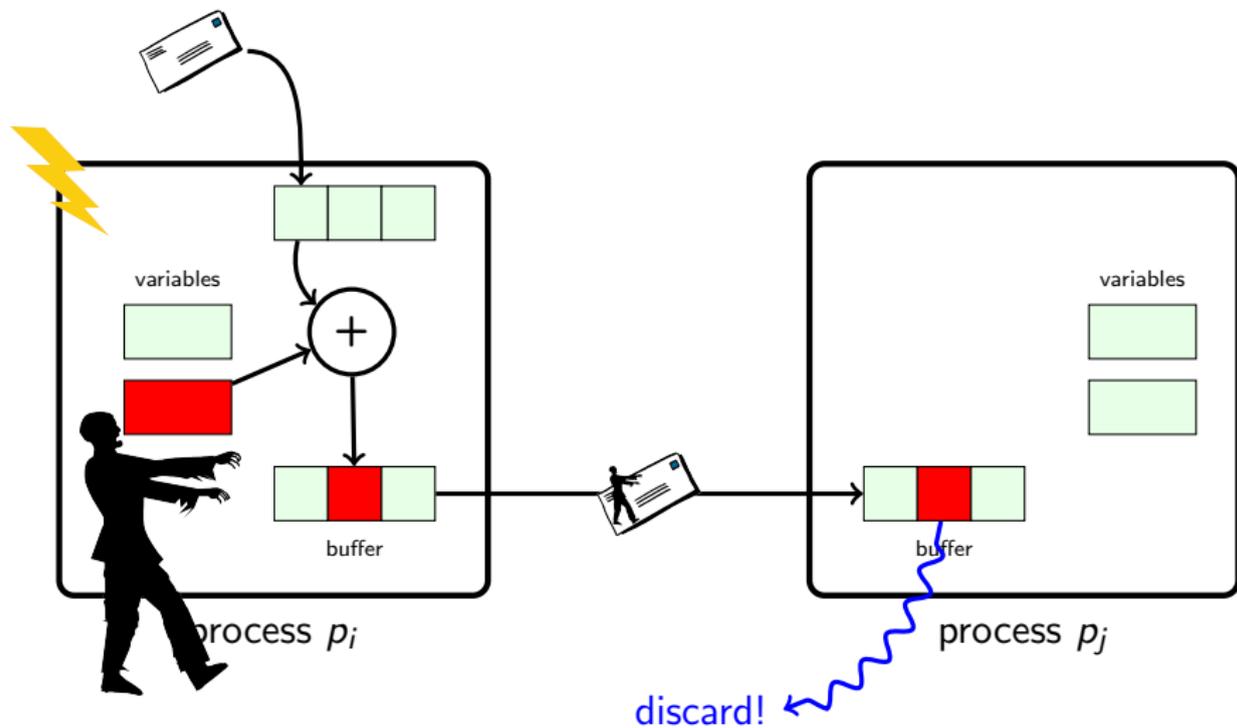
This talk is about...

HOW TO KILL A ZOMBIE

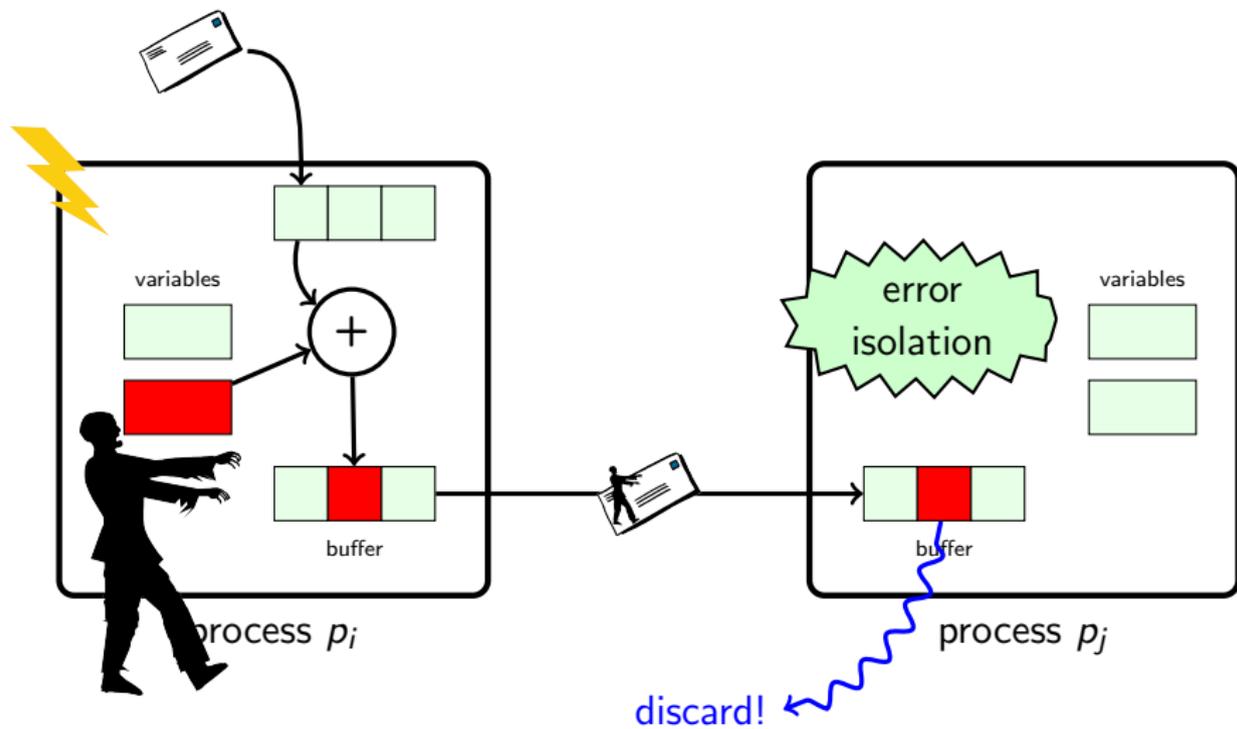
isolate



Goal: error isolation



Goal: error isolation



How to deal with data corruptions?

DIY: Ad hoc software checks

```
while(1) {
    switch(state) {
        case INIT: {
            // create socket, bind and listen
            fd = socket(AF_INET, SOCK_STREAM, 0);
            if (fd < 0) {
                perror("socket");
                return EXIT_FAILURE;
            }

            // this is important, so that if a process restarts, it can
            // getchikly reuse the same port
            int on = 1;
            if (setsockopt(fd, SOL_SOCKET, SO_REUSEADDR, &on, sizeof(on)) < 0) {
                perror("setsockopt");
                return EXIT_FAILURE;
            }

            bzero(&addr, sizeof(addr));
            addr.sin_family = AF_INET;
            addr.sin_addr.s_addr = htonl(INADDR_ANY);
            addr.sin_port = htons(port);

            if (bind(fd, (struct sockaddr*)&addr, sizeof(addr)) < 0) {
                perror("bind");
                return EXIT_FAILURE;
            }

            if (listen(fd, 2) < 0) {
                perror("listen");
                return EXIT_FAILURE;
            }

            // initialize ukv service
            ukv = ukv_init();

            state = ACCT;
            break;
        }

        case RECV: {
            // once a connection is accepted, read the connection
            // until it is closed
            read = recvfrom(cfd, buffer, BUFSIZE, 0, (struct sockaddr*)&caddr, &len);
            if (read <= 0) {
                perror("recvfrom");
                close(cfd);
            }

            state = ACCT;
            break;
        }

        buffer[read] = '\0';
        msg = buffer;

        state = PRDC;
        break;
    }

    case PRDC: {
        r = ukv_recv(ukv, msg);
        if (!r) state = FINI;
        else state = SEND;
        break;
    }

    case SEND: {
        sendto(cfd, r, strlen(r), 0,
              (struct sockaddr*)&caddr, sizeof(caddr));
        ukv_done(ukv, r);
        state = RECV;
        break;
    }
}
}
```



