**Introduction**

**Motivation:**
- Storage is one of the common problematic subsystems in a cloud environment.
- Need to make upper layers resilient to storage failures.
- Need a framework to study the impact of disk failures on a large testbed.

**PRObE:**
- Aims to build a large testbed for systems research with such a framework.

**Goals:**
- Lets users of Emulab testbed simulate various disk errors.
- Provide a scriptable and repeatable means to inject failures.
- Compress real disk-failure timelines into shorter timelines for experimentation.
- Replay I/O traces from real systems to model real disk failures.
- Try it out by signing up for a free account at http://emulab.net/

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**System Architecture**

1. **Device Mapper on Linux**
   - Maps virtual disks onto real storage disks
   - Provides various disk target types
   - Target types can be used to simulate disk failures
   - Ability to dynamically change disk target type

2. **Event System/NS on Emulab**
   - Ability to schedule/trigger disk faults at later point in time
   - NS syntax to script disk failure experiments

3. **Disk-Agent for Emulab**
   - Interfaces libdevmapper and Event system
   - Listens to disk events and invokes various disk failure conditions

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**Example**

Typical NS TCL script to specify experiments on Emulab

```tcl
set nodeA [Ns new node]
set disk0 [NodeA disk-agent -type "linear" -mountpoint "/mnt"]
Ns at 0 "$disk0 run"
set disk1 [NodeA disk-agent -type "delay" -mountpoint "/mnt" -parameters "100"]
Ns at 22 "$disk1 run"
set disk2 [NodeA disk-agent -type "linear" -mountpoint "/mnt"]
Ns at 72 "$disk2 run"
```

The above NS script allocates a physical node, specifies a disk which starts out being a good disk and 22 seconds later, we turn it into a slow disk by delaying the I/O’s by 100ms. And then, at 72nd second we turn it back into a normal disk.

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