#### Lifetime Management of Flash-Based SSDs Using Recovery-Aware Dynamic Throttling

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10th USENIX Conference on File and Storage Technologies February 17, 2012

### Flash-based SSDs in Enterprise

 Flash-based SSDs (Solid-State Drives) are becoming an attractive storage solution for enterprise systems.





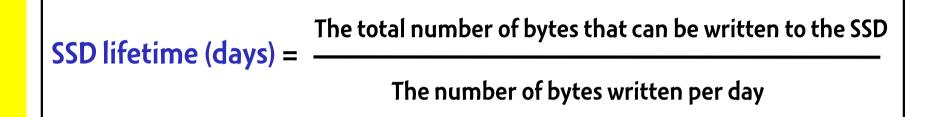
<PCIe-based Flash Array>

<MLC-based SSD>

 The limited lifetime caused by poor write endurance is a main barrier for wider adoption of SSDs in the enterprise market.

### SSD Lifetime

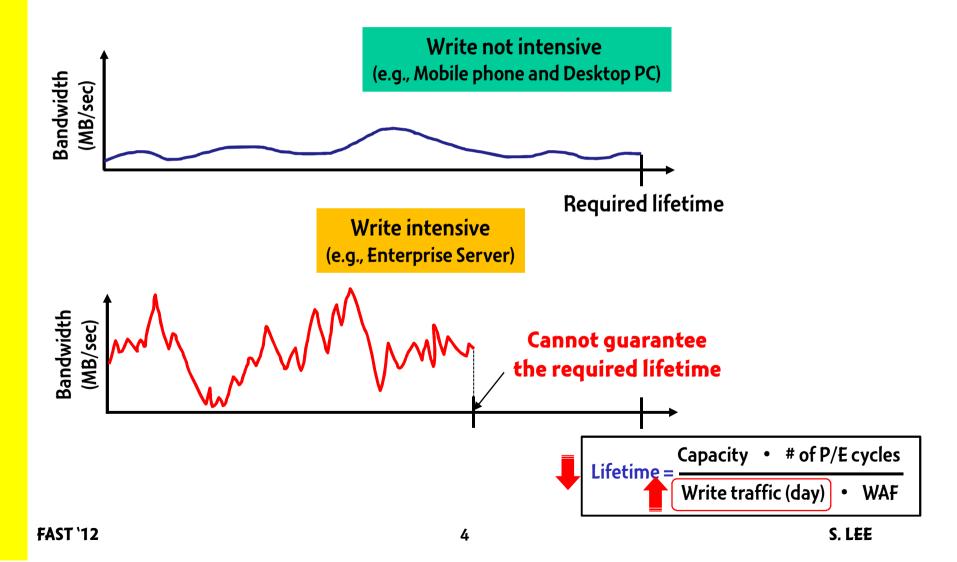
#### The SSD lifetime is determined by two main factors:



- (1) SSD capacity
- (2) Number of program/erase (P/E) cycles
- (3) Incoming write traffic
- (4) Write Amplification Factor (WAF)
  - Efficiency of FTL algorithms

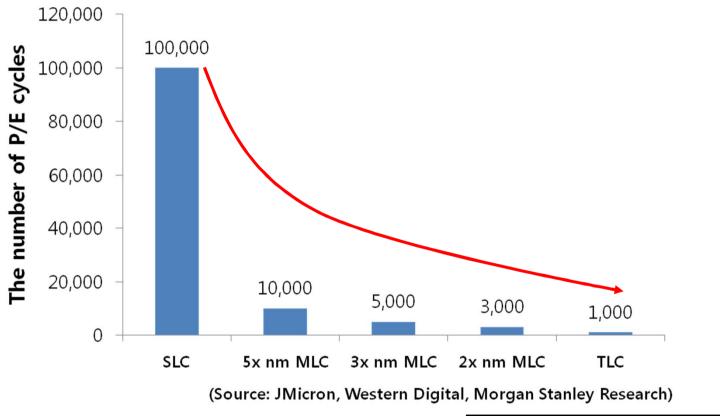
#### **Intensive Write Traffic**

Enterprise systems exhibit high write traffic



# Decreasing P/E Cycles

 The number of P/E cycles is continuously decreasing as the semiconductor process is scaled-down