DIY: Ad hoc software checks

```
while(1) {
    switch(state) {
    case INIT: {
        // create socket, bind and listen
        fd = socket(AF_INET, SOCK_STREAM, 0);
        if (fd < 0) {
            perror("socket");
            return EXIT_FAILURE;
        }

        // this is important, so that if a process restarts, it can
        // quickly reuse the same port
        int on = 1;
        if (setsockopt(fd, SOL_SOCKET, SO_REUSEADDR, &on, sizeof(on)) < 0) {
            perror("setsockopt");
            return EXIT_FAILURE;
        }

        bzero(&addr, sizeof(addr));
        addr.sin_family = AF_INET;
        addr.sin_addr.s_addr = htonl(INADDR_ANY);
        addr.sin_port = htons(port);

        if (bind(fd, (struct sockaddr*)&addr, sizeof(addr)) < 0) {
            perror("bind");
            return EXIT_FAILURE;
        }

        if (listen(fd, 2) < 0) {
            perror("listen");
            return EXIT_FAILURE;
        }

        // initialize ukv service
        ukv = ukv_init();
        state = ACCT;
        break;
    }
    case RECV: {
        // once a connection is accepted, read the connection
        // until it is closed
        read = recvfrom(cfd, buffer, BUFSIZE, 0, (struct sockaddr*)&caddr, &len);
        if (read <= 0) {
            perror("recvfrom");
            close(cfd);
            state = ACCT;
            break;
        }

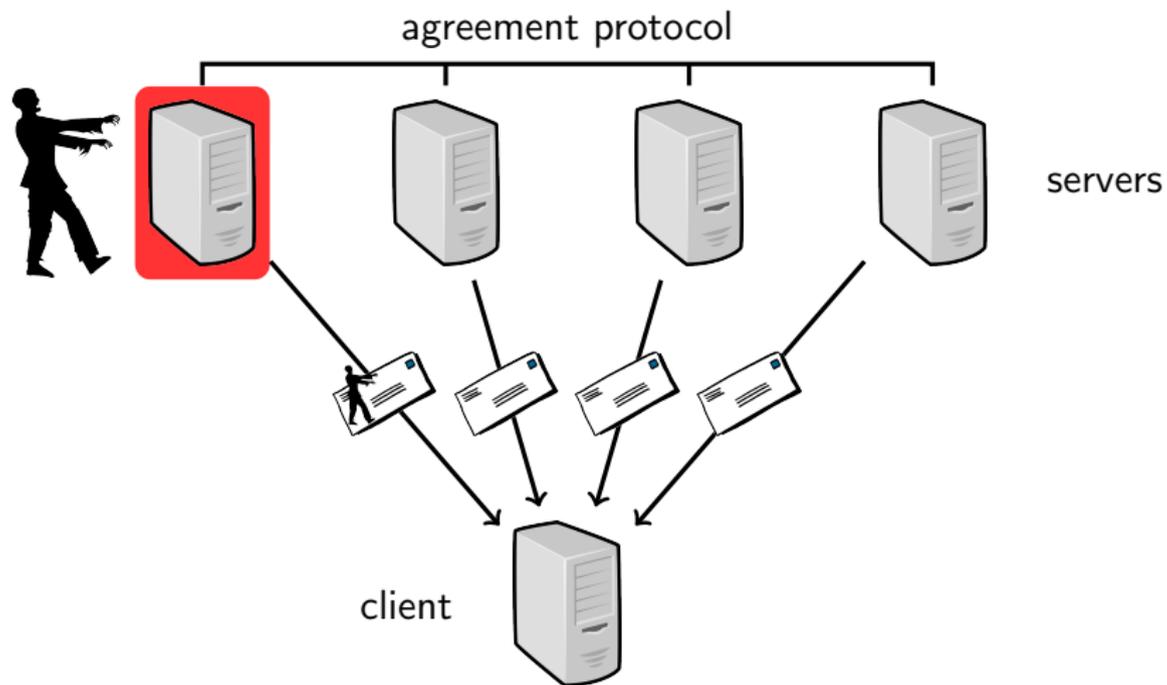
        buffer[read] = '\0';
        msg = buffer;

        state = PROC;
        break;
    }
    case PROC: {
        r = ukv_recv(ukv, msg);
        if (!r) state = FINI;
        else state = SEND;
        break;
    }
    case SEND: {
        sendto(cfd, r, strlen(r), 0,
              (struct sockaddr*)&caddr, sizeof(caddr));
        ukv_done(ukv, r);
        state = RECV;
        break;
    }
    }
}
```

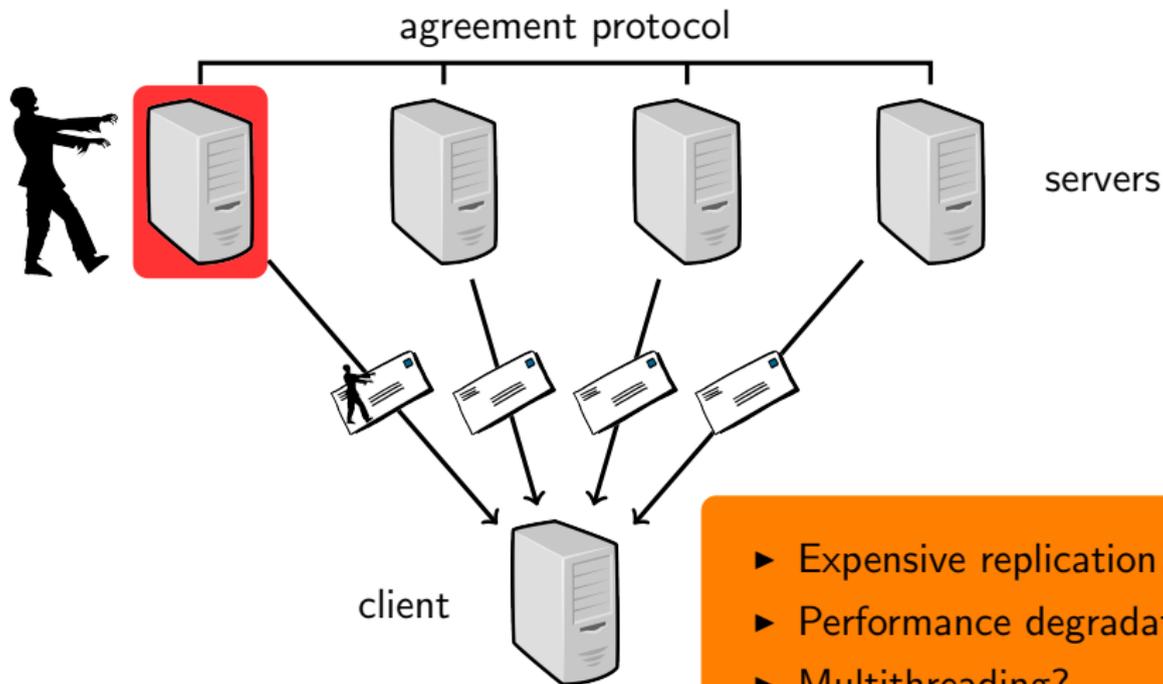
- ▶ Complex, time consuming
- ▶ Which errors to consider?
- ▶ No principled approach



Principled approach: Byzantine fault tolerance



Principled approach: Byzantine fault tolerance



Principled approach: Local hardening

- ▶ **Instruction duplication (SWIFT, CGO'05)**
 - + compiler technique
 - not designed for distributed systems
 - last-mile faults (no error isolation)

- ▶ **Instruction duplication (SWIFT, CGO'05)**

- + compiler technique
- not designed for distributed systems
- last-mile faults (no error isolation)

- ▶ **PASC (ATC'12)**

- + achieves error isolation
- large memory overhead (2x)
- no support for multithreading

Scalable Error Isolation

A new approach



Local hardening

No additional messages exchanged;
Local redundancy in space and time

Scalable Error Isolation (SEI)



Local hardening

No additional messages exchanged;
Local redundancy in space and time



End-to-end

CRCs for communication and **computation**

Scalable Error Isolation (SEI)



Local hardening

No additional messages exchanged;
Local redundancy in space and time



End-to-end

CRCs for communication and **computation**



Formal guarantees

Fault model and correctness proof

Scalability dimensions



Memory scalability

Small footprint (ECC or other error codes)



Memory scalability

Small footprint (ECC or other error codes)



Thread scalability

Support for multithreaded applications

Scalability dimensions



Memory scalability

Small footprint (ECC or other error codes)



Thread scalability

Support for multithreaded applications

`main()`

Codebase scalability

Compiler technique reduces developer work



Overview of SEI

Requirements, fault model, and algorithm



Challenges

Support for multithreaded applications

foo()

Implementation: libsei

Library for C-based programs



Evaluation

Fault coverage and performance overhead



Overview of SEI

Requirements, fault model, and algorithm



Challenges

Support for multithreaded applications

foo()

Implementation: libsei

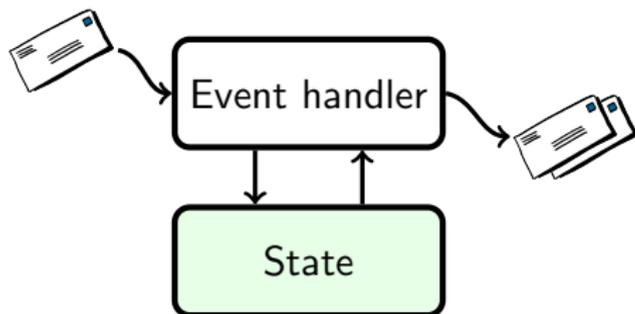
Library for C-based programs



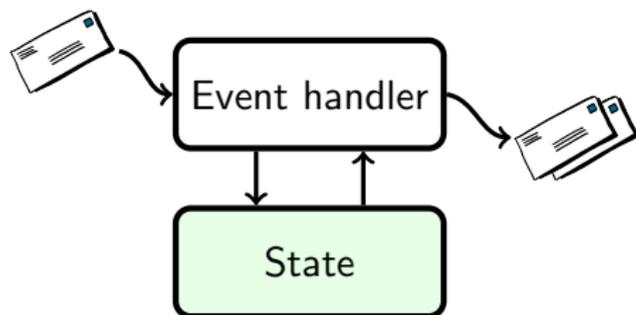
Evaluation

Fault coverage and performance overhead

- ▶ **Event based – message passing**



▶ Event based – message passing

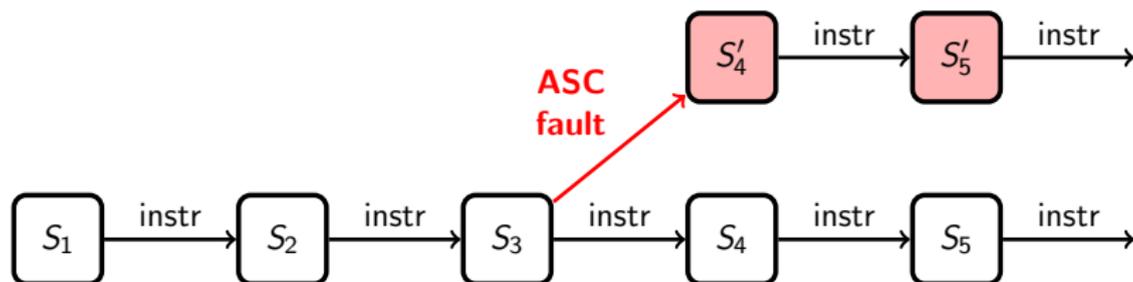


▶ Multithreaded applications

- Critical sections to access shared variables
- Hierarchical locking (consistent order) to avoid deadlocks