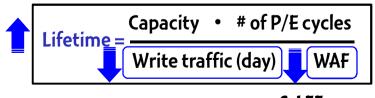




#### **Existing Lifetime-Enhancement Schemes**

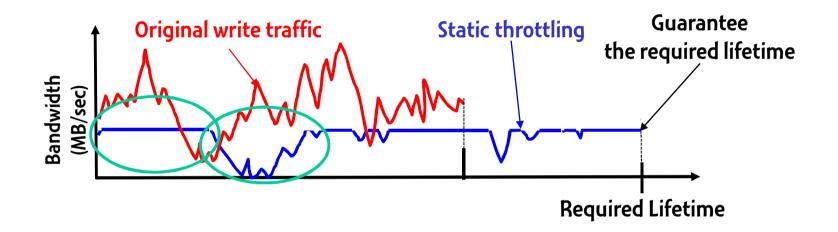
- Reduce WAF
  - Optimize garbage collection algorithms
  - Optimize wear-leveling algorithms
  - Use more fine-grained mapping schemes
- Reduce incoming write traffic
  - Use lossless data compression
  - Use data deduplication

All those approaches improve the overall SSD lifetime, but cannot guarantee the required SSD lifetime !



#### Static Throttling (Existing Approach)

Limit the maximum throughput of SSDs

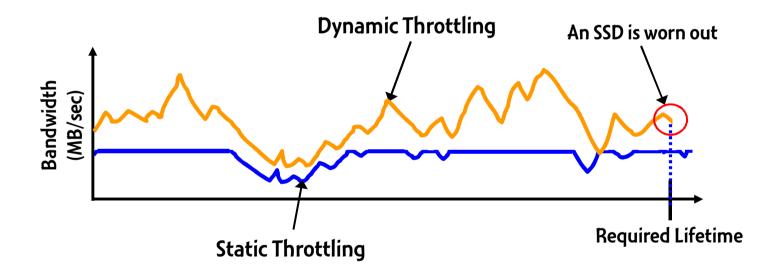


#### Disadvantages

- Likely to throttle performance uselessly
  - High performance penalty and high response time variations
- Underutilize the available endurance

#### Our Approach (1): Dynamic Throttling

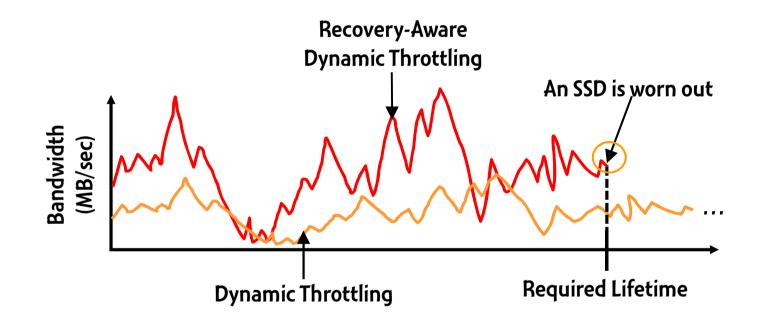
- Throttle SSD performance dynamically depending on:
  - The characteristics of a given workload
  - The remaining SSD lifetime



- Less performance penalty and response time variations
- Fully utilize the available endurance

#### Our Approach (2): Exploit Self-Recovery Effect

 The effective P/E cycles are much larger than the number on datasheets due to the recovery effect



Guarantee the SSD lifetime with less throttling overheads

#### Contribution

- Propose a novel REcovery-Aware DYnamic throttling technique, called READY
  - Throttle the SSD performance to guarantee the required SSD lifetime
  - Exploit the self-recovery property of a flash memory cell to lessen the performance penalty caused by throttling
- Evaluate the proposed READY technique using realworld enterprise traces
  - Guarantee the required SSD lifetime for all evaluated traces
  - Achieve 4.4x higher responses time over a simple static throttling technique

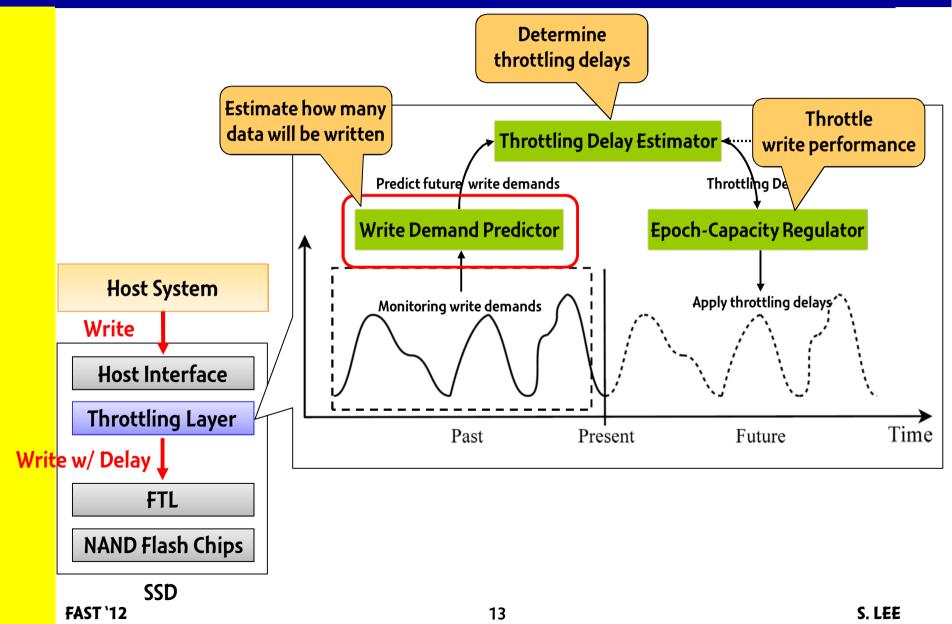
### Outline

- Introduction
- Motivation
- Recovery-Aware Dynamic Throttling
- Evaluation Results
- Conclusion

### **Design Goals of READY**

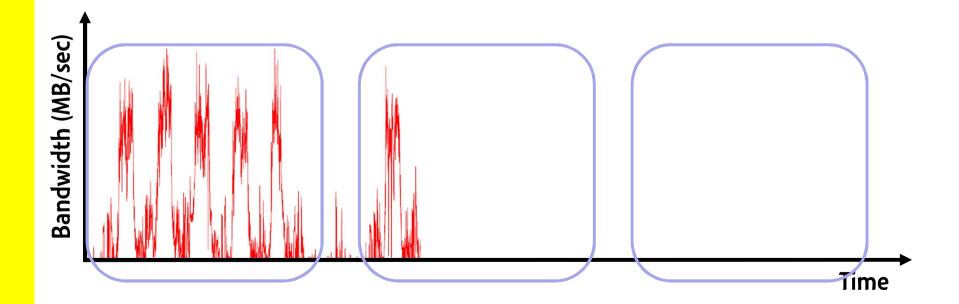
- Design goal 1: guarantee the required SSD lifetime
  - Throttle the write throughput of SSDs by applying throttling delays to write requests
- Design goal 2: minimize average response times
  - Determine a throttling delay as low as possible so that the SSD is completely worn out at the required lifetime
- Design goal 3: minimize response time variations
  - Distribute a throttling delay as evenly as possible over every write request