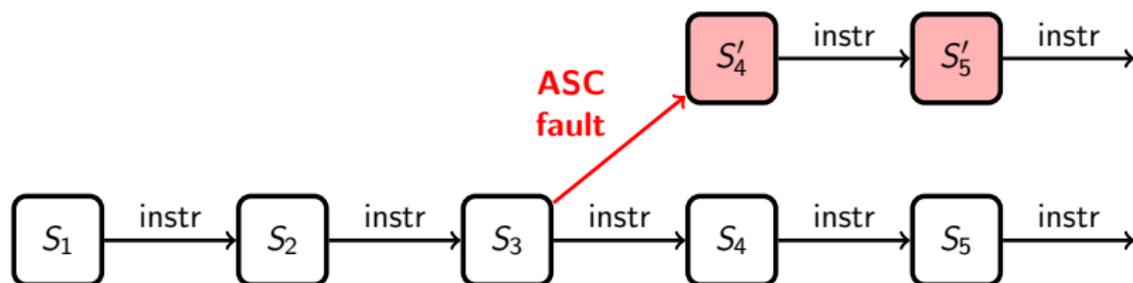
Arbitrary State Corruption (ASC) Model

Faults corrupt any number of variables



Arbitrary State Corruption (ASC) Model

Faults corrupt any number of variables

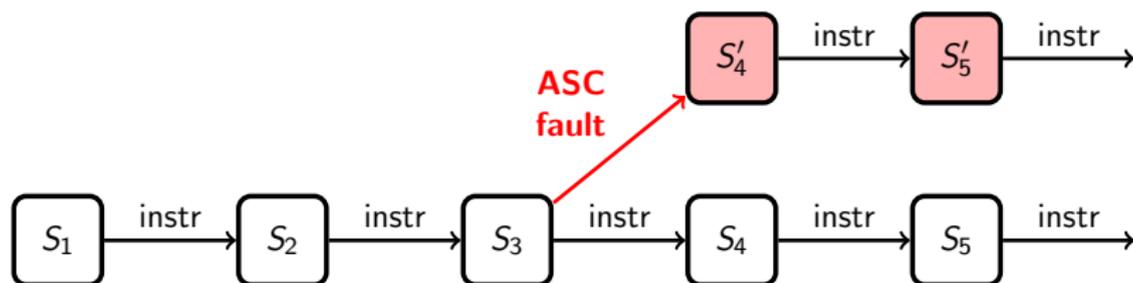


Assumptions:

- ▶ **Fault frequency:**
at most one 1 fault per event handler

Arbitrary State Corruption (ASC) Model

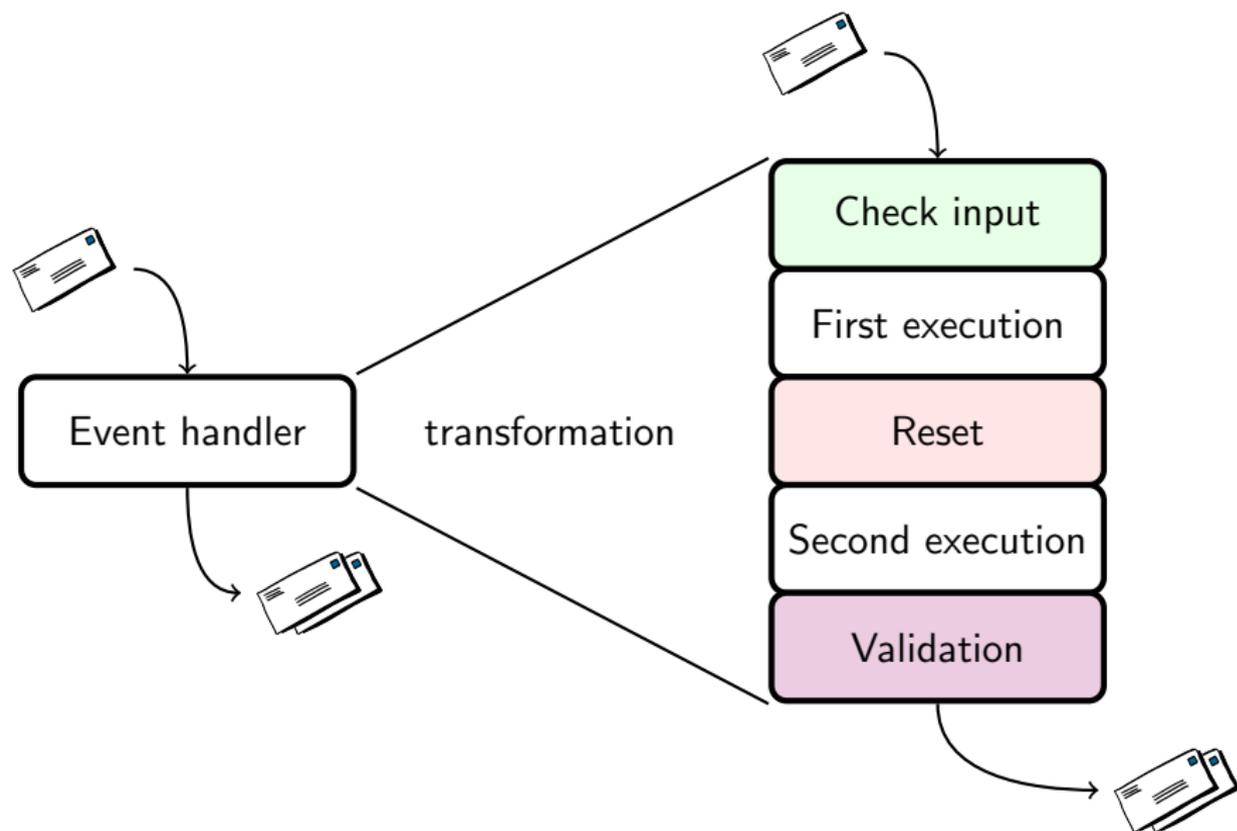
Faults corrupt any number of variables



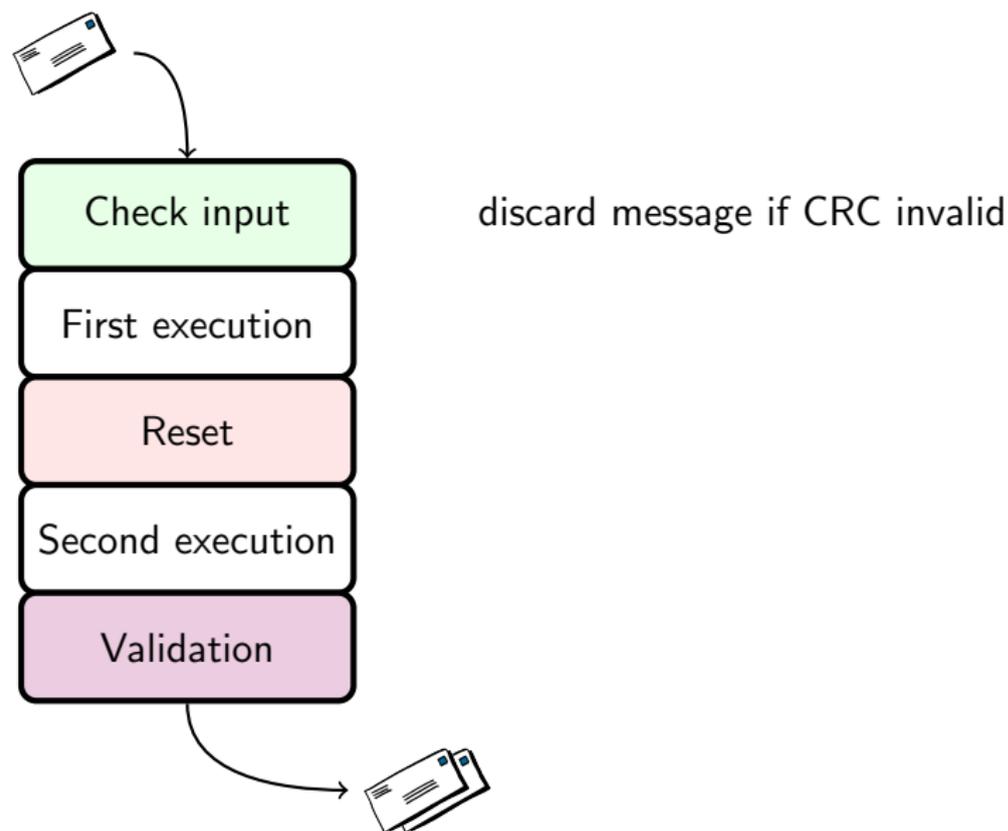
Assumptions:

- ▶ **Fault frequency:**
at most one 1 fault per event handler
- ▶ **Corruption coverage:**
detection codes work, e.g., ECC, CRC

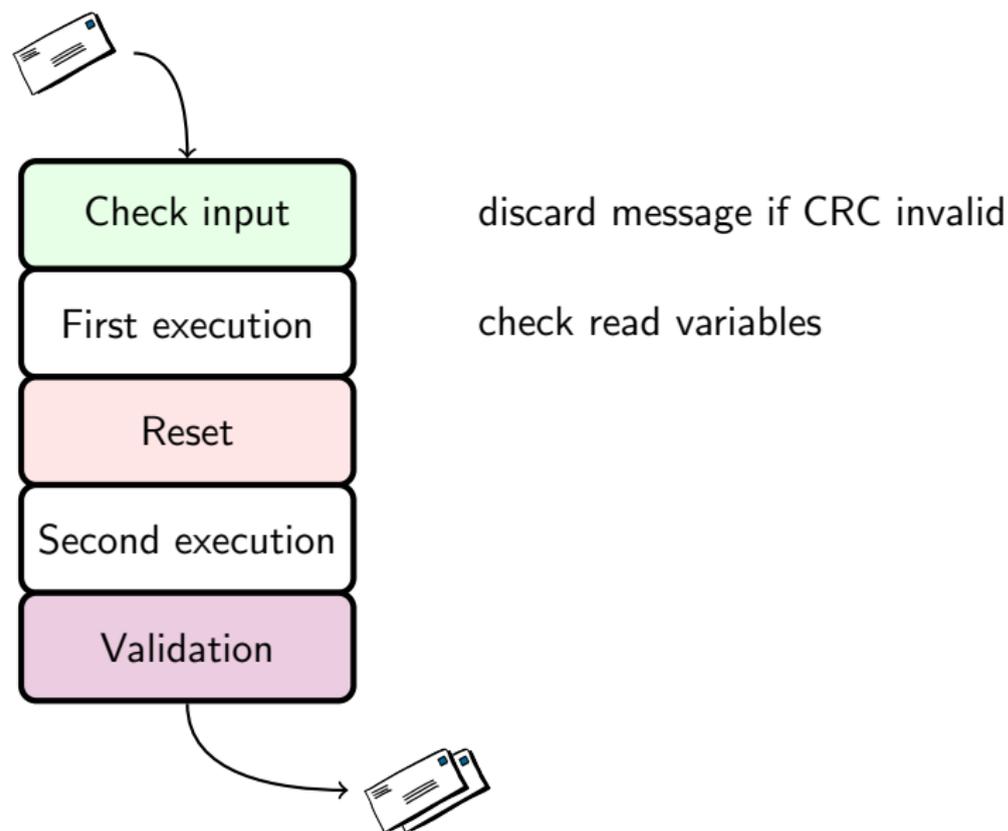
Hardening with SEI



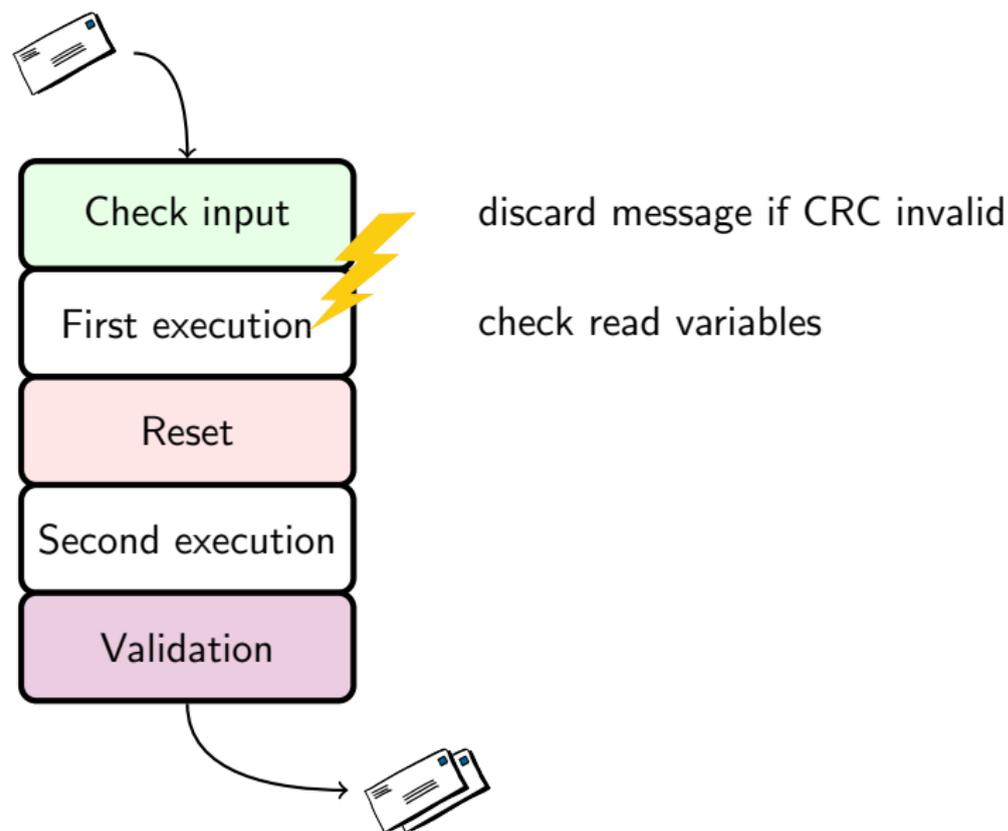
Hardening with SEI



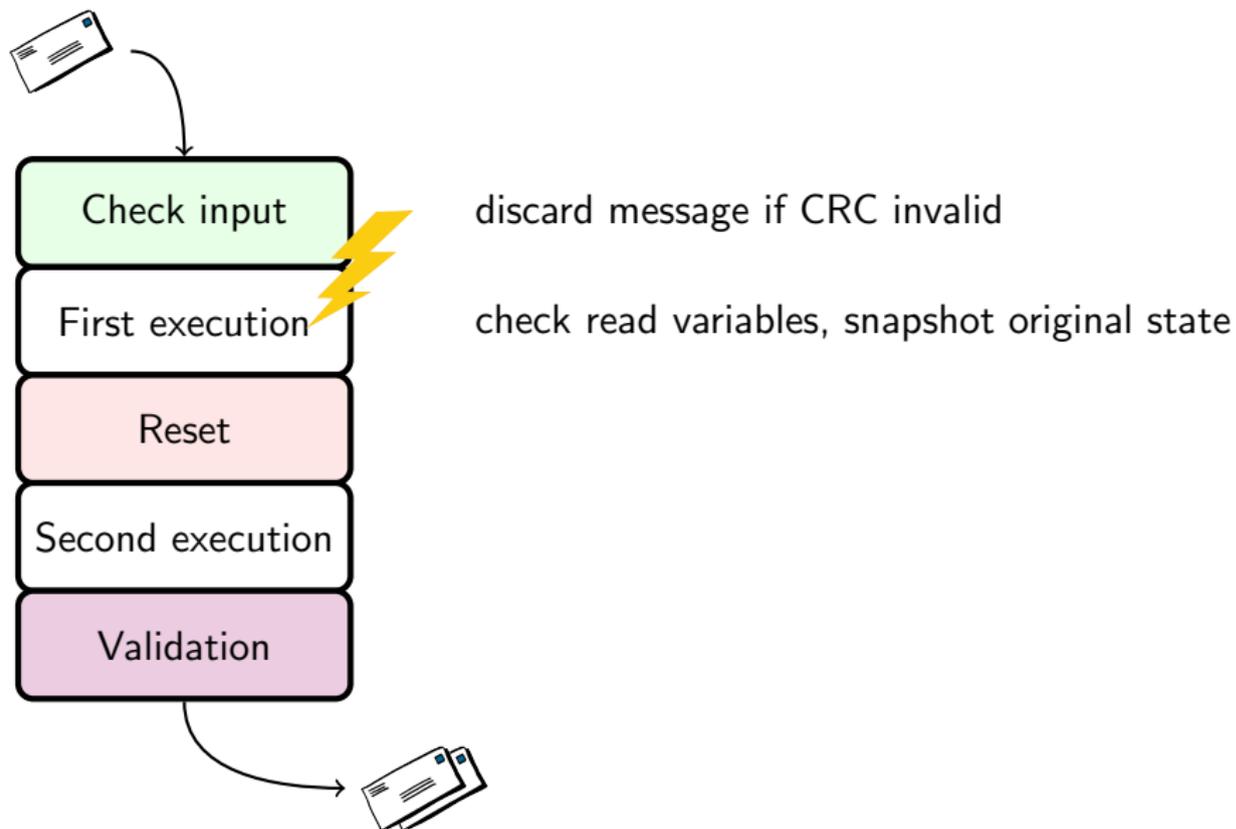
Hardening with SEI



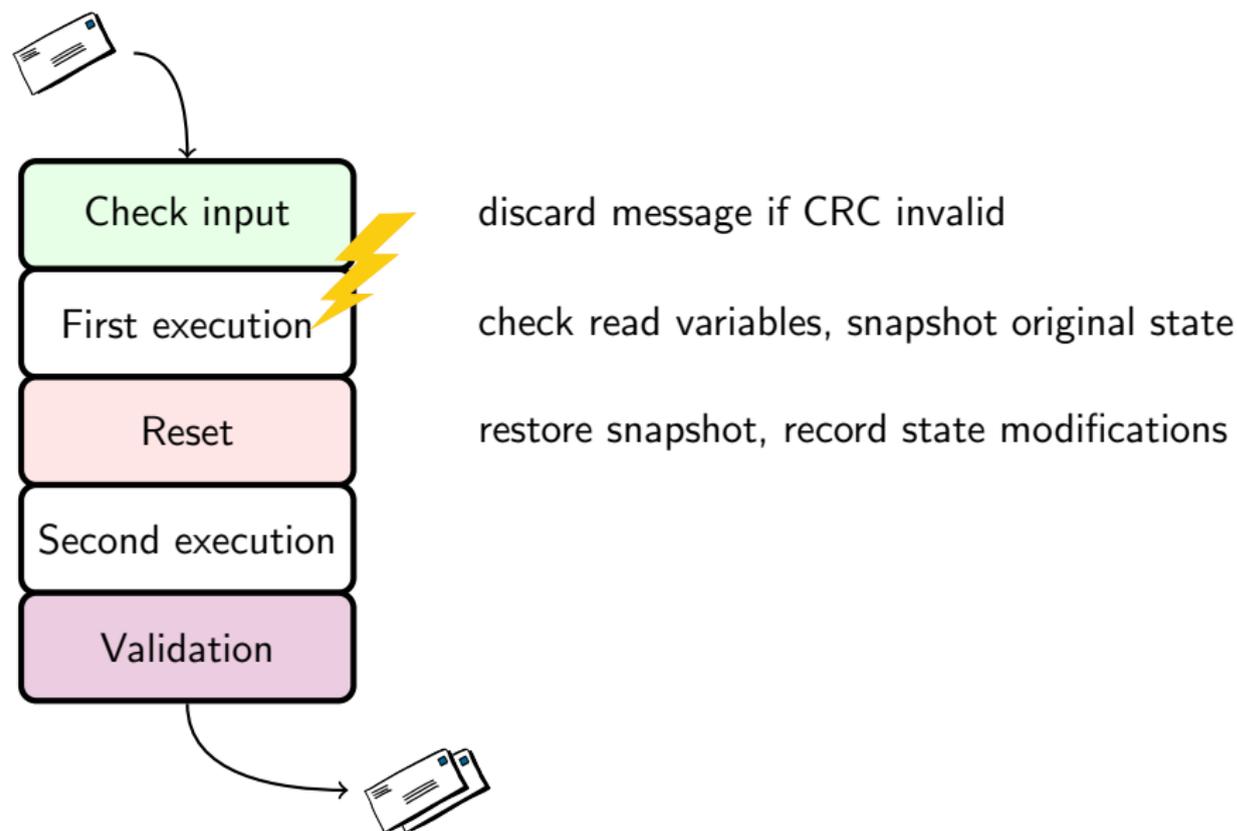