#### **Overall Architecture of READY**



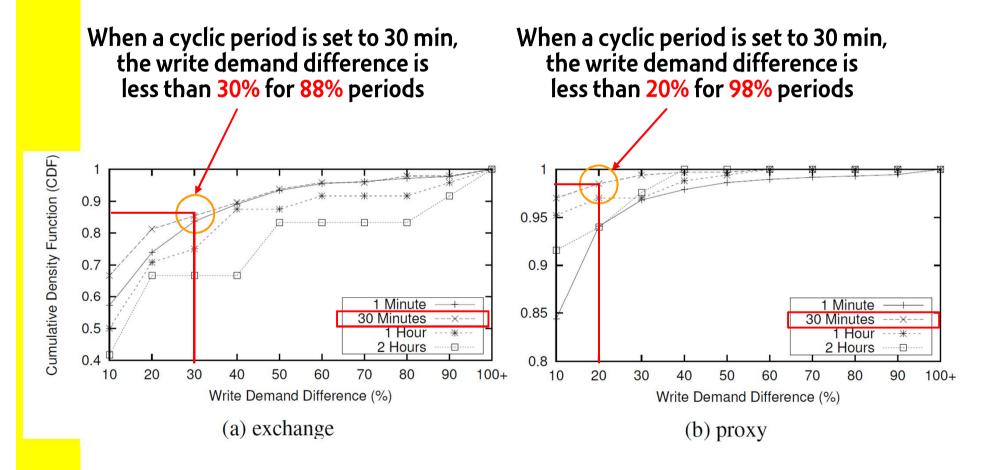
#### Write Demand Predictor

- The write traffic of enterprise workloads is likely to change significantly over time
- How to predict future write traffic for throttling?
  - Exploit cyclic behaviors of enterprise applications!



#### **Cyclical Behaviors of Enterprise Workloads**

 A strong cyclical behavior is frequently observed in enterprise applications

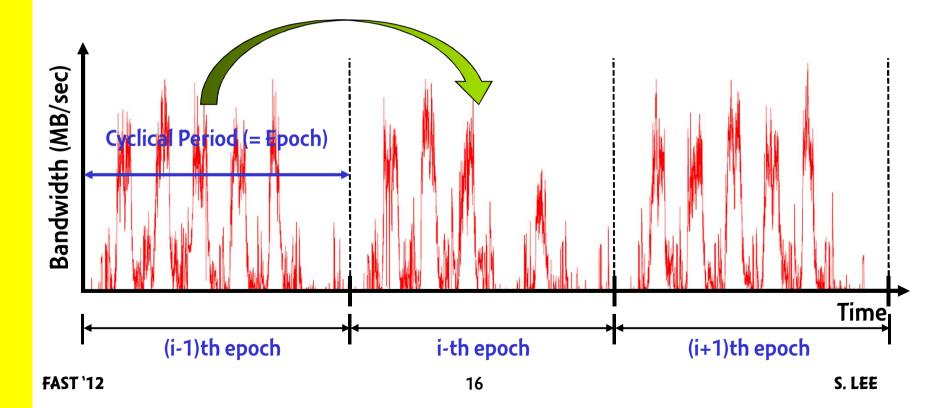


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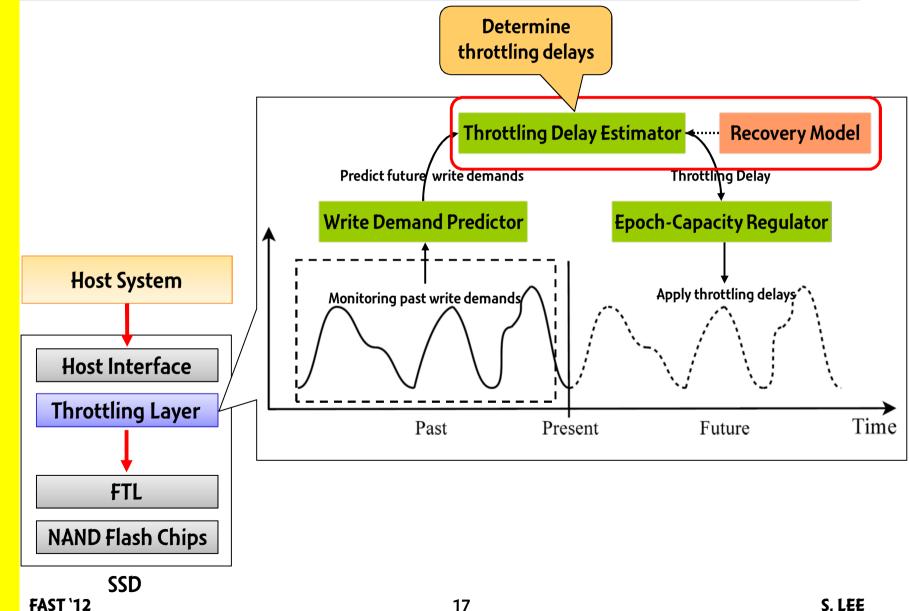
#### **Future Write Demand Estimation**