Hardening with SEI



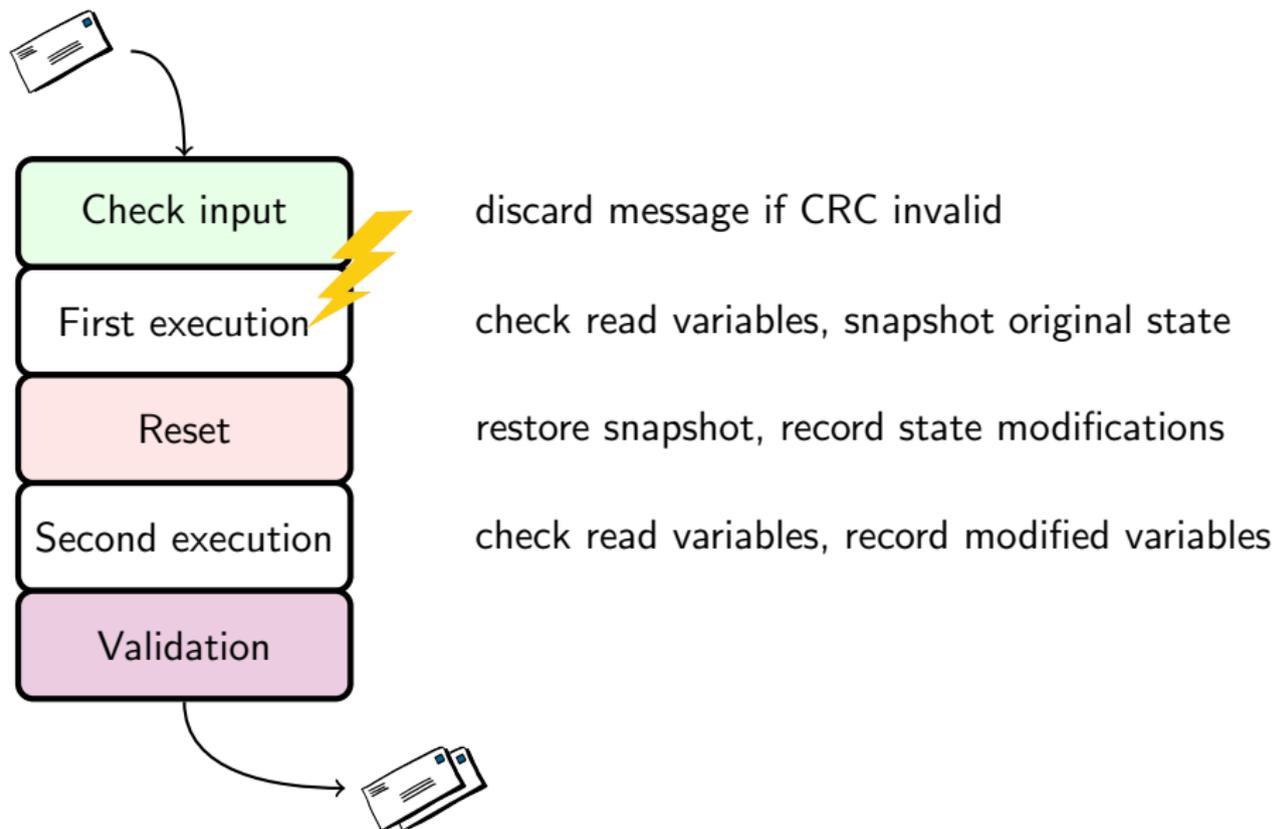
Hardening with SEI



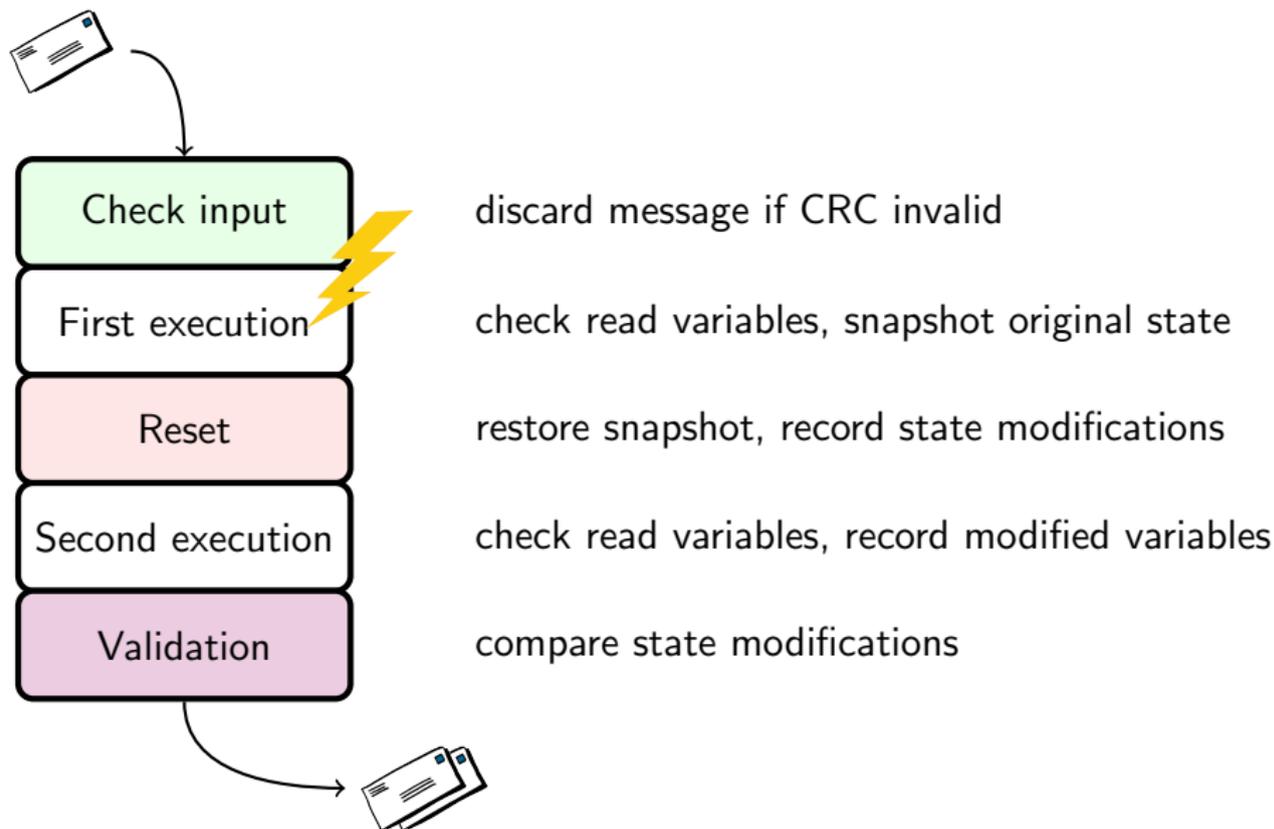
Hardening with SEI



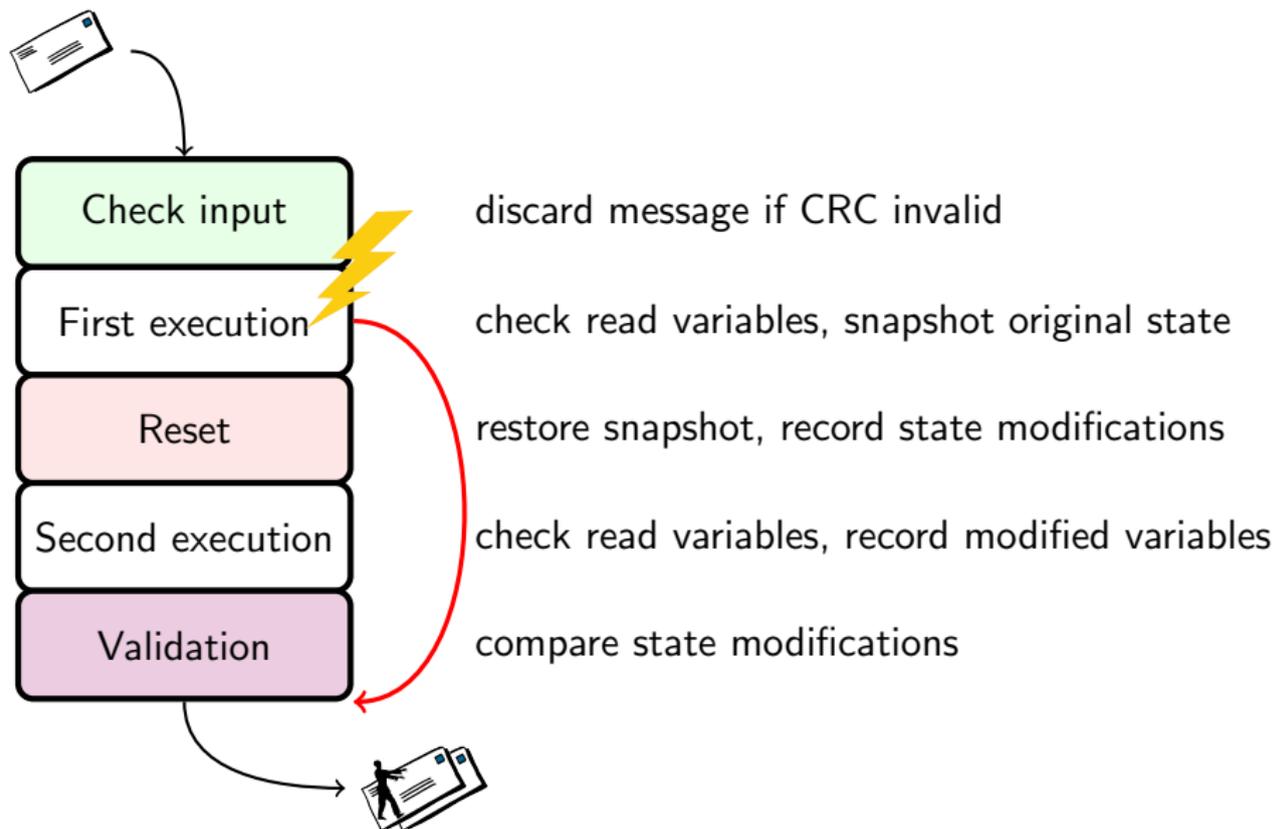
Hardening with SEI



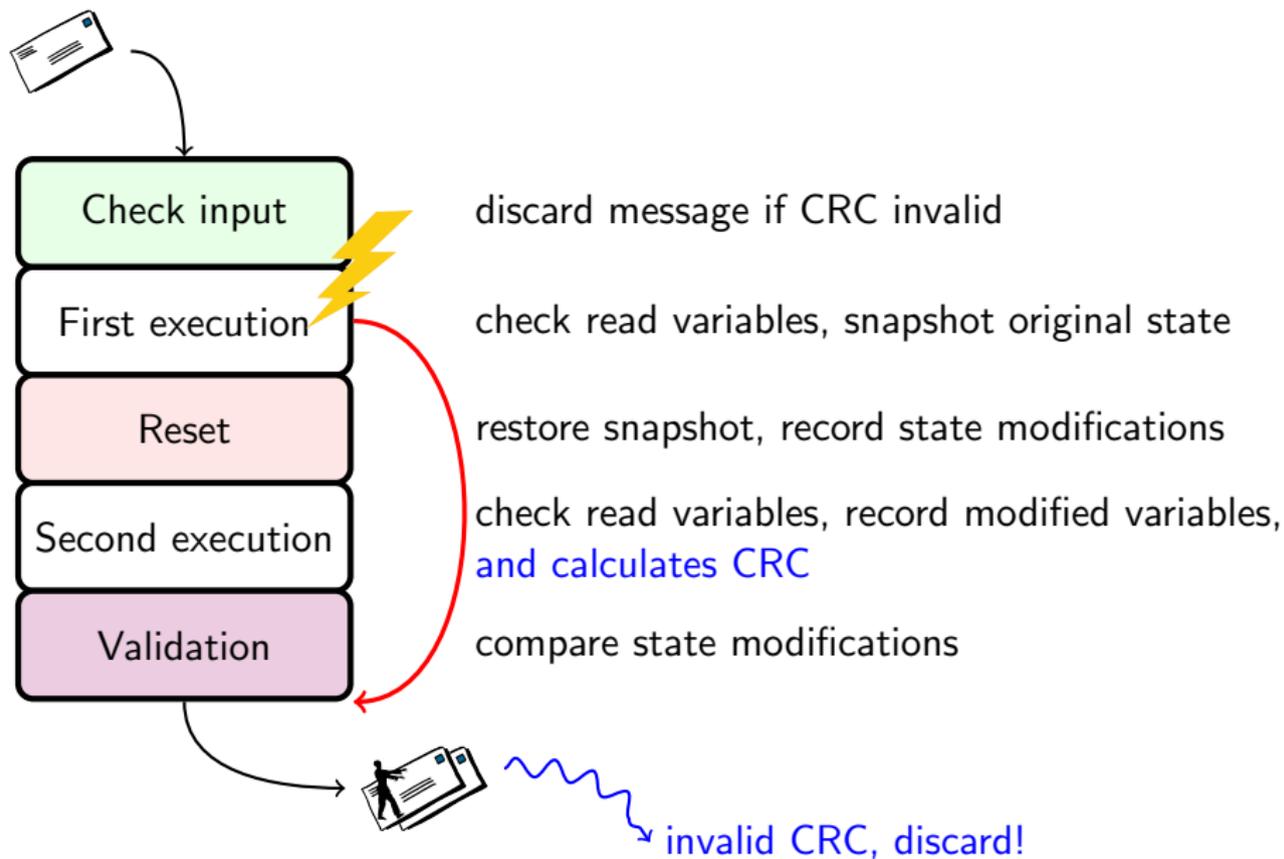
Hardening with SEI



Hardening with SEI



Hardening with SEI





Overview of SEI

Requirements, fault model, and algorithm



Challenges

Support for multithreaded applications

foo()