- (1) Divide time into epochs which exhibit similar write demands
- (2) Estimate the similar amount of data written during the latest epoch will be written during the next epoch

The similar amount of data will be written during the i-th epoch



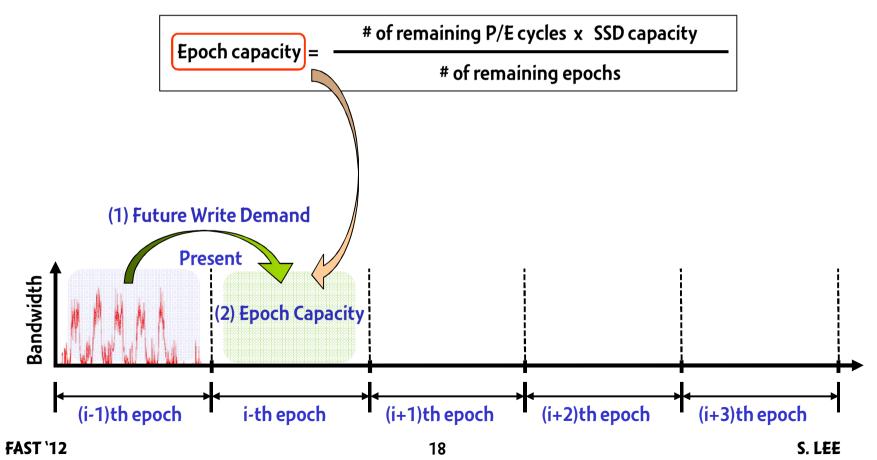
#### **Overall Architecture of READY**



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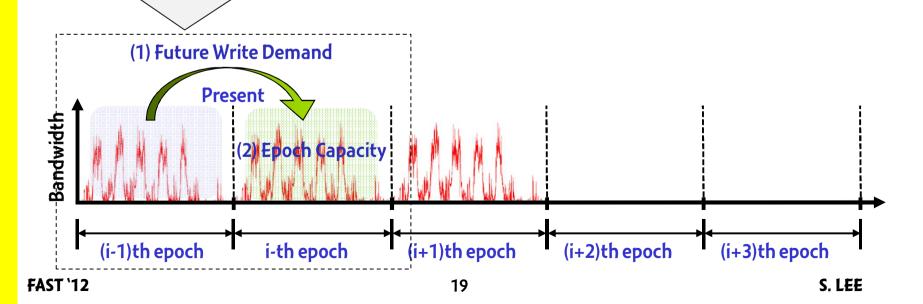
# **Throttling Delay Estimator**

- Determine a throttling delay
  - (1) The future write demand for the next epoch We already know it
  - (2) The epoch capacity
    - The amount of data allowed to be written during the epoch



# **Change Throttling Delay**

- A throttling delay is initially set to 0 and is changed adaptively at the beginning of each epoch.
  - Case 1: future write demand = epoch capacity
    - Don't change a throttling delay
  - Case 2: future write demand > epoch capacity
    - Increase a throttling delay
  - Case 3: future write demand < epoch capacity</p>
    - Decrease a throttling delay

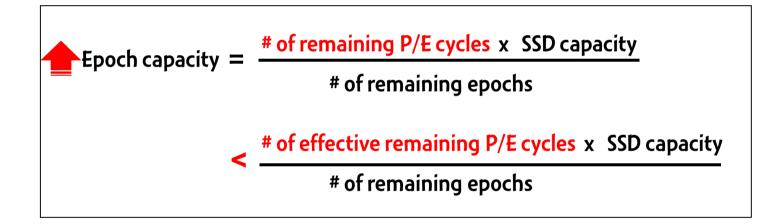


### **Exploit Effective P/E Cycles**

- P/E operations cause damage to NAND flash memory cells
- This damage is partially recovered during the idle time



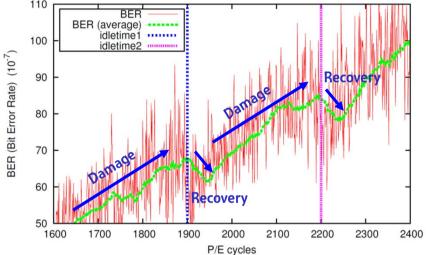
Effective P/E cycles are larger than pre-set P/E cycles