Implementation: libsei

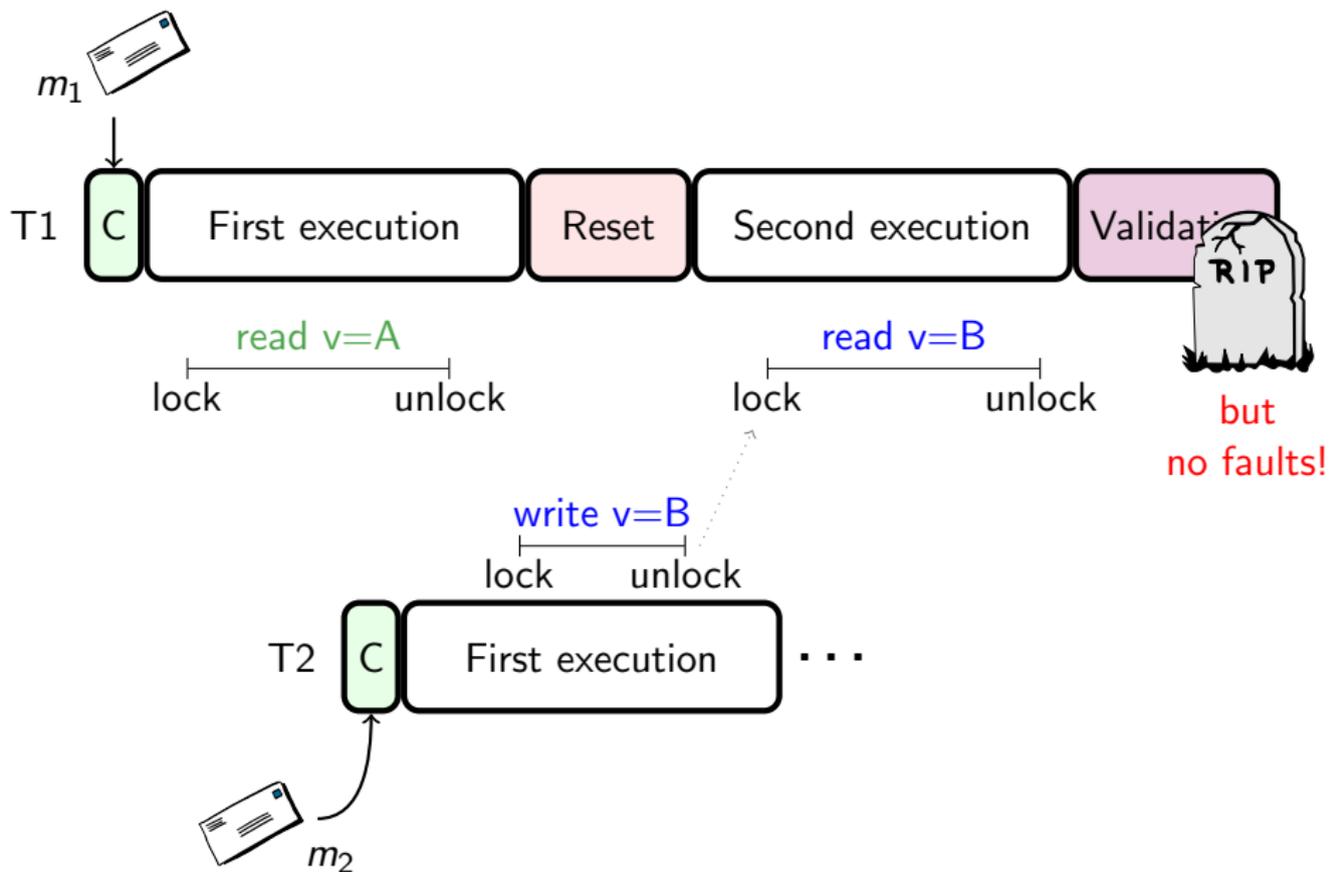
Library for C-based programs



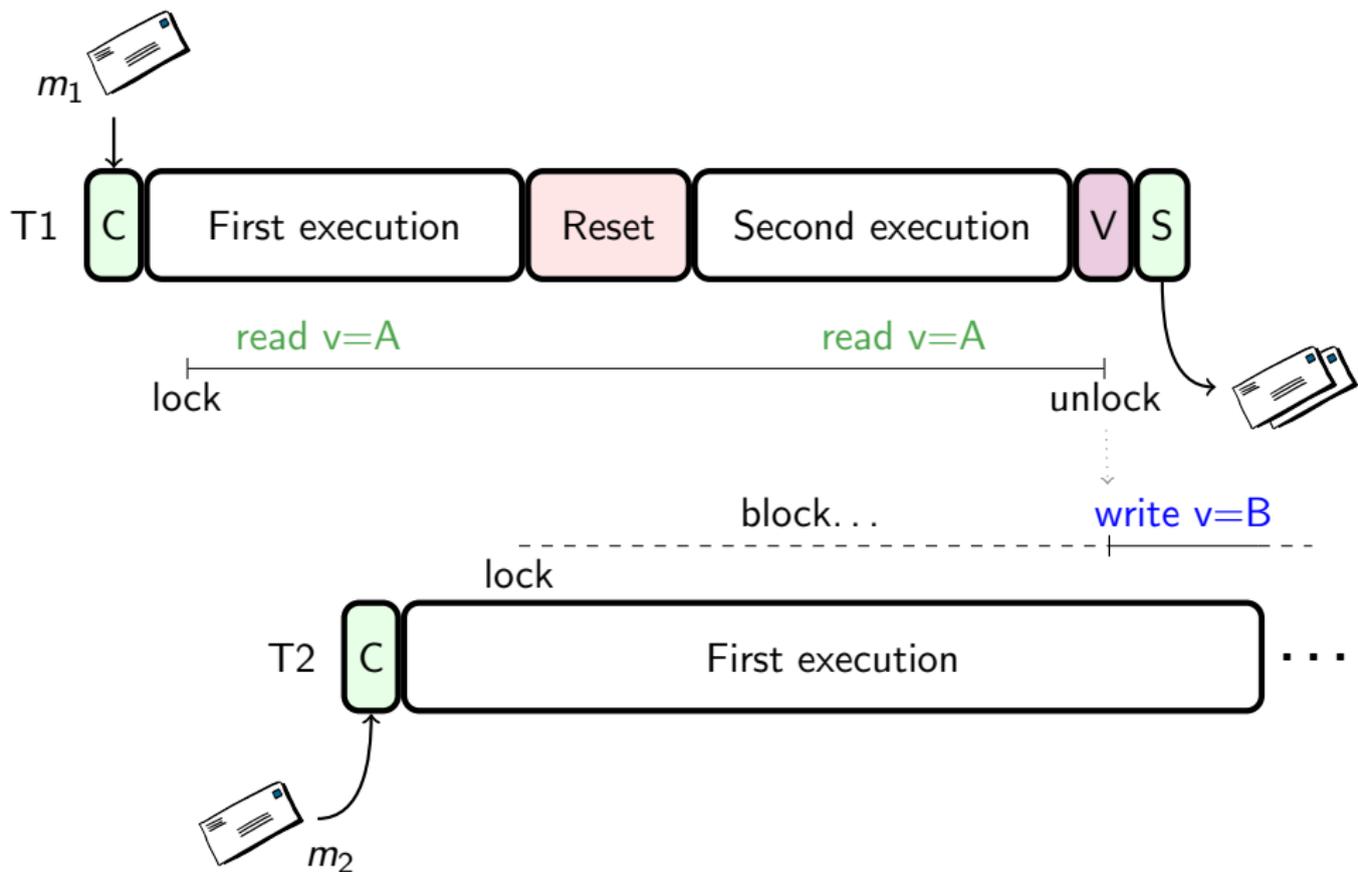
Evaluation

Fault coverage and performance overhead

Deterministic event handling with multithreading



Deterministic event handling with multithreading





Overview of SEI

Requirements, fault model, and algorithm



Challenges

Support for multithreaded applications

foo()

Implementation: libsei

Library for C-based programs



Evaluation

Fault coverage and performance overhead

libsei: SEI implementation in C

bitbucket.org/db7/libsei

```
while(1) {
    ilen = recv_msg(msg, &crc);

    do_something_here(msg);
    omsg = create_message(&olen);

    send_msg(omsg, olen, CRC(omsg, olen));
}
```

- ▶ **Annotate event handler**
with `__begin` and `__end`
- ▶ **Annotate messages**
`__output*` for annotation
`__crc_pop` for next CRC

libsei: SEI implementation in C

bitbucket.org/db7/libsei

```
while(1) {
    ilen = recv_msg(msg, &crc);
    if (__begin(msg, ilen, crc)) {
        do_something_here(msg);
        msg = create_message(&olen);

        __end();          // end of handler
    } else continue; //discard invalid

    send_msg(msg, olen, CRC(msg, olen));
}
```

- ▶ **Annotate event handler**
with `__begin` and `__end`
- ▶ **Annotate messages**
`__output*` for annotation
`__crc_pop` for next CRC

libsei: SEI implementation in C

bitbucket.org/db7/libsei

```
while(1) {
    ilen = recv_msg(msg, &crc);
    if (__begin(msg, ilen, crc)) {
        do_something_here(msg);
        msg = create_message(&olen);
        __output_append(msg, olen);
        __output_done();
        __end();          // end of handler
    } else continue; //discard invalid

    send_msg(msg, olen, CRC(msg, olen));
}
```

- ▶ **Annotate event handler**
with `__begin` and `__end`
- ▶ **Annotate messages**
`__output*` for annotation
`__crc_pop` for next CRC

libsei: SEI implementation in C

bitbucket.org/db7/libsei

```
while(1) {
    ilen = recv_msg(msg, &crc);
    if (__begin(msg, ilen, crc)) {
        do_something_here(msg);
        msg = create_message(&olen);
        __output_append(msg, olen);
        __output_done();
        __end();          // end of handler
    } else continue; //discard invalid

    send_msg(msg, olen, __crc_pop());
}
```

- ▶ **Annotate event handler**
with `__begin` and `__end`
- ▶ **Annotate messages**
`__output*` for annotation
`__crc_pop` for next CRC

libsei: SEI implementation in C

bitbucket.org/db7/libsei

```
while(1) {
    ilen = recv_msg(msg, &crc);
    if (__begin(msg, ilen, crc)) {
        do_something_here(msg);
        msg = create_message(&olen);
        __output_append(msg, olen);
        __output_done();
        __end();          // end of handler
    } else continue; //discard invalid

    send_msg(msg, olen, __crc_pop());
}
```

- ▶ **Annotate event handler**
with `__begin` and `__end`
- ▶ **Annotate messages**
`__output*` for annotation
`__crc_pop` for next CRC
- ▶ **Compile with GCC \geq 4.7**
state updates within handler
instrumented with TM pass

libsei: SEI implementation in C

bitbucket.org/db7/libsei

```
while(1) {
    ilen = recv_msg(msg, &crc);
    if (__begin(msg, ilen, crc)) {
        do_something_here(msg);
        msg = create_message(&olen);
        __output_append(msg, olen);
        __output_done();
        __end();          // end of handler
    } else continue; //discard invalid

    send_msg(msg, olen, __crc_pop());
}
```

- ▶ **Annotate event handler**
with `__begin` and `__end`
- ▶ **Annotate messages**
`__output*` for annotation
`__crc_pop` for next CRC
- ▶ **Compile with GCC \geq 4.7**
state updates within handler
instrumented with TM pass
- ▶ **libsei does the rest**
 - executes handler twice
 - calculates CRCs
 - validates state updates



Overview of SEI

Requirements, fault model, and algorithm



Challenges

Support for multithreaded applications

foo()

Implementation: libsei

Library for C-based programs



Evaluation

Fault coverage and performance overhead

- ▶ memcached
 - Key-value store
 - Widely used as cache for databases
 - Internally, a huge hash table with eviction queues
 - Multithreaded

- ▶ memcached
 - Key-value store
 - Widely used as cache for databases
 - Internally, a huge hash table with eviction queues
 - Multithreaded

- ▶ Deadwood
 - DNS recursive server
 - Single-threaded
 - See paper for results

Fault coverage: targeted software fault injection

Fault coverage: targeted software fault injection

Fault group	Variant	Undetected	SEI-detected	Crash/other
Control flow	native	9.66%	-	90.34%
	SEI	0.06%	14.70%	85.23%
Data flow	native	44.18%	-	55.82%
	SEI	0.15%	57.55%	42.29%

Fault coverage: targeted software fault injection



Fault group	Variant	Undetected	SEI-detected	Crash/other
Control flow	native	9.66%	-	90.34%
	SEI	0.06%	14.70%	85.23%
Data flow	native	44.18%	-	55.82%
	SEI	0.15%	57.55%	42.29%