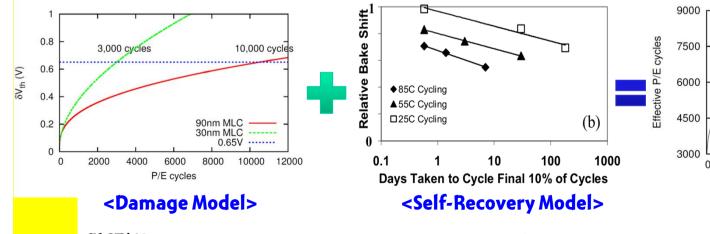
# **Effective P/E Cycles Modeling**

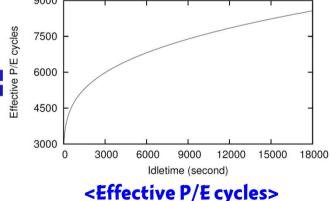
Self-recovery effect validation from real measurements





Effective P/E cycles modeling

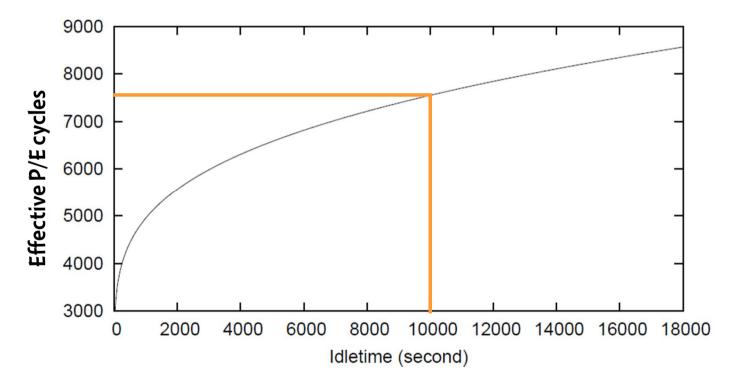




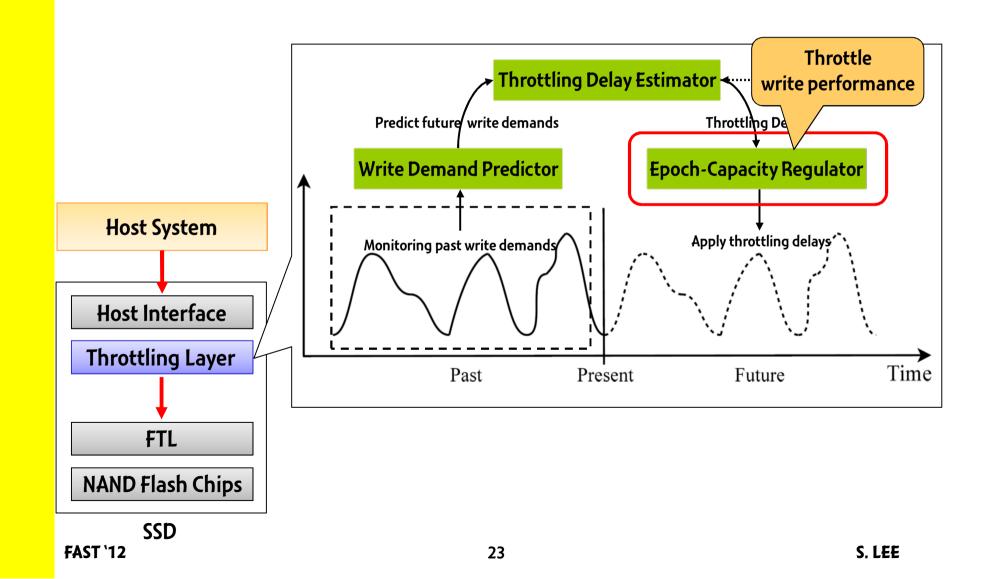
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# **The Effective P/E Cycles**

- The maximum P/E cycles without the recovery effect are 3K.
- The effective P/E cycles are gradually increased in proportional to the length of the idle time.

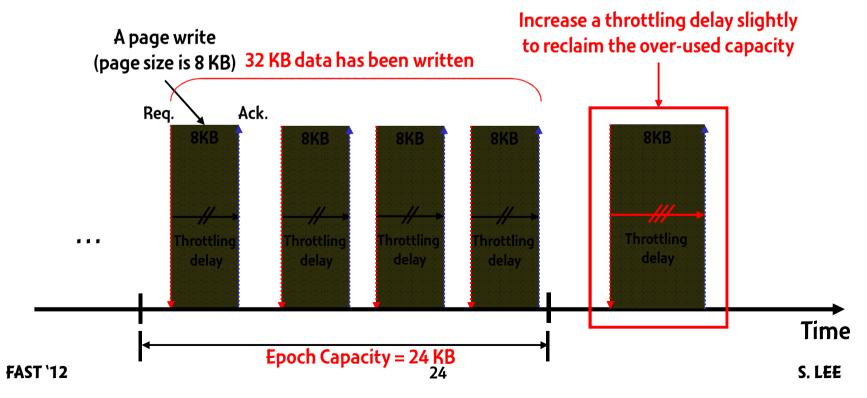


#### **Overall Architecture of READY**



#### **Epoch-Capacity Regulator**

- Throttle write performance as evenly as possible
  - To minimize response time variations
- (1) Apply the same throttling delay to every page write
- (2) Increase a throttling delay later to reclaim the over-used capacity



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#### **Experimental Setting**

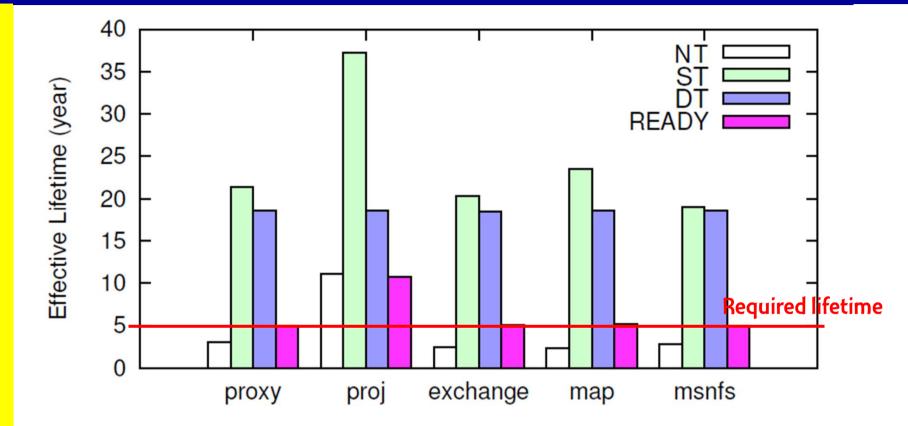
- Used the DiskSim-based SSD simulator for evaluations
  - 20 nm 2-bit MLC NAND flash memory with 3K P/E cycles
  - The target SSD lifetime is set to 5 years
- Evaluated four SSD configurations
  - NT: No Throttling
    - No performance throttling; No lifetime guarantee
  - ST: Static Throttling
  - DT: Dynamic Throttling without Recovery
  - **READY**: Recover-Aware Dynamic Throttling

#### Benchmarks

#### Used the traces from MSR-Cambridge and MS-Production benchmarks

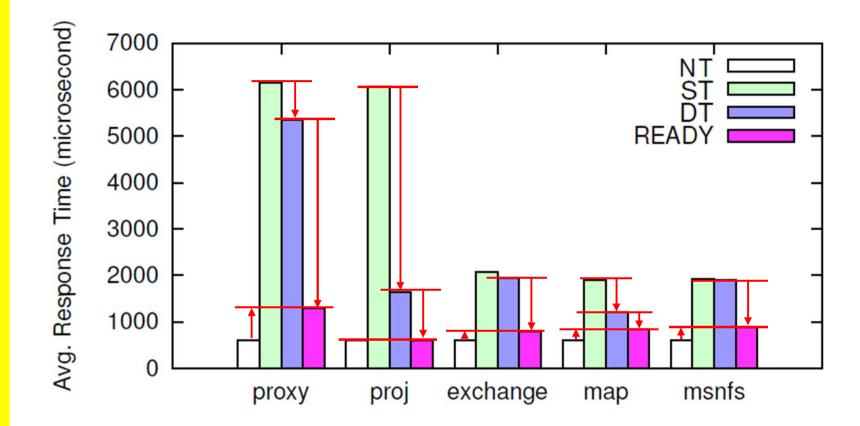
| Trace    | Duration | Data written<br>per hour (GB) | WAF  | SSD<br>capacity (GB) |
|----------|----------|-------------------------------|------|----------------------|
| proxy    | 1 week   | 4.94                          | 1.93 | 32                   |
| proj     | 1 week   | 2.08                          | 1.62 | 32                   |
| exchange | 1 day    | 20.61                         | 2.24 | 128                  |
| map      | 1 day    | 23.82                         | 1.68 | 128                  |
| msnfs    | 6 hours  | 18.19                         | 2.26 | 128                  |