Fault coverage: targeted software fault injection

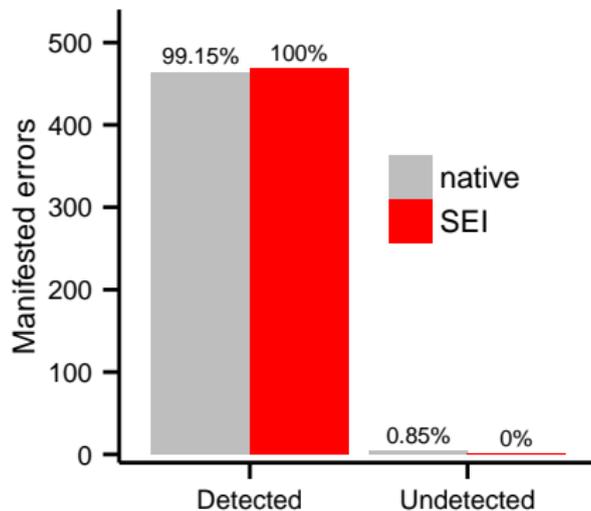


Fault group	Variant	Undetected	SEI-detected	Crash/other
Control flow	native	9.66%	-	90.34%
	SEI	0.06%	14.70%	85.23%
Data flow	native	44.18%	-	55.82%
	SEI	0.15%	57.55%	42.29%

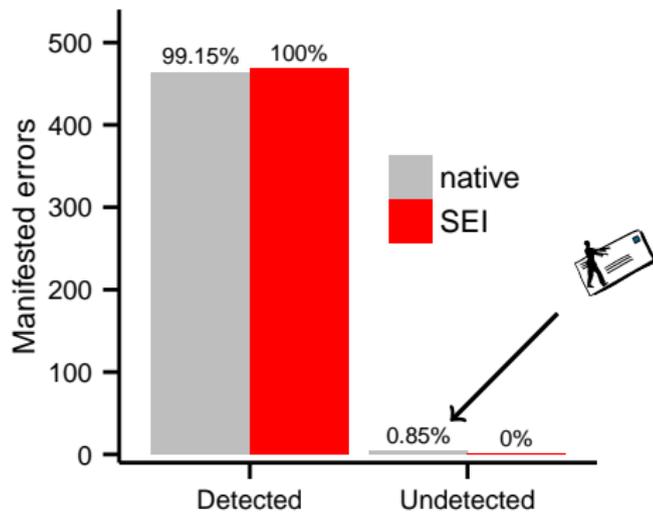
SEI: two orders of magnitude fewer undetected errors

Fault coverage: CPU undervolting

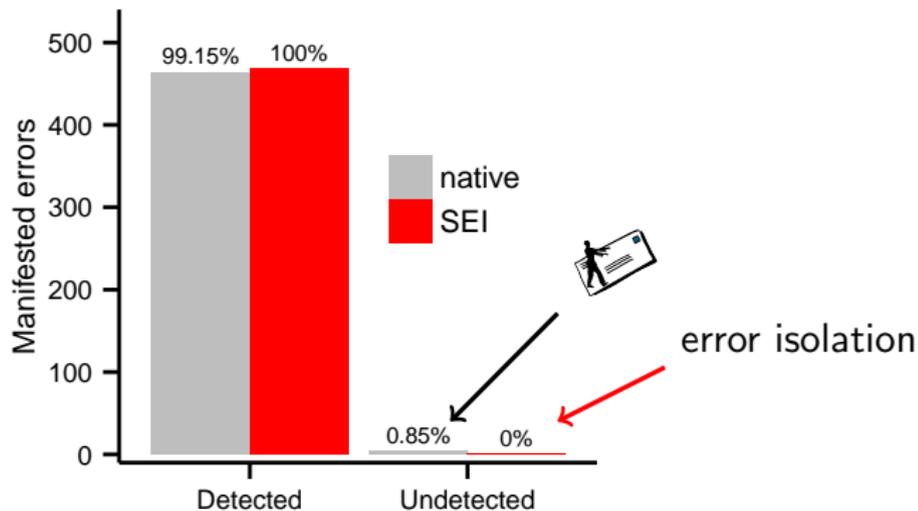
Fault coverage: CPU undervolting



Fault coverage: CPU undervolting



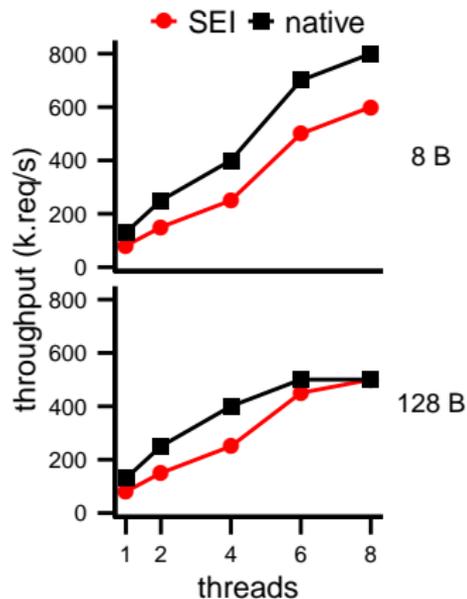
Fault coverage: CPU undervolting



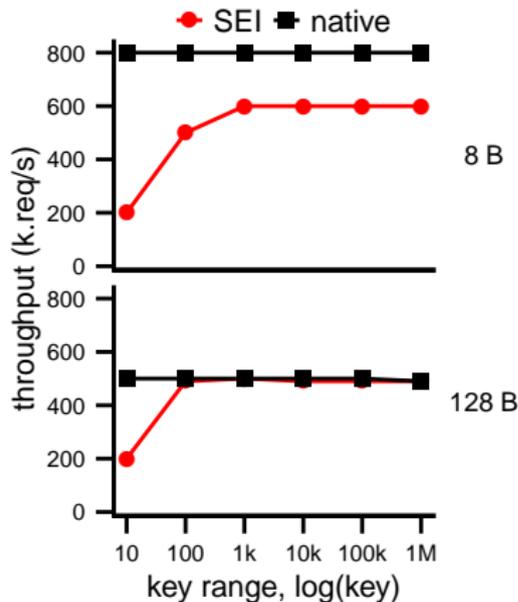
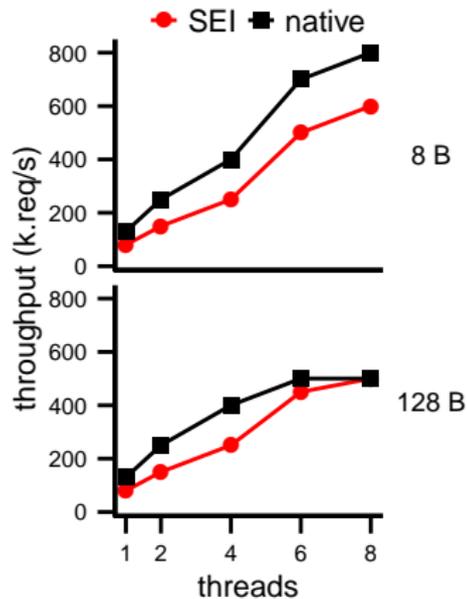
SEI: no undetected errors

memcached performance: threads and key range

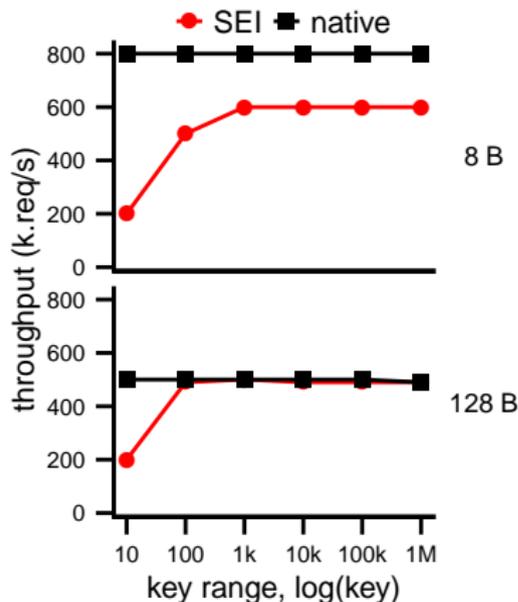
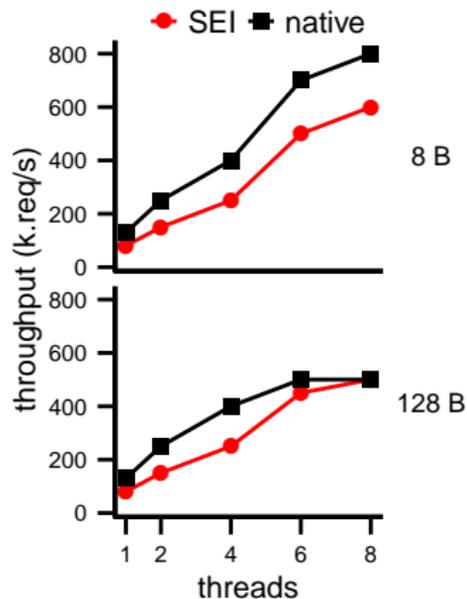
memcached performance: threads and key range



memcached performance: threads and key range



memcached performance: threads and key range



SEI: little overhead with ≥ 128 B and ranges of ≥ 100 keys

- ▶ **Algorithm: Scalable Error Isolation (SEI)**
 - Local and end-to-end
 - Effective against data corruptions
- ▶ **Implementation: libsei**
 - No memory overhead with ECC
 - Little performance overhead with non-CPU intensive applications
 - Implementation is open source

Thank you! Questions?

Source code and technical report:

<http://bitbucket.org/db7/libsei>