### **Lifetime Analysis**



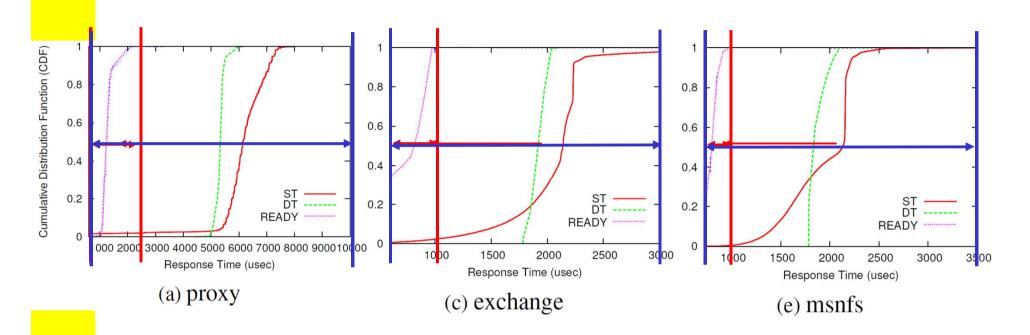
- NT cannot guarantee the required SSD lifetime (except for proj)
- READY achieves the lifetime close to 5 years
- ST and DT exhibit the lifetime much longer than 5 years

#### **Performance Analysis**



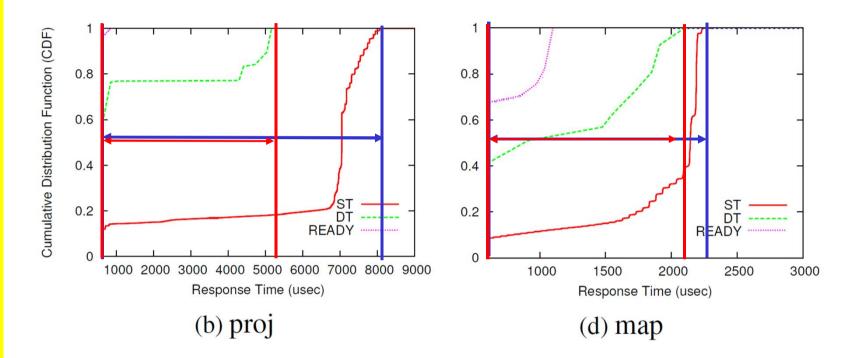
- NT exhibits the best performance among all the configurations
- READY perform better than ST and DT while guaranteeing the required lifetime

#### **Response Time Variations (1)**



- READY shows shorter response times than ST/DT.
- ST exhibits significant response time variations.
  - Stop writing if incoming write traffic is higher than a fixed throughput

#### **Response Time Variations (2)**



- The write traffic of proj and map changes greatly with time.
  - It is hard to predict future write traffic.
- READY and DT exhibit relatively high fluctuation on response times, but is more stable than ST

#### Conclusion

- We proposed the recovery-aware dynamic throttling technique, called READY
  - Guarantee the SSD lifetime by throttling SSD performance
  - Reduce throttling overheads by exploiting the self-recovery effect of flash memory cells
  - Achieve about 4.4x higher performance over the existing static throttling with less response time variations

#### Future works

- Implement READY in a real SSD platform
- Support latency-aware performance throttling

# Thank